

Background

September-12-11
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Fields

Basic theory of vector spaces works over any field.

$\mathbb{Q}, \mathbb{R}, \mathbb{C}, \mathbb{F}_p$

- We will mostly work over \mathbb{C} or \mathbb{R}
- Other fields if convenient

Algebraically Closed

\mathbb{F} is called algebraically closed if every polynomial

$p(x) \in \mathbb{F}[x]$ factors into linear terms.

$$p(x) = c(x - a_1) \dots (x - a_n)$$

$$x \in \mathbb{F}, n = \deg p$$

Fundamental Theorem of Algebra

\mathbb{C} is algebraically closed

Determinants

If $A = [a_{i,j}]_{n \times n}$ then $\det A$ is determined algorithmically.

$$\det I_n = 1$$

Determinant is n-linear

Think of $A = |v_1, v_2, \dots, v_n|$ $v_i \in \mathbb{F}^n$

$$\det \left(v_1, v_2, \dots, v_{i-1}, \sum_j a_j w_j, v_{i+1}, \dots, v_n \right) = \sum_j a_j \det(v_1, \dots, v_{i-1}, w_j, v_{i+1}, \dots, v_n)$$

Determinant is antisymmetric

$$\det(v_1, \dots, v_{i-1}, u, v_{i+1}, \dots, v_{j-1}, u, v_{j+1}, \dots, v_n) = 0$$

\Rightarrow (except if $1+1=0$)

$$\det(v_1, \dots, v_{i-1}, v_j, v_{i+1}, \dots, v_{j-1}, v_i, v_{j+1}, \dots, v_n) = -\det(v_1, \dots, v_n)$$

Theorem 1

$$\det(AB) = \det A \times \det B$$

Theorem 2

$\det A = 0 \Leftrightarrow A$ is singular

Linear Transformation and Matrices

V is a vector space (over field \mathbb{F})

$\mathcal{L}(V)$ is the set of all linear transformations from V to V

W another vector space over \mathbb{F}

$\mathcal{X}(V, W)$ = linear transformation from V to W

If $\beta(v_1, \dots, v_n)$ is a basis for V

$T \in \mathcal{L}(V)$

$$T v_j = \sum_{i=1}^n a_{ij} v_i$$

$|T|_\beta = [a_{ij}]$ is the matrix of T with respect to β

$x \in V, x = \sum_{i=1}^n x_i v_i$

$$|T x|_\beta = [a_{ij}](x_1, \dots, x_n) = |T|_\beta |x|_\beta$$

Also if $S \in \mathcal{L}(V, W)$

$\beta = \{v_1, \dots, v_n\}$ bases for V

$\beta' = \{w_1, \dots, w_m\}$ bases for W

$$S(v_j) = \sum_{i=1}^m a_{ij} w_i \quad i \leq j \leq n$$

$$|S|_{\beta'}^\beta = [a_{ij}]$$

Theorem

If $T \in \mathcal{L}(V)$ then $\det |T|_\beta$ is independent of the choice of basis.

So we can define $\det T := \det |T|_\beta$

Sketch of Theorem 2

If A is singular (i.e. $\text{rank } A < n$)

Some column $V_{i_0} = \sum_{i \neq i_0} a_i v_i$

$$\det A = \det \left(v_i, v_{i_0-1}, \sum_{i \neq i_0} a_i v_i, v_{i_0+1}, v_n \right) = \sum_{i \neq i_0} a_i \det(v_i, \dots, v_{i_0-1}, v_i, v_{i_0+1}, \dots, v_n) = 0$$

If A is invertible,

$$1 = \det I = \det(AA^{-1}) = \det A \times \det A^{-1}$$

$$\therefore \det A \neq 0$$

Proof of Theorem

Let $\beta = \{v_1, \dots, v_n\}$ and $\beta' = \{w_1, \dots, w_n\}$ be two bases for V

Write

$$w_j = \sum_{i=1}^n a_{ij} v_i$$

$$Q = |a_{ij}| = |I|_{\beta'}^\beta = |w_1|_\beta, |w_2|_\beta, \dots, |w_n|_\beta|$$

$$\text{If } x = \sum_{j=1}^n x_j w_j = \sum_{j=1}^n \sum_{i=1}^n a_{ij} x_j v_i = \sum_{i=1}^n \left(\sum_{j=1}^n a_{ij} x_j \right) v_i$$

$$|x|_\beta = |a_{ij}| |x|_{\beta'} = Q |x|_{\beta'}$$

Look at Tx

$$|Tx|_\beta = |T|_\beta |x|_\beta = |T|_\beta Q |x|_{\beta'}$$

$$|Tx|_{\beta'} = Q^{-1} |T|_\beta Q |x|_{\beta'}$$

$$\therefore \det |T|_{\beta'} = \det Q^{-1} |T|_\beta Q = \det Q^{-1} \times \det |T|_\beta \times \det Q = \det |T|_\beta$$

QED

$\det |T|_\beta$ does not depend on which basis is used.

Eigenvalues

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Eigenvalue (a.k.a. characteristic value)

$T \in \mathcal{L}(V)$ = set of all linear transformations from V to V
 A scalar $\lambda \in \mathbb{F}$ is an eigenvalue for T if $\exists v \neq 0$ s.t. $Tv = \lambda v$

Eigenvector

Any non-zero vector v s.t. $Tv = \lambda v$ is an eigenvector for (T, λ)

Eigenspace

The space $\ker(T - \lambda I) = \{v: Tv = \lambda v\}$ is the eigenspace for (T, λ)

Theorem

$T \in \mathcal{L}(V)$, The following are equivalent

- λ is an eigenvalue for T
- $T - \lambda I$ is singular
- $\det(T - \lambda I) = 0$

Characteristic Polynomial

The characteristic polynomial of T is

$$P_T(x) = \det(xI - T)$$

Note

$P_T(x)$ is a monic polynomial of degree $n = \dim V$

Monic: coefficient on highest degree is 1

Spectrum

The spectrum of T is $\sigma(T)$, the set of all eigenvalues.

Corollary

$\sigma(T)$ is the set of zeros of $P_T(x)$

Corollary

$\sigma(T)$ has at most $n = \dim V$ eigenvalues.

Corollary

Similar transformations have the same spectrum

Direct Sums

Say V is the direct sum of V_1 and V_2 if $V_1 \cap V_2 = \{0\}$ and $V_1 + V_2 = V$. Write $V = V_1 \dot{+} V_2$ or $V = V_1 \oplus V_2$

Say V is the direct sum of V_1, \dots, V_k if

- $V = \sum_{i=1}^k V_i$
- $V_j \cap \left(\sum_{i \neq j} V_i \right) = \{0\}$, for $1 \leq j \leq k$

Proposition

If $\{V_i\}_{i=1}^k \neq V_i$ subspaces of V such that

$$V = \sum_{i=1}^k V_i$$

then TFAE (the following are equivalent)

- Sum is direct: $V = V_1 \dot{+} \dots \dot{+} V_k$
- If $0 \neq v_i \in V_i$, then $\{v_1, \dots, v_k\}$ is linearly independent
- If $w_i \in V_i$ and $\sum_{i=1}^k w_i = 0$ then $w_i = 0$, $1 \leq i \leq k$
- Every $v \in V$ has a unique expression as

$$v = \sum_{i=1}^k w_i, w_i \in V_i$$

Corollary

If $V = V_1 \dot{+} V_2 \dot{+} \dots \dot{+} V_k$

Then if you take a basis for each V_i , say v_{i1}, \dots, v_{id_i}

then the union $\{v_{11}, \dots, v_{1d_1}, v_{21}, \dots, v_{k1}, \dots, v_{kd_k}\}$ is a basis for V .

Example

T is diagonal w.r.t. bases $\beta = \{v_1, \dots, v_n\}$ if

$$[T]_{\beta} = \begin{bmatrix} \lambda_1 & 0 & \dots \\ 0 & \lambda_2 & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

So $Tv_i = \lambda_i v_i$

So $\lambda_1, \dots, \lambda_n$ are eigenvalues

If $u \in \{\lambda_1, \dots, \lambda_n\}$ eigenspace for u

$$\ker(T - \mu I) = \text{span}\{v_i: \lambda_i = \mu\}$$

$$\mu \neq \{\lambda_1, \dots, \lambda_n\}$$

Only eigenvalues are $\{\lambda_1, \dots, \lambda_n\}$

$$T = \text{diagonal}(1, 2, 1, 2, 1, 3)$$

$$\ker T - I = \text{span}\{v_1, v_3, v_5\}$$

$$\ker(T - 2I) = \text{span}\{v_2, v_4\}$$

$$\ker(T - 3I) = \text{span}\{v_6\}$$

Example

$$T = \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix}$$

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

1 is an eigenvalue, $\ker(T - I) = \mathbb{F} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

\mathbb{F} - span or set of all multiples of

$$T \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

2 is an eigenvalue

$$\ker(T - 2I) = \mathbb{F} \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$$u \neq \{1, 2\}$$

$$T - uI = \begin{pmatrix} 1-u & 3 \\ 0 & 2-u \end{pmatrix}$$

$$\begin{pmatrix} 1-u & 3 \\ 0 & 2-u \end{pmatrix} \begin{pmatrix} 1-u & -\frac{3}{(2-u)(1-u)} \\ 0 & \frac{1}{2-u} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

So it is invertible, so rank is 0, so no more eigenvalues.

Proof of Theorem

1. λ is an eigenvalue for T

$$\Leftrightarrow \ker(T - \lambda I) \neq \{0\}$$

$$\Leftrightarrow 2. T - \lambda I \text{ is singular}$$

$$\Leftrightarrow 3. \det(T - \lambda I) = 0$$

Example

$$T = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

Look at

$$p(x) = \det(xI - T) = \begin{vmatrix} x & 1 \\ -1 & x \end{vmatrix} = x^2 + 1$$

$\mathbb{F} = \mathbb{R}$ no eigenvalues

$$\mathbb{F} = \mathbb{C} \quad x^2 + 1 = (x+i)(x-i)$$

$$T - iI = \begin{vmatrix} -i & -1 \\ 1 & -i \end{vmatrix} \begin{pmatrix} 1 \\ -i \end{pmatrix} = 0$$

$$T + iI = \begin{vmatrix} i & -1 \\ 1 & i \end{vmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} = 0$$

$\pm i$ are eigenvalues

In \mathbb{R}^2 , T is a rotation

Example

$$T = \begin{bmatrix} 4 & -1 & -1 \\ -2 & 5 & -1 \\ 3 & -3 & 6 \end{bmatrix}$$

$$p(x) = \det(xI - T) = \begin{vmatrix} x-4 & 1 & 1 \\ 2 & x-5 & 1 \\ -3 & 3 & x-6 \end{vmatrix}$$

$$= (x-4)((x-5)(x-6) - 3) - 1(2(x-6) + 3) + 1(6 + 3(x-5))$$

$$= (x-4)(x^2 - 11x + 27) - (2x - 9) + (3x - 9)$$

$$= x^3 - 15x^2 + 71x - 108$$

$$= (x-3)(x-6)^2$$

Eigenvalues are 3, 6

$$T - 3I = \begin{bmatrix} 1 & -1 & -1 \\ -2 & 2 & -1 \\ 3 & -3 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 & -1 \\ 0 & 0 & -3 \\ 0 & 0 & 0 \end{bmatrix} \begin{pmatrix} a \\ a \\ 0 \end{pmatrix} = 0$$

$$T - 6I = \begin{bmatrix} -2 & -1 & -1 \\ -2 & -1 & -1 \\ 3 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -2 & -1 & -1 \\ 0 & 0 & 0 \\ 1 & -1 & 0 \end{bmatrix} \begin{pmatrix} a \\ a \\ -3a \end{pmatrix} = 0$$

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$T \begin{pmatrix} 1 \\ -3 \end{pmatrix} = 6 \begin{pmatrix} 1 \\ -3 \end{pmatrix}$$

Only 2-dimensions of eigenvectors!

Proof of 3rd Corollary

$T \in \mathcal{L}(V), S$ invertible

STS^{-1} is similar to T

$$P_{STS^{-1}}(x) = \det(xI - STS^{-1}) = \det(S(xIS^{-1}S - T)S^{-1}) = \det(xI - T) = P_T(x)$$

Proof of Proposition

My Proofs

1 \Rightarrow 2

Suppose $v_i \neq 0 \in V_i$ and

$$\sum_{i=0}^k a_i v_i = 0 \text{ for some } a_i \in \mathbb{F} \text{ not all } 0$$

Then, for $a_i \neq 0$

$$a_i v_i = - \sum_{j \neq i} a_j v_j$$

$$a_i v_i \in V_i \text{ and } - \sum_{j \neq i} a_j v_j \in \sum_{j \neq i} V_j \text{ but}$$

$$V_i \cap \sum_{j \neq i} V_j = \{0\},$$

a contradiction since $a_i \neq 0$ and $v_i \neq 0$.

2 \Rightarrow 3

$$\sum_{i=1}^k w_i = 0 \Rightarrow w_i$$

w_i are linearly dependent, but by 2 $w_i \neq 0 \Rightarrow w_i$ are linearly independent, so $w_i = 0 \forall i$

3 \Rightarrow 4

By definition of vector sums, for any $v \in V$ there exists at least one set of $v_i \in V_i$ such that $v = \sum_i v_i$

Now suppose there exists $w_i \in V_i$, such that

$$v = \sum_i v_i = \sum_i w_i$$

$$\Rightarrow 0 = \sum_i v_i - w_i$$

But $v_i - w_i \in V_i$ therefore by 3, $v_i - w_i = 0 \Rightarrow v_i = w_i \forall 1 \leq i \leq k$

4 \Rightarrow 1

Already have

$$V = \sum_{i=1}^k V_i$$

Suppose for some $1 \leq j \leq k, \exists e \neq 0$ s. t.

$$e \in V_j \cap \sum_{i \neq j} V_i, \text{ Select } w_i \in V_i \text{ s. t. } e = \sum_{i \neq j} w_i$$

Let $w_j = e \in V_j$

Then

$$e = w_j + \sum_{i \neq j} 0 = 0 + \sum_{i \neq j} w_i,$$

This is not unique, a contradiction, so

$$V_j \cap \sum_{i \neq j} V_i = \{0\}$$

since 0 is certainly in both V_j and $\sum_{i \neq j} V_i$

QED

His Proof

3 \Rightarrow 1

$$\text{If } v \in V_i \cap \left(\sum_{j \neq i} V_j \right)$$

$$v = v_i \in V$$

$$= \sum_{j \neq i} v_j \quad v_j \in V_j$$

$$\therefore -v_i + \sum_{j \neq i} v_j = 0$$

By 3, $v_i = 0 = v_j$,

$$\therefore v_i \cap \sum_{j=i} V_j = \{0\}$$

Proof of Corollary

Suppose

$$0 = \sum_{i,j} a_{ij} v_{ij} = \sum_i \left(\sum_j a_{ij} v_{ij} \right) = \sum_i v_i \text{ where } v_i \in V_i$$

by 3, $v_i = 0$ $1 \leq i \leq k$

$\{v_{ij}\}$ is a basis for V_i , so all $a_{ij} = 0$

$\{v_{ij}\}_{i=1, j=1}$ is lin indep.

Clearly v_i spans V

\therefore basis

■

Diagonalization

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Proposition

Let $T \in \mathcal{L}(V)$
 $\sigma(T) = \{\lambda_1, \dots, \lambda_k\}$
 $W_i = \ker(T - \lambda_i I)$
 $W = \sum_{i=1}^k W_i \subseteq V$

Then $W = W_1 + W_2 + \dots + W_k$

Diagonalizable

A linear transformation $T \in \mathcal{L}(V)$ is diagonalizable if it has a basis $\beta = \{v_1, \dots, v_n\}$ so that

$$[T]_{\beta} = \begin{pmatrix} c_1 & 0 & 0 & \dots & 0 \\ 0 & c_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & c_n \end{pmatrix}$$

is diagonal.

Note

$Tv_i = c_i v_i$
 So v_i is an eigenvector
 T is diagonalizable $\Leftrightarrow V$ has a basis containing eigenvectors of T
 $\sigma(T) = \{c_1, \dots, c_n\} = \{\lambda_1, \dots, \lambda_k\}$
 $\{c_1, \dots, c_n\}$ - might have repetitions
 $\lambda \in \mathbb{F}, \ker(T - \lambda I) = \text{span}\{v_i : c_i = \lambda\}$

$p \in \mathbb{F}[x]$ polynomial

$$p(T) = \begin{pmatrix} p(c_1) & 0 & 0 & \dots & 0 \\ 0 & p(c_2) & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & p(c_n) \end{pmatrix}$$

Nullity

$\text{nul}(T) = \dim \ker T$

Theorem

$T \in \mathcal{L}(V), \sigma(T) = \{\lambda_1, \dots, \lambda_k\}$

TFAE

- T is diagonalizable
- $\sum_{i=1}^k \text{nul}(T - \lambda_i I) = n = \dim V$
- $p_T(x) = \prod_{i=1}^k (x - \lambda_i)^{d_i}$
 where $d_i = \text{nul}(T - \lambda_i I)$

Corollary

If T has n distinct eigenvalues, then T is diagonalizable.

Proof of Proposition

Suffices to show that if $w_i \in W_i, 1 \leq i \leq k$ and $\sum_{i=1}^k w_i = 0$ then $w_i = 0$ for $1 \leq i \leq k$
 (By Proposition in previous lecture)

If $w \in W_i$ then $(T - \lambda_i I)w = 0$ and

$$Tw = \lambda_i w, \quad T^2 w = \lambda_i^2 w, \quad \dots$$

Therefore for any polynomial $p(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_p x^p$

$$p(T) = a_0 I + a_1 T + a_2 T^2 + \dots + a_p T^p$$

$$p(T)w = \sum_{j=0}^p a_j T^j w = \left(\sum_{j=0}^p a_j \lambda_i^j \right) w = p(\lambda_i)w$$

Fix i and show $w_i = 0$:

$$\text{Let } p(x) = \prod_{j \neq i} (x - \lambda_j)$$

$$\text{Let } x = \sum_{j=1}^k w_j = 0$$

$$0 = p(T)x = p(T) \left(\sum_{j=1}^k w_j \right) = \sum_{j=1}^k p(\lambda_j)w_j = \left(\prod_{j \neq i} (\lambda_i - \lambda_j) \right) w_i$$

$$\prod_{j \neq i} (\lambda_i - \lambda_j) \neq 0, \text{ so } w_i = 0$$

$\therefore w_i = 0 \forall i, \Rightarrow$ Sum is direct

Example

$$T = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} \in \mathcal{L}(\mathbb{C}^2)$$

$p(x) = \mathbb{C}[x]$

$$p(T) = \begin{pmatrix} p(0) & 0 & 0 & 0 \\ 0 & p(0) & 0 & 0 \\ 0 & 0 & p(1) & 0 \\ 0 & 0 & 0 & p(2) \end{pmatrix}$$

Let $A(T) = \text{span}\{I, T, T^2, T^3, \dots\} \subseteq \mathcal{L}(V)$

$$A(T) = \begin{pmatrix} a & 0 & 0 & 0 \\ 0 & a & 0 & 0 \\ 0 & 0 & b & 0 \\ 0 & 0 & 0 & c \end{pmatrix}, a, b, c \in \mathbb{C}$$

Because given $a, b, c \exists p$ (of degree 2) s.t. $p(0) = a, p(1) = b, p(2) = c$
 $A(T)$ is isomorphic to $\mathcal{C}(\{0, 1, 2\})$, the algebra of functions in $\{0, 1, 2\}$

Question

Which $T \in \mathcal{L}(V)$ are diagonalizable?

Example

$$T = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, p_T(x) = x^2 + 1$$

No eigenvalues in \mathbb{R} so it is not diagonalizable if $V = \mathbb{R}^2$ but $mV = \mathbb{C}^2, \sigma(T) = \{i, -i\}$

$\therefore \exists v_1, v_2, Tv_1 = iv_1, Tv_2 = -iv_2$

$\therefore \{v_1, v_2\}$ is a basis $[T]_{\beta} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$

Example

$$T = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$p_T(x) = \det(xI - T) = \begin{vmatrix} x & -1 \\ 0 & x \end{vmatrix} = x^2$$

$\sigma(T) = \{0\}$

$$\ker(T) = \mathbb{C} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Need two linearly independent eigenvectors to diagonalize T - NOT POSSIBLE.

Proof

T has basis $\beta = \{v_1, \dots, v_n\}$

$$[T]_{\beta} = \begin{pmatrix} c_1 & 0 & 0 & \dots & 0 \\ 0 & c_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & c_n \end{pmatrix}$$

$1 \Rightarrow 2$

$$\ker(T - \lambda_i I) = \text{span}\{v_j : c_j = \lambda_i\}$$

$$\text{nul}(T - \lambda_i I) = \{j: c_j = \lambda_i\}$$

$$\text{So } \sum_{i=1}^k \text{nul}(T - \lambda_i I) = \{j: 1 \leq j \leq n\} = n$$

2 \Rightarrow 1

Let $W_i = \ker(T - \lambda_i I)$

$$\sum_{i=1}^k W_i = W_1 + \dots + W_k$$

$$\dim\left(\sum_{i=1}^k W_i\right) = \sum_{i=1}^k \dim W_i = \sum_{i=1}^k \text{nul}(T - \lambda_i I) = n, \text{ by (2)}$$

$$\therefore \sum W_i = V$$

Take a basis for each W_i

- they are eigenvectors for the eigenvalues λ_i
- put them together, get a basis for V consisting of eigenvectors \Rightarrow diagonalizable

1 \Rightarrow 3

$$T = \begin{pmatrix} c_1 & 0 & 0 & \dots & 0 \\ 0 & c_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & c_n \end{pmatrix}$$

$$\text{nul}(T - \lambda_i I) = \{j: c_j = \lambda_i\}$$

$$p_T(x) = \det(xI - T) = \begin{vmatrix} x - c_1 & 0 & 0 & \dots & 0 \\ 0 & x - c_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & x - c_n \end{vmatrix} = \prod_{i=1}^k (x - \lambda_i)^{d_i}$$

$$\text{where } d_i = \{j: c_j = \lambda_i\} = \text{nul}(T - \lambda_i I)$$

3 \Rightarrow 2

$$\sum_{i=1}^k \text{nul}(T - \lambda_i I) = \sum_{i=1}^k d_i = \deg(p_T) = n$$

Proof of Corollary

$\text{nul}(T - \lambda_i I) = 1$ for $1 \leq i \leq n$ so by 2, T is diagonalizable.

Linear Recursion

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Computational Device

Suppose you are given T as in example * and you need to compute T^n

If D is the diagonal matrix of T

$$T = QDQ^{-1}$$

$$T^n = (QDQ^{-1})^n = QDQ^{-1}QDQ^{-1} \dots QDQ^{-1} = QD^nQ^{-1}$$

Linear Recursion

In general, if we have x_0, x_1, \dots, x_n given,

$$x_{k+1} = a_0x_k + a_1x_{k-1} + \dots + a_nx_{k-n}$$

linear recursion

$$\begin{pmatrix} x_{k+1} \\ x_k \\ x_{k-1} \\ \vdots \\ x_{k-n} \end{pmatrix} = \begin{pmatrix} a_0 & a_1 & a_2 & \dots & a_n \\ 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{pmatrix} \begin{pmatrix} x_k \\ x_{k-1} \\ x_{k-2} \\ \vdots \\ x_{k-n-1} \end{pmatrix}$$

$$p_A(x) = \det(xI - A) = \begin{vmatrix} x - a_0 & -a_1 & -a_2 & \dots & -a_n \\ -1 & x & 0 & \dots & 0 \\ 0 & -1 & x & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & -1 \end{vmatrix}$$

$$= x^{n+1} - a_0x^n - a_1x^{n-1} - a_2x^{n-2} - \dots - a_n$$

Now try to diagonalize A, and get a formula for x_n

Example *

$$T = \begin{pmatrix} -3 & 3 & -1 & -2 \\ -8 & 2 & 3 & -4 \\ -4 & 2 & 1 & -2 \\ 0 & -4 & 4 & 1 \end{pmatrix}$$

Using Matlab got

$$p_T(x) = (x - 1)^2(x + 1)$$

$$\text{So } \sigma(T) = \{1, 0, -1\}$$

$$\ker(T - I) = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ -1 \end{pmatrix} \right\}$$

$$\ker(T) = \text{span} \left\{ \begin{pmatrix} 3 \\ 1 \\ 2 \\ -4 \end{pmatrix} \right\}$$

$$\ker(T + I) = \text{span} \left\{ \begin{pmatrix} -2 \\ 1 \\ -1 \\ 4 \end{pmatrix} \right\}$$

Change of basis matrix:

$$Q = \begin{pmatrix} 0 & 1 & 3 & -2 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & -1 \\ 1 & -1 & -4 & 4 \end{pmatrix}$$

$$Q^{-1}TQ = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} = D$$

Example: Fibonacci Sequence

$$x_0 = 0, x_1 = 1$$

$$x_n = x_{n-1} + x_{n-2} \text{ for } n \geq 2$$

$$\begin{pmatrix} x_n \\ x_{n+1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_{n-1} \\ x_n \end{pmatrix}$$

$$\text{Let } A = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} x_n \\ x_{n+1} \end{pmatrix} = A^n \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$p_A(x) = \det \begin{pmatrix} x & -1 \\ -1 & x-1 \end{pmatrix} = x(x-1) - 1 = x^2 - x - 1$$

$$\tau = \frac{1 \pm \sqrt{1+4}}{2}$$

$$\tau = \frac{1 + \sqrt{5}}{2}, \frac{1 - \sqrt{5}}{2} = -\frac{1}{\tau}$$

$$\sigma(A) = \left\{ \frac{1 + \sqrt{5}}{2}, \frac{1 - \sqrt{5}}{2} \right\} = \left\{ \tau, -\frac{1}{\tau} \right\}$$

$$A - \tau I = \begin{pmatrix} -\tau & 1 \\ 1 & 1 - \tau \end{pmatrix} \begin{pmatrix} 1 \\ \tau \end{pmatrix} = \begin{pmatrix} 0 \\ 1 + \tau - \tau^2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\ker(A - \tau I) = \mathbb{C} \begin{pmatrix} 1 \\ \tau \end{pmatrix}$$

$$A + \frac{1}{\tau} I = \begin{pmatrix} \frac{1}{\tau} & 1 \\ 1 & 1 + \frac{1}{\tau} \end{pmatrix} \begin{pmatrix} \tau \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ \tau - 1 - \frac{1}{\tau} \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{\tau^2 - \tau - 1}{\tau} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\ker\left(A + \frac{1}{\tau} I\right) = \mathbb{C} \begin{pmatrix} \tau \\ -1 \end{pmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

$$Q = \begin{pmatrix} 1 & \tau \\ \tau & -1 \end{pmatrix}$$

$$Q^{-1} = \frac{1}{-1 - \tau^2} \begin{pmatrix} -1 & -\tau \\ -\tau & 1 \end{pmatrix} = \frac{1}{1 + \tau^2} \begin{pmatrix} 1 & \tau \\ \tau & -1 \end{pmatrix} = \frac{1}{1 + \tau^2} Q$$

$$Q^{-1}AQ = D = \begin{pmatrix} \tau & 0 \\ 0 & -\frac{1}{\tau} \end{pmatrix}$$

$$\begin{aligned}
A^n &= QD^nQ^{-1} = \frac{1}{1+\tau^2} \begin{pmatrix} 1 & \tau \\ \tau & -1 \end{pmatrix} \begin{pmatrix} \tau^n & 0 \\ 0 & \frac{(-1)^n}{\tau^n} \end{pmatrix} \begin{pmatrix} 1 & \tau \\ \tau & -1 \end{pmatrix} \\
&= \frac{1}{1+\tau^2} \begin{pmatrix} 1 & \tau \\ \tau & -1 \end{pmatrix} \begin{pmatrix} \tau^n & \tau^{n+1} \\ \frac{(-1)^n}{\tau^{n-1}} & \frac{(-1)^{n+1}}{\tau^n} \end{pmatrix} \\
&= \frac{1}{1+\tau^2} \begin{pmatrix} \tau^n + \frac{(-1)^n}{\tau^{n-2}} & \tau^{n+1} + \frac{(-1)^{n+1}}{\tau^{n-1}} \\ \tau^n + \frac{(-1)^{n+1}}{\tau_{n+1}} & \tau^{n+2} + \frac{(-1)^{n+2}}{\tau^n} \end{pmatrix} \\
\begin{pmatrix} x_n \\ x_{n+1} \end{pmatrix} &= A^n \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \left(\tau^{n+1} + \frac{(-1)^{n+1}}{\tau^{n+1}} \right) \\ 1 + \tau^2 \end{pmatrix}^* \\
x_n &= \left(\frac{\tau}{1+\tau^2} \right) \left(\tau^n - \left(-\frac{1}{\tau} \right)^n \right) \\
\frac{\tau}{1+\tau^2} &= \frac{1}{\sqrt{5}} \\
x_n &= \frac{\tau^n - \left(-\frac{1}{\tau} \right)^n}{\sqrt{5}} \\
x \geq 2, x_n &\text{ is the closest integer to } \frac{\tau^n}{\sqrt{5}}
\end{aligned}$$

Triangular Forms

September-21-11
9:31 AM

Upper Triangular

A matrix T is upper triangular if $a_{ij} = 0$ if $j < i$

Say $T \in \mathcal{L}(V)$ is triangularizable if there is a basis β such that $|T|_\beta$ is upper triangular.

Triangular Determinant

$$\det T = \prod_{i=1}^n a_{ii}$$

- $\sigma(T) = \{a_{11}, a_{22}, \dots, a_{nn}\}$
- $p_T(x)$ factors into linear terms.

Invariant Subspace

If $T \in \mathcal{L}(V)$, a subspace $W \subseteq V$ is an invariant subspace for T if $TW \subseteq W$

$$W_k = \text{span} \{v_1, v_2, \dots, v_k\} \quad 0 \leq k \leq n$$

Theorem

For $T \in \mathcal{L}(V)$, TFAE

- T is triangularizable
- $p_T(x)$ factors into linear terms
- T has a chain of invariant subspaces $\{0\} = W_0 \subset W_1 \subset W_2 \subset \dots \subset W_n = V$
With $\dim W_k = k$ for $1 \leq k \leq n$

Corollary

If \mathbb{F} is algebraically closed (such as \mathbb{C}) then every $T \in \mathcal{L}(V)$ is triangularizable.

Determinant of Upper Triangular

$$\begin{vmatrix} a & b \\ 0 & d \end{vmatrix} = ad$$

For $n > 2$, take determinant of first column leaves a_{11} *determinant of upper triangular matrix with $n-1$

So by induction, $\det T = a_{11}a_{22} \dots a_{nn}$

Alternate Proof

$$|a_{ij}| = \sum_{\sigma \in S_n} (-1)^{\text{sign}(\sigma)} \prod_{i=1}^n |a_{i\sigma(i)}$$

If $\sigma \in S_n$ and for some $i, \sigma(i) = j < i$ then $a_{i\sigma(i)} = 0 \Rightarrow \prod_{i=1}^n a_{i\sigma(i)} = 0$

Only $\sigma = \text{identity}$ satisfies $\sigma(i) \geq i \forall i$ because if say $\sigma(i) = 1$ for $1 \leq i < i_0$ but $\sigma(i_0) > i_0$ then some j has $\sigma(j) = i_0$, but $j > i_0$

$$\therefore \prod_{i=1}^n a_{i\sigma(i)} = 0$$

$$|a_{ij}| = \prod_{i=1}^n a_{ii}$$

Types of Invariant Subspaces

If T is upper triangular w.r.t. $\beta = \{v_1, \dots, v_n\}$

$Tv_1 = a_{11}v_1$ eigenvector

$\therefore W_1 = \text{span}\{v_1\}$ is invariant

$W_0 = \{0\}$ is invariant for every T

$W_n = V$ is invariant for every T

$$Tv_2 = a_{22}v_2 + a_{12}v_1 \in \text{span}\{v_1, v_2\}$$

$$Tv_1 = a_{11}v_1 \in \text{span}\{v_1, v_2\}$$

$\therefore W_2 = \text{span}\{v_1, v_2\}$ is invariant for T

$$W_k = \text{span}\{v_1, v_2, \dots, v_k\} \quad 0 \leq k \leq n$$

$$Tv_j = \sum_{i=1}^n a_{ij}v_i = \sum_{i=1}^j a_{ij}v_i \in \text{span}\{v_1, \dots, v_j\} = W_j \subseteq W_k \text{ if } j \leq k$$

$$Tv_j \in W_k \quad 1 \leq j \leq k$$

$\therefore TW_k \subseteq W_k$

Suppose conversely that I have such a chain of invariant subspaces. Pick $0 \neq v_1 \in W_1$

$\dim(W_1) = 1$, so $W_1 = \text{span}\{v_1\}$

In W_2 , pick $v_2 \in W_2$ independent of v_1 so $\{v_1, v_2\}$ is a basis for W_2 , since $\dim W_2 = 2$

End up with a basis $\beta = \{v_1, \dots, v_n\}$ such that $W_k = \text{span}\{v_1, \dots, v_k\} \quad 1 \leq k \leq n$

Find $|T|_\beta, Tv_1 \in W_1$ since $(TW_1 \subseteq W_1)$

$$\therefore Tv_1 = a_{11}v_1$$

$$Tv_2 \in W_2$$

$$\therefore Tv_2 = a_{22}v_2 + a_{12}v_1$$

$$Tv_k \in W_k$$

$$Tv_k \in \sum_{i=1}^k a_{ik}v_i$$

$$\text{So } |T|_\beta = \begin{vmatrix} a_{11} & a_{12} & a_{13} & \dots \\ 0 & a_{22} & a_{23} & \dots \\ 0 & 0 & a_{33} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{vmatrix} \text{ is triangular}$$

Proof

Already proved $1 \Rightarrow 2, 1 \Rightarrow 3$, and $3 \Rightarrow 1$

Let's show $2 \Rightarrow 1$ by induction on n .

$n = 1$: $T = |a|_{1 \times 1}$ is always upper triangular

$n > 1$: assume theorem for $n-1$

$$p_T(x) = (x - \lambda_1)(x - \lambda_2) \dots (x - \lambda_n)$$

λ_1 is an eigenvalue of T

So we can find an eigenvector $v_1 \neq 0$ so $Tv_1 = \lambda_1 v_1$

Extend v_1 to a basis $\beta_1 = \{v_1, w_2, w_3, \dots, w_n\}$

Express T in this basis.

$$|T|_{\beta_1} = \begin{vmatrix} \lambda_1 & b_{12} & \dots & b_{1n} \\ 0 & & & \\ \vdots & & T_1 & \\ 0 & & & \end{vmatrix}$$

$$p_T(x) = \det(xI_n - T) = \det \left(\begin{vmatrix} x - \lambda_1 & -b_{12} & \dots & -b_{1n} \\ 0 & & & \\ \vdots & & xI_{n-1} - T_1 & \\ 0 & & & \end{vmatrix} \right) = (x - \lambda_1) |xI_{n-1} - T_1|$$

$$= (x - \lambda_1) p_{T_1}(x)$$

$$p_T(x) = (x - \lambda_1) p_{T_1}(x) = (x - \lambda_1)(x - \lambda_2) \dots (x - \lambda_n)$$

$$\therefore p_{T_1}(x) = (x - \lambda_2) \dots (x - \lambda_n)$$

So $p_{T_1}(x)$ factors into linear terms. By the induction hypothesis, $W = \text{span}\{w_2, \dots, w_n\}$ has another

basis $\beta' = \{v_2, \dots, v_n\}$ so that $|T_1|_{\beta} = \begin{bmatrix} a_{22} & \dots & a_{2n} \\ 0 & \dots & a_{3n} \\ \vdots & \ddots & \vdots \\ 0 & \dots & a_{nn} \end{bmatrix}$ is upper triangular.

So $\beta = \{v_1, v_2, \dots, v_n\}$ is a basis for V and

$$|T|_{\beta_1} = \begin{bmatrix} \lambda_1 & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{bmatrix}$$

So $|T|_{\beta}$ is upper triangular ■

Cayley-Hamilton Theorem

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9:56 AM

Cayley-Hamilton Theorem

$T \in \mathcal{L}(V)$, then $p_T(T) = 0$

Computational Aside

If $T = \begin{pmatrix} A & B \\ 0 & D \end{pmatrix}$, block upper triangular.

$$T^2 = \begin{pmatrix} A^2 & AB + BD \\ 0 & D^2 \end{pmatrix}$$

$$T^3 = \begin{pmatrix} A^3 & A^2B + 2ABD + BD^2 \\ 0 & D^3 \end{pmatrix}$$

...

$$T^k = \begin{pmatrix} A^k & * \\ 0 & D^k \end{pmatrix}$$

$$p(x) = a_0 + a_1x + \dots + a_dx^d$$

$$p(T)$$

$$= \begin{pmatrix} a_0I_k & 0 \\ 0 & a_0I_{n-k} \end{pmatrix} + \begin{pmatrix} a_1A & * \\ 0 & a_1D \end{pmatrix} + \dots$$

$$+ \begin{pmatrix} a_dA^d & * \\ 0 & a_dD^d \end{pmatrix} = \begin{pmatrix} p(A) & * \\ 0 & p(D) \end{pmatrix}$$

Example

$$T = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$p_T(x) = x^2 + 1$ does not factor over \mathbb{R} so it is not triangularizable over \mathbb{R}

It does factor over \mathbb{C} so it is triangularizable over \mathbb{C}

$$T \sim \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, \quad \sim \text{similar}$$

$$p_{T(T)} = T^2 + I = \begin{vmatrix} -1 & 0 \\ 0 & -1 \end{vmatrix} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 0$$

Example

$$T = \begin{vmatrix} 2 & 3 & 5 \\ -1 & -3 & -4 \\ 0 & 1 & 1 \end{vmatrix}$$

$$p_T(x) = \begin{vmatrix} x-2 & -3 & -5 \\ 1 & x+3 & 4 \\ 0 & -1 & x-1 \end{vmatrix} = (x-2)((x+3)(x-1)+4) - 1((-3)(x-1)-5) = x^3$$

x^3 splits into linear terms so T is triangularizable

$\sigma(T) = \{0\}$ - look for kernel

$$\begin{vmatrix} 2 & 3 & 5 \\ -1 & -3 & -4 \\ 0 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 3 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{vmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\ker T = \mathbb{R} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$$

$$\text{Take new basis } v_1 = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$v_2 \mapsto \begin{pmatrix} 3 \\ -3 \\ 1 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} + (-6) \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 4 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$v_3 \mapsto \begin{pmatrix} 5 \\ -4 \\ 1 \end{pmatrix} = 5 \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} - 9 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 6 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$T_{\beta_1} = \begin{vmatrix} 0 & 3 & 5 \\ 0 & -6 & -4 \\ 0 & 4 & 6 \end{vmatrix}$$

$$T_1 = \begin{vmatrix} -6 & -9 \\ 4 & 6 \end{vmatrix}, p_{T_1}(x) = x^2$$

$$\ker T_1 = \mathbb{R} \begin{pmatrix} 3 \\ -2 \end{pmatrix}$$

New bases

$$w_1 = v_1 = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, w_2 = \begin{pmatrix} 0 \\ 3 \\ -2 \end{pmatrix}, w_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$Tw_2 = \begin{vmatrix} 2 & 3 & 5 \\ -1 & -3 & -4 \\ 0 & 1 & 1 \end{vmatrix} \begin{pmatrix} 0 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} = -w_1$$

$$Tw_3 = \begin{pmatrix} 5 \\ -4 \\ 1 \end{pmatrix} = 5 \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} - 3 \begin{pmatrix} 0 \\ 3 \\ -2 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$T_{\beta} = \begin{vmatrix} 0 & -1 & 5 \\ 0 & 0 & -3 \\ 0 & 0 & 0 \end{vmatrix}$$

$|T|_{\beta}$ is upper triangular, diagonal entries all 0 since roots of $p_T(x) = x^3$ are 0, 0, 0

$$|T^2|_{\beta} = \begin{vmatrix} 0 & 0 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix}$$

$$|T^3|_{\beta} = \begin{vmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix}$$

$$T^3 = 0 = p_T(T)$$

Proof of Cayley-Hamilton Theorem

First assume $p_T(x)$ splits into linear factors.

Apply triangular theorem, find basis to triangularize T.

So wlog, T is triangular

$$p_T(x) = (x - \lambda_1)(x - \lambda_2) \dots (x - \lambda_n)$$

Proceed by induction on n.

n=1

$$T = |\lambda_1|, p_T(x) = x - \lambda_1, p_T(T) = T - \lambda_1 I = |\lambda_1| - |\lambda_1| = 0$$

Assume for $k < n$

$$\text{Write } T = \begin{vmatrix} \lambda_1 & t_{12} & \dots & t_{1n} \\ 0 & & & \\ \vdots & & T_1 & \\ 0 & & & \end{vmatrix}$$

From the proof of triangularizability

$$p_{T_1} = (x - \lambda_2)(x - \lambda_3) \dots (x - \lambda_n)$$

By the induction hypothesis $p_{T_1}(T_1) = 0$

$$\begin{aligned}
p_T &= (x - \lambda_1)P_{T_1}(x) \\
P_T(T) &= (T - \lambda_1 I)P_{T_1}(T) = \begin{vmatrix} 0 & * \\ 0 & T_1 - \lambda_1 I \end{vmatrix} P_{T_1} \left(\begin{vmatrix} \lambda_1 & * \\ 0 & T_1 \end{vmatrix} \right) = \begin{vmatrix} 0 & 0 \\ 0 & T_1 - \lambda_1 I \end{vmatrix} \begin{vmatrix} P_{T_1}(\lambda_1) & * \\ 0 & 0 \end{vmatrix} = \begin{vmatrix} 0 & 0 \\ 0 & 0 \end{vmatrix} \\
&= 0
\end{aligned}$$

So by induction $p_T(T) = 0$. For algebraically closed fields.

In general, $p_T(x)$ does not split on $\mathbb{F}[x]$ but there is always a bigger field $\mathbb{G} \supseteq \mathbb{F}$ so that $p_T(x)$ splits on $\mathbb{G}[x]$

$$T = [t_{ij}] \in M_n(\mathbb{F})$$

Can think of T as an element of $M_n(\mathbb{G})$. $p_T(x)$ splits in $\mathbb{G}[x] \therefore p_T(T) = 0$

But the calculation of $p_T(T)$ happens over \mathbb{F} since all the coefficients $a_k \in \mathbb{F}[x]$

So $p_T(x) = a_0 I + a_1 T + \dots + a_n T^n$, this is all in $M_n(\mathbb{F})$

$\therefore p_T(T) = 0$ in $M_n(\mathbb{F})$

Ideals

September-26-11
9:31 AM

Look at $\mathbb{F}[x]$ - the ring of polynomials with coefficients in \mathbb{F}

Ideal

An ideal in $\mathbb{F}[x]$ is a non-empty subset $J \subseteq \mathbb{F}[x]$ which is

- 1) a subspace
- 2) if $p \in J$ and $q \in \mathbb{F}[x]$ then $pq \in J$

Principal Ideal

A principal ideal is an ideal of the form

$$(p_0) = \{p_0q : q \in \mathbb{F}[x]\}$$

Theorem

Every ideal in $\mathbb{F}[x]$ is principal

Lemma

$T \in \mathcal{L}(V)$

$J = \{p \in \mathbb{F}[x] : p(T) = 0\}$ is a non-zero ideal in $\mathbb{F}[x]$

Corollary

$$\{p : p(T) = 0\} = (m_T)$$

Minimal Polynomial

The unique monic polynomial $m_T(x)$ generating $\{p : p(T) = 0\}$ is the minimal polynomial of T

Theorem

$T \in \mathcal{L}(V)$

Then $m_T(x)$ has the same roots as $p_T(x)$, namely $\sigma(T)$, except for multiplicity. Furthermore, it also has the same irreducible polynomial factors.

Principal Ideal

Check that (p_0) is an ideal

1. $p_0, p_r \in (p_0), \lambda \in F$ then
 $p_0q + p_0r = p_0(q+r) \in p_0$
 $\lambda(p_0q) = p_0(\lambda q) \in p_0$
 $\therefore (p_0)$ is a vector space
2. If $p_0q \in (p_0), r \in \mathbb{F}[x]$ then
 $(p_0q)r = p_0(qr) \in p_0$

Proof

Let J be an ideal of $\mathbb{F}[x]$. If $J = \{0\}$, then $J = (0)$.

Otherwise let p_0 be a monic polynomial in J of minimal degree.

$$p_0 = x^d + a_{d-1}x^{d-1} + \dots + a_0$$

Let q be any non-zero element of J . Use the division algorithm to divide p_0 into q .

$q = p_0q_1 + r$, $\deg(r) < \deg(p_0)$, but p_0 was the element of smallest degree.

\therefore by minimality, $r = 0$, so $q = p_0q_1$.

$\therefore J = (p_0)$

*monic generator is unique

Proof of Lemma

$p_T \in J$, so $J \neq \{0\}$ (by Cayley-Hamilton)

If $p, q \in J, \lambda \in \mathbb{F}[x]$

$$(p+q)(T) = p(T) + q(T) = 0$$

$$(\lambda p)(T) = \lambda p(T) = 0$$

\therefore subspace

$p \in J, q \in \mathbb{F}[x]$ then

$$(pq)(T) = p(T)q(T) = 0 \blacksquare$$

Example

$$T = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$p_T(x) = x^4, m_T(x) = x^2$$

$$T = \text{diag}(1, 1, 2, 2, 2, 3)$$

$$p_T(x) = (x-1)^2(x-2)^3(x-3)$$

$$m_T(x) = (x-1)(x-2)(x-3)$$

$$T = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

$$p_T(x) = (x-1)^3$$

$$m_T | p_T \text{ so } m_T(x) = (x-1)^d, d \in \{1, 2, 3\}$$

$$T - I = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(T - I)^2 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(T - I)^3 = 0$$

$$\therefore m_T = p_T = (x-1)^3$$

Proof of Theorem

$m_T | p_T$ so $\text{roots}(m_T) \subseteq \text{roots}(p_T) = \sigma(T)$

If λ is an eigenvalue of $T \exists v \neq 0$ eigenvector $Tv = \lambda v$

$$\therefore T^k v = \lambda^k v, \forall k \geq 0$$

$$\Rightarrow p(T)v = p(\lambda)v$$

$$\text{So } 0 = m_T(T)v = m_T(\lambda)v, \therefore m_T(\lambda) = 0$$

So $\text{roots}(m_T) \supseteq \sigma(T)$

$$\therefore \text{roots}(m_T) = \text{roots}(p_T) = \sigma(T)$$

Remark

Over a non-algebraically closed field \mathbb{F} this proof does not show the stronger fact that the same irreducible factors will be in both p_T and m_T

Possible Problem

$T \in \mathcal{L}(\mathbb{R}^4)$

$$p_T(x) = (x^2 + 1)^2$$

$$m_T | p_T, m_T \neq 1$$

$$\therefore m_T = x^2 + 1, \text{ or } (x^2 + 1)^2$$

If we can calculate $T \in \mathcal{L}(\mathbb{C}^4)$ then m_T can be

$$x^2 + 1, (x^2 + 1)^2, (x^2 + 1)(x - i), \text{ or } (x^2 + 1)(x + i)$$

Calculate $m_T(T)$ using a real basis

$$\text{Take } p(x) = (x^2 + 1)(x - i)$$

$$0 = p(T) = (T^2 + I)(T - iI) = (T^2 + I)T - i(T^2 + I) = 0 + iI$$

$$T^2 + I = 0$$

Better Proof of Theorem

The minimal polynomial $m_T(x)$ of $T \in \mathcal{L}(V)$ has degree d if $\{I, T, T^2, \dots, T^{d-1}\}$ is linearly independent, but $\{I, T, T^2, \dots, T^d\}$ is linearly dependent. $m_T(x)$ is given the unique way to express T^d as $\sum_{i=0}^{d-1} a_i T^i$

$$T^d = \sum_{i=0}^{d-1} a_i T^i$$

$$T^{d+k} = \sum_{i=0}^{d-1} a_i T^{i+k} = \sum_{i=0}^{d-1} b_i T^i$$

$$\therefore A(T) = \text{span} \{I, T, T^2, \dots, T^d\} = \text{span} \{I, T, T^2, \dots, T^{d-1}\}$$

$$\therefore d = \dim(A)$$

This unique way to express m_T does not depend on a larger field.

$\therefore m_T(x)$ is unchanged if we enlarge the base field so that $p_T(x)$ splits.

Diag. & Nilpotent

September-28-11
9:45 AM

Theorem

$T \in \mathcal{L}(V)$ and $p_T(x)$ splits then
T is diagonalizable

\Leftrightarrow

$m_T(x)$ has only simple roots.

i. e. $m_T(x) = (x - \lambda_1)(x - \lambda_2) \dots (x - \lambda_k)$

where $\sigma(T) = \{\lambda_1, \lambda_2, \dots, \lambda_k\}$

Lemma

$A, B \in \mathcal{L}(V)$

$nul(AB) \leq nul(A) + nul(B)$

Nilpotent Matrices

$T \in \mathcal{L}(V)$ is **nilpotent of order k** if $T^k = 0$ and $T^{k-1} \neq 0$

Proof of Theorem

" \Rightarrow "

$T = diag(c_1, c_2, \dots, c_n)$

$\sigma(T) = \{\lambda_1, \lambda_2, \dots, \lambda_k\}$

Rearrange bases so

$T = diag(\lambda_1, \dots, \lambda_1, \lambda_2, \dots, \lambda_2, \dots, \lambda_k, \dots, \lambda_k)$

$m_T(x)$ has $\lambda_1, \dots, \lambda_k$ as roots

$(T - \lambda_1 I)(T - \lambda_2 I) \dots (T - \lambda_k I)$

$diag(0, \dots, 0, \lambda_2, \dots, \lambda_2, \dots, \lambda_k, \dots, \lambda_k) *$

$diag(\lambda_1, \dots, \lambda_1, 0, \dots, 0, \dots, \lambda_k, \dots, \lambda_k) *$

$diag(\lambda_1, \dots, \lambda_1, \lambda_2, \dots, \lambda_2, \dots, 0, \dots, 0) = diag(0, \dots, 0) = 0$

$\therefore m_T(x) = (x - \lambda_1) \dots (x - \lambda_k)$

? 2nd Proof of \Rightarrow

$nul(T - \lambda_i) = |\{c_j : c_j = \lambda_i\}|$

$\sum_{i=1}^k nul(T - \lambda_i I) = \sum_{i=1}^k |\{c_j : c_j = \lambda_i\}| = |\{c_j\}| = n$

$\ker \prod_{i=1}^k (T - \lambda_i I) \supseteq \sum_{i=1}^k \ker(T - \lambda_i I) = V$

" \Leftarrow "

Proof of Lemma

$\ker(AB) \supseteq \ker B$

chose a basis v_1, \dots, v_b for $\ker B$, $b = nul(B)$

Extend to a basis for $\ker(AB)$: $v_1, \dots, v_b, v_{b+1}, \dots, v_{b+c}$

$span\{v_{b+1}, \dots, v_{b+c}\} \cap span\{v_1, \dots, v_b\} = \{0\}$

So $B|_{span\{v_{b+1}, \dots, v_{b+c}\}}$ is injective (1-1)

B maps $sp\{v_{b+1}, \dots, v_{b+c}\}$ into $\ker A$

$\therefore nul A = \dim \ker A \geq \dim span\{v_{b+1}, \dots, v_{b+c}\}$

$nul AB = b + c = nul(B) + c \leq nul(B) + nul(A)$

■

Back to Theorem

By hypothesis

$0 = m_T(T) = (T - \lambda_1)(T - \lambda_2) \dots (T - \lambda_k)$

$n = nul(m_T(T)) \leq \sum_{i=1}^k nul(T - \lambda_i I)$

but know that $\sum_{i=1}^k \ker(T - \lambda_i I)$ is a direct sum, so

$\sum_{i=1}^k nul(T - \lambda_i I) = \dim \left(\sum_{i=1}^k \ker(T - \lambda_i I) \right) \leq n$

Example of Nilpotent

$T = \begin{vmatrix} 1 & 1 \\ -1 & -1 \end{vmatrix}, T^2 = \begin{vmatrix} 0 & 0 \\ 0 & 0 \end{vmatrix}$

$\{0\} \subset \ker T \subset \ker T^2 = R^2$

$\ker T = \mathbb{R} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

Chose a new basis

$v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$Tv_1 = 0, Tv_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix} = v_1$

$\beta = \{v_1, v_2\}$

$[T]_\beta = \begin{vmatrix} 0 & 1 \\ 0 & 0 \end{vmatrix}$

Example

$T = \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{vmatrix}$

$$T^2 = \begin{vmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix}$$

$$T^3 = 0$$

$$T^d = 0 \Rightarrow T^n = 0, p_T(x) = x^n$$

$$\{0\} \subset \ker T \subset \ker T \subset \ker T^2 = \mathbb{R}^3$$

$$\ker T = \mathbb{R} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\ker T^2 = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$[T]_{\beta} = \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{vmatrix}$$

Jordan Nilpotent

September-30-11
9:41 AM

Jordan Nilpotent

The Jordan nilpotent of order k is

$$J_k = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ & 0 & 1 & \dots & 0 \\ & & & \dots & 1 \\ & & & & 0 \end{pmatrix}_{k \times k}$$

i. e. There is a basis e_1, e_2, \dots, e_k and
 $J_k e_i = e_{i-1} \quad 2 \leq i \leq k$
 $J_k e_1 = 0$

We can get a lot of nilpotent matrices by taking direct sums of Jordan nilpotents (Canonical form):

$$n_1 \leq n_2 \leq \dots \leq n_k$$

$$J_{n_1} \oplus J_{n_2} \oplus \dots \oplus J_{n_k}$$

Complement

If subspace $W_1 \subseteq V$ then a complement of W_1 in V is a subspace $W_2 \subseteq V$ s.t. $W_1 \cap W_2 = \{0\}$ and $W_1 + W_2 = V$.
 i.e. $V = W_1 \dot{+} W_2$

Extension

Suppose $W_1, W_2 \subseteq Y \subseteq V$
 $W_1 \cap W_2 = \{0\}$ but $W_1 + W_2 \subset Y$
 Can find $W_3 \supset W_2$ s.t. $Y = W_1 \dot{+} W_3$

Note: Nimpotence

If T is nimpotent of order k, then $m_T(x) = x^k$
 and $p_T(x) = x^n, n = \dim V$

Theorem

$T \in \mathcal{L}(V)$ is nilpotent \Leftrightarrow there is a basis in which T is strictly block upper triangular

Better Example

$$A = \begin{pmatrix} 13 & -2 & -5 & 4 \\ 6 & -8 & -4 & 1 \\ 5 & -3 & -7 & -1 \\ 1 & -5 & 3 & 2 \end{pmatrix}$$

$$A^3 = 0$$

$$\ker A = \text{sp} \left\{ \begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix} \right\}$$

$$\ker A^2 = \text{sp} \left\{ \begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$\ker A^3 = \ker A^4 = \text{sp} \left\{ \begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\text{Let } v_4 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{Let } v_3 = Av_4 = \begin{pmatrix} 4 \\ 1 \\ -1 \end{pmatrix} \in \ker A^2, v_3 \notin \ker A$$

$$\text{Let } v_2 = Av_3 = \begin{pmatrix} 2 \\ 22 \\ 22 \\ 0 \end{pmatrix} \in \ker A$$

$$\text{Find a vector } v_1 \text{ s.t. } \ker A = \text{sp}\{v_1, v_2\}, v_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$$

$$|A|_\beta = \begin{vmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{vmatrix} = |0| \oplus \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = J_1 \oplus J_3$$

Complement Example

Suppose $V = \mathbb{R}^3$

$$W_1 = \text{span} \left\{ e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

then $W_2 = \text{sp} \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ is a complement but $W'_2 = \text{sp} \left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\}$ is also a complement

$$\text{In general } W'_2 = \text{span} \left\{ \begin{pmatrix} * \\ * \\ 1 \end{pmatrix} \right\}$$

Find a Complement

To find a complement, choose a basis for W_1 , say $\{v_1, \dots, v_k\}$ extend to a basis of V $\{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$ let $W_2 = \text{span} \{v_{k+1}, \dots, v_n\}$
 Then W_2 is a complement of W_1

Proof of Extension

Same proof:

Chose basis for W_1, W_2 combine and extend to basis for Y . Remove W_1 basis and have remainder is span of W_3

Proof of Nimpotence note

T^k and $T^{k-1} \neq 0$

$$q(x) = x^k$$

$$\Rightarrow q(T) = 0 \therefore q \in J = \{p(x) : p(T) = 0\} = (m_T) = \{m_T(x)r(x)\}$$

So $m_T | x^k \therefore m_T(x) = x^d$ for some $d \leq k$

But $T^{k-1} \neq 0$ so $d \geq k \therefore m_T(x) = x^k$

$p_T(x)$ has the same roots $\therefore 0$ is the only root of p_T

$$\text{deg}(p_T) = n \therefore p_T(x) = x^n$$

Proof of Theorem

\Rightarrow

Look at

$$V_0 = \{0\}, V_1 = \ker T, \dots, V_i = \ker T^i, \dots, V_k = \ker T^k = V$$

$$\{0\} \subset V_0 \subset V_1 \subset \dots \subset V_k = V$$

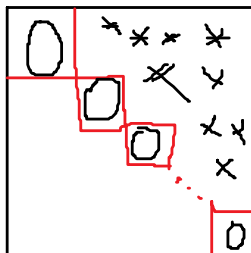
If I choose a basis v_1, \dots, v_{n_1} for V_1 and extend to basis $v_1, \dots, v_{n_1}, v_{n_1+1}, \dots, v_{n_2}$

And so on to $v_1, \dots, v_{n_1}, v_{n_1+1}, \dots, v_{n_2}, \dots, v_{(n_{k-1}+1)}, \dots, v_{n_k}$

T is block upper triangular with diagonal blocks = 0.

\Leftarrow Strictly block upper triangular

Conversely, if $|T|_\beta$ is strictly block upper triangular then T is nilpotent



Suppose $T = J_{n_1} \oplus J_{n_2} \oplus \cdots \oplus J_{n_k}$

$$n_1 \leq n_2 \leq \dots \leq n_k$$

$$\ker J_n = \mathbb{F}e_1$$

$$\ker J_n^2 = \text{span}\{e_1, e_2\}$$

$$\ker J_n^i = \text{span}\{e_1, \dots, e_i\}$$

$$\text{nul}(J_n^i) = \begin{cases} i & \text{if } i \leq n \\ n & \text{if } i > n \end{cases}$$

$$\text{nul}(J_{n_1} \oplus \cdots \oplus J_{n_k}) = k$$

$$\text{nul}(J_{n_1} \oplus \cdots \oplus J_{n_k})^2$$

Example

$$T = J_1 \oplus J_1 \oplus J_2 \oplus J_5 \oplus J_7$$

$$\text{nul}(T) = 5, \text{nul}(T^2) = 8, \text{nul}(T^3) = 10, \text{nul}(T^4) = 12, \text{nul}(T^5) = 14, \text{nul}(T^6) = 15, \text{nul}(T^7) = 16 = \dim V$$

$$\begin{aligned} \text{nul}(T^i) - \text{nul}(T^{i-1}) &= |\{n_j: n_j \geq i\}| = |\{n_j: n_j = i\}| + |\{n_j: n_j > i\}| \\ &= |\{n_j: n_j = i\}| + |\{n_j: n_j \geq i + 1\}| = |\{n_j: n_j = i\}| + \text{nul}(T^{i+1}) - \text{nul}(T^i) \\ \therefore |\{n_j: n_j = i\}| &= 2 \text{nul}(T^i) - \text{nul}(T^{i+1}) - \text{nul}(T^{i-1}) \end{aligned}$$

Nilpotent Jordan Canonical Form

October-03-11
9:37 AM

Theorem

$T \in \mathcal{L}(V)$ nilpotent of order k , then T is similar to a direct sum of Jordan nilpotents.

$$T \sim J_{n_1} \oplus J_{n_2} \oplus \dots \oplus J_{n_s}$$

$$k = n_1 \geq n_2 \geq \dots \geq n_s$$

Moreover,

$$|\{n_i = j\}| = 2n\text{ul}(T^j) - n\text{ul}(T^{j+1}) - n\text{ul}(T^{j-1})$$

Proof of Theorem

(taken from Herstein, Intro to Alg)

Induction on $n = \dim V$

$$n = 1: T = |0| = J_1$$

Now assume it holds for $\dim V < n$

$$T^k = 0 \neq T^{k-1}$$

$$\exists u_1 \in V \text{ s.t. } T^{k-1}u_1 \neq 0$$

Claim

$\{u_1, Tu_1, T^2u_1, \dots, T^{k-1}u_1\}$ is linearly independent.

$$\text{If } 0 = \sum_{i=0}^{k-1} a_i T^i u_1, \quad a_i \text{ not all zero, then } \exists i_0 \text{ s.t. } a_i = 0 \forall i < i_0, a_{i_0} \neq 0$$

$$0 = T^{k-i_0-1} \left(\sum_{i=0}^{\infty} a_i T^i u_1 \right) = a_{i_0} T^{k-1} u_1 + a_{i_0+1} T^k u_1 \dots = a_{i_0} T^{k-1} u_1$$

$$T^{k-1} u_1 \neq 0 \Rightarrow a_{i_0} = 0$$

\therefore linearly independent

Let $U = \text{sp}\{u_1, Tu_1, \dots, T^{k-1}u_1\}$

$$\dim U = k, TU \subseteq U$$

$$A = T|_U$$

$$A \begin{cases} (T^i u_1) = T^{i+1} u_1 & 0 \leq i < k-1 \\ (T^{k-1} u_1) = 0 \end{cases}$$

$$\therefore A \sim J_k$$

Need to find subspace W s.t.

$$1) U \cap W = \{0\}$$

$$2) U + W = V$$

$$3) TW \subseteq W$$

$$\Rightarrow V = U \dot{+} W$$

$$\Rightarrow T \sim T|_U \oplus T|_W$$

$$0 = T^k = (T|_U)^k \oplus (T|_W)^k$$

$B = (T|_W)$ is nilpotent of order $\leq k$

By induction, $B \sim J_{n_2} \oplus J_{n_3} \oplus \dots \oplus J_{n_s}$

$$\therefore T \sim J_k \oplus J_{n_2} \oplus \dots \oplus J_{n_s}$$

Take a maximal subspace W satisfying

$$1) U \cap W = \{0\}$$

$$2) TW \subseteq W$$

So $U \dot{+} W$ is direct

Claim: If $Tv \in U + W$, so $Tv = u + w$ $u \in U, w \in W$ then $u = \sum_{i=1}^{k-1} a_i T^i u_1$

$$\text{Let } u = \sum_{i=0}^{k-1} a_i T^i u_1$$

$$Tv = u + w$$

$$\therefore 0 = T^{k-1}(Tv) = T^{k-1}u + T^{(k-1)}w$$

$$\in U \quad \in W \quad \text{because } TU \subseteq U, TW \subseteq W$$

$$U \cap W = \{0\} \therefore T^{k-1}u = 0, T^{k-1}w = 0$$

$$0 = T^{k-1}a_0 u_1 \Rightarrow a_0 = 0$$

Claim $U + W = V$

Suppose otherwise. Pick $v \notin U + W$

Look at $v \notin U + W, Tv, T^2v, \dots, T^{k-1}v, T^k v = 0 \in U + W$

$\therefore \exists v_1 = T^i v \notin U + W$, but $Tv_1 \in U + W$

$$Tv_1 = u_2 + w_2, u_2 \in U, w_2 \in W$$

$$u_2 = \sum_{i=1}^{k-1} a_i T^i u_1 = T \left(\sum_{i=0}^{k-2} a_{i+1} T^i u_1 \right) = Tu_3$$

Let $v_2 = v_1 - u_3 \notin U + W$

$$Tv_2 = Tv_1 - Tu_3 = (u_2 + w_2) - u_2 = w_2 \in W$$

Let $W' = \text{span}\{w_2, v_2\} \supset W$

$$TW' = \text{span}\{Tw_2, Tv_2\} \subseteq W \subseteq W'$$

$$W' \cap U = \{0\}$$

(otherwise $\alpha v_2 + w \in W = u \in U \Rightarrow \alpha = u - w \in U + W \Rightarrow \alpha = 0 \Rightarrow W = 0, U = 0$)

So W is not maximal w.r.t 1), 3) a contradiction. So $U + W = V \therefore V = U \dot{+} W$

This completes the proof. ■

2nd Proof

More constructive

$$\text{Let } N_i = \ker T^i \quad 0 \leq i \leq k$$

$$\{0\} = N_0 \subset N_1 \subset N_2 \subset \dots \subset N_k = V$$

Choose a complement W_k to $N_{k-1}: N_{k-1} \dot{+} W_k = V$

Choose a basis w_1, \dots, w_{r_1} for W_k

$w_j, Tw_j, \dots, T^{k-1}w_j$ all non-zero

As first proof, they are linearly independent

$$T|_{\text{span}\{w_j, \dots, T^{k-1}w_j\}} \sim J_k$$

Claim

Tw_1, Tw_2, \dots, Tw_r are linearly independent, and $\text{sp}\{Tw_1, \dots, Tw_r\} \cap N_{k-2} = \{0\}$

Proof

Suppose $\sum_{i=1}^r a_i Tw_i = v \in N_{k-2}$

$$\therefore T^{k-2} \sum_{i=1}^r a_i Tw_i = T^{k-2}v = 0 = T^{k-1} \left(\sum_{i=1}^r a_i w_i \right)$$

$$\therefore \sum_{i=1}^r a_i w_i \in N_{i-1} \cap W_k = \{0\}$$

$\{w_i\}$ lin. indep. $\Rightarrow a_i = 0$

$\therefore \{Tw_i\}$ lin. independent, $\text{sp}\{Tw_1, \dots, Tw_r\} \cap N_{k-2} = \{0\}$

$$N_{k-2} + \text{sp}\{Tw_1, \dots, Tw_r\} \subseteq N_{k-1}$$

Find W_{k-1} s.t. $N_{k-2} + \text{span}\{Tw_1, \dots, Tw_r\} + W_{k-1} = N_{k-1}$

Choose a basis for $W_{k-1} = \{w_{r_1+1}, \dots, w_{r_2}\}$

Claim

Suppose $N_j = N_{j-1} + U_j, j \geq 2$. U_j has basis u_1, \dots, u_m

then $\{Tu_1, \dots, Tu_m\}$ is linearly independent and $\text{sp}\{Tu_1, \dots, Tu_m\} \cap N_{j-2} = \{0\}$

Proof

$$\text{If } \sum_{i=1}^m a_i Tu_i = v \in N_{j-2} \Rightarrow T^{j-2} \left(\sum_{i=1}^m a_i Tu_i \right) = T^{j-2}v = 0 \Rightarrow T^{k-1} \left(\sum_{i=1}^m a_i u_i \right)$$

$$\Rightarrow \sum_{i=1}^m a_i u_i \in N_{j-1} \cap U_j = \{0\}$$

$$\therefore a_i = 0, v = 0$$

Then I can extend $\{Tu_1, \dots, Tu_m\}$ to a complement of N_{j-2} inside N_{j-1} by adding new basis vectors

$$v_{r_{k-j}+1}, \dots, v_{r_{k+1-j}}$$

This process builds the Jordan form. Get $\dim V - \dim(N_{k-1})$ blocks of length k

Our formula was

$$2 \text{nul}(T^k) - \text{nul}(T^{k+1}) - \text{nul}(T^{k-1}) = 2n - n - \dim(N_{k-1}) = \dim V - \dim(N_{k-1})$$

$$N_j = N_{j-1} + U_j$$

$$\dim U_j = \dim N_j - \dim N_{j-1} = \# \text{ of Jordan blocks of size } \geq j$$

$$\text{nul}(T^j) - \text{nul}(T^{j-1}) = \{n_i \geq j\}$$

$$\text{nul}(T^{j+1}) - \text{nul}(T^j) = \{n_i > j\}$$

$$2 \text{nul}(T^j) - \text{nul}(T^{j+1}) - \text{nul}(T^{j-1}) = \{n_i = j\}$$

The Algebra of Nilpotent Transformation

October-05-11
10:05 AM

Homomorphism

A homomorphism between two algebras A and B over a ring K is a map $F: A \rightarrow B$ with the following properties:

- $\forall k \in K, x, y \in A$
- 1) $F(xk) = kF(x)$
- 2) $F(x + y) = F(x) + F(y)$
- 3) $F(xy) = F(x)F(y)$

Modulo Polynomials

If $m \in \mathbb{F}[x]$, (m) ideal of all multiples of m .
Say $p \equiv q \pmod{(m)}$ if $p - q \in (m) \equiv m|(p - q)$
Make $\mathbb{F}[x]/(m)$ into a ring. Elements are equivalence classes.

- $|p| = \{q \equiv p \pmod{(m)}\}$
- $|p| \pm |q| = |p \pm q|$
- $|p||q| = |pq|$

Check that this is well-defined.

- If $p_1 \equiv p_2 \pmod{(m)}, q_1 \equiv q_2 \pmod{(m)}$
- $(p_1 \pm q_1) - (p_2 \pm q_2) = (p_1 - p_2) + (q_1 - q_2) \in (m)$
- $p_1 \pm q_1 \equiv p_2 \pm q_2$
- $p_2q_2 - p_1q_1 = (p_2 - p_1)q_2 + p_1(q_2 - q_1) \in (m)$
- $p_2q_2 \equiv p_1q_1$

Algebra

An algebra is a set A which is

- 1) A vector space over a field \mathbb{F}
- 2) Has an associative multiplication
- 3) Distributive law

$$a(x \pm y) = ax \pm ay, \quad a, x, y \in A$$

$$\lambda(x + y) = \lambda x + \lambda y, \quad \lambda \in \mathbb{F}$$

Algebra of Nilpotent Transformation

$T \in \mathcal{L}(V)$
 $A(T) = \{sp \mid I, T, T^2, T^3, \dots\} = \{p(T) : p \in \mathbb{F}[x]\}$
There is a map from
 $\mathbb{F}[x] \rightarrow A(T), \quad \Phi: p \mapsto p(T)$

This is a homomorphism. i.e.

$$\alpha, \beta \in \mathbb{F}, p, q \in \mathbb{F}[x]$$

$$(\alpha p + \beta q) \mapsto (\alpha p + \beta q)(T) = \alpha p(T) + \beta q(T)$$

$$(pq) \mapsto (pq)(T) = p(T)q(T)$$

Lemma

If $T^d = 0 \neq T^{d-1}, p \in \mathbb{F}[x]$ then

- 1) $p(T)$ is invertible $\Leftrightarrow p(0) \neq 0$
- 2) $p(T) = 0 \Leftrightarrow x^d | p$

Equivalence Class

$$T = J_k = \begin{pmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & \ddots & \ddots & \\ & & & 0 & 1 \\ & & & & 0 \end{pmatrix}_{k \times k}$$

$$p(x) = a_0 + a_1x + \dots + a_mx^m$$

$$p(T) = a_0I + a_1T + a_2T^2 + \dots + a_mT^m$$

$$= \begin{pmatrix} a_0 & & & & \\ & \ddots & & & \\ & & a_0 & & \\ & & & \ddots & \\ & & & & a_0 \end{pmatrix} + \dots + \begin{pmatrix} 0 & & & & \\ & \ddots & & & \\ & & a_1 & & \\ & & & \ddots & \\ & & & & a_1 \end{pmatrix} + \dots + \begin{pmatrix} 0 & & & & \\ & \ddots & & & \\ & & a_{k-1} & & \\ & & & \ddots & \\ & & & & 0 \end{pmatrix}$$

$$= \begin{pmatrix} a_0 & a_1 & \dots & a_{k-1} \\ & \ddots & \ddots & \vdots \\ & & a_0 & a_1 \\ & & & a_0 \end{pmatrix}$$

If q is some polynomial $q(x) = b_0 + b_1x + \dots + b_mx^m$
 $p(T) = q(T)$
 $\Leftrightarrow a_i = b_i \text{ for } 0 \leq i \leq k-1$
 $\Leftrightarrow x^k | (p(x) - q(x))$
 $\Leftrightarrow p \equiv q \pmod{(x^k)}$

Algebra of Nilpotent Transformation Explanation

$T^d = 0 \neq T^{d-1}$
map is linear, preserves product
Show $p(T) = \Phi(p) = \Phi(q) = q(T) \Leftrightarrow p - q \in (x^d) \Leftrightarrow x^d | p - q$

$m \in \mathbb{F}[x]$

$\mathbb{F}[x]/(m)$ is a "quotient ring" of polynomials modulo m .

$p \equiv q \Leftrightarrow m | p - q$

$\Psi: \mathbb{F}[x] \rightarrow \mathbb{F}[x]/(x^d)$ is a homomorphism

Showed if $p_1 \equiv p_2, q_1 \equiv q_2 \pmod{x^d}$ then $ap_1 + \beta q_1 \equiv ap_2 + \beta q_2$ and $p_1q_1 \equiv p_2q_2 \pmod{x^d}$
 \therefore maps are well defined

$\ker \Phi = (x^d) = \ker \Psi$

$\mathbb{F}[x] \xrightarrow{\Phi} A(T)$

$\mathbb{F}[x] \xrightarrow{\Psi} \mathbb{F}[x]/(x^d)$

$\mathbb{F}[x] \xrightarrow{\Phi^{-1}} A(T)$

Can defined Φ^{-1} by $\Phi^{-1}(|p|) = p(T)$

Well defined $p_1 \equiv p_2 \pmod{x^d}$ then $x^d | p_1 - p_2$

$(p_1 - p_2)(x) = x^d r(x)$

$p_1(T) - p_2(T) = T^d r(T) = 0$

$\therefore p_1(T) = p_2(T)$

$\therefore \Phi^{-1}$ is well defined

Claim: Φ^{-1} is 1-1 and onto

$\Phi^{-1}(|p|) = 0 \Leftrightarrow p(T) = 0$

Proof

2) $p_T(x) = x^d$

$p(T) = 0 \Leftrightarrow x^d | p$

1) Write $p(x) = a_0 + a_1x + a_2x^2 + \dots + a_kx^k$
 $p(0) = a_0$

If $p(0) = a_0 = 0$ then $p(x) = xq(x)$

$\therefore p(T) = Tq(T)$

T is not invertible $\therefore p(T)$ is not invertible

If $p(0) = a_0 \neq 0$

$p(x) = a_0(1 + xq(x))$

$p(T) = a_0(I + Tq(T))$

Proof 1:

T upper triangular, 0 on diagonal

$$p(T) = \begin{pmatrix} a_0 & & & \\ & \ddots & & \\ & & \ddots & \\ & & & a_0 \end{pmatrix}$$

$\therefore \sigma(p(T)) = \{a_0\} \neq 0 \therefore$ invertible

Proof 2:

Let $\beta = a_0^{-1} (I - Tq(T) + (Tq(T))^2 - \dots + (-1)^d T^d q(T)^d)$

$$p(T)\beta = a_0 (I + Tq(T)) \frac{1}{a_0} (I - Tq(T) + (Tq(T))^2 - \dots + (-1)^d T^d q(T)^d)$$

$$= I - Tq(T) + (Tq(T))^2 - \dots + (-1)^d T^d q(T)^d + Tq(T) - (Tq(T))^2 - \dots + (-1)^d T^{d+1} q(T)^{d+1} = I + (-d)^d T^{d+1} q(T)^{d+1} = I$$

Φ^\sim is 1-1
 Φ^\sim is onto, $\Phi^\sim(|p|) = p(T) \in A(T)$

If $\Phi^\sim(|p|) = \Phi^\sim(|q|) \Leftrightarrow \Phi^\sim(|p - q|) = 0 \Leftrightarrow x^d |p - q| \Leftrightarrow |p - q| = 0 \Leftrightarrow |p| = |q|$

Φ^\sim is an isomorphism

(It is a bijection, homomorphism, and Φ^\sim is a homomorphism)

Did this for $T = J_d = \begin{bmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & \ddots & \ddots & \\ & & & 0 & 1 \\ & & & & 0 & 1_d \end{bmatrix}$

General case

$T = J_{n_1} \oplus J_{n_2} \oplus \dots \oplus J_{n_s}$

$n = n_1 \geq n_2 \geq \dots \geq n_s$

$T = \begin{bmatrix} 0 & 1 & & & \\ & 0 & 1 & & \\ & & \ddots & \ddots & \\ & & & 0 & 1 \\ & & & & 0 & 1 \end{bmatrix}^{d \times d} \oplus \begin{bmatrix} 0 & 1 \\ & 0 & 1 \\ & & 0 & 1 \end{bmatrix} \oplus \begin{bmatrix} 0 & 1 \\ & 0 & 1 \end{bmatrix} \oplus |0| \oplus |0|$

$p(x) = a_0 + a_1x + a_2x^2 + \dots + a_kx^k$

$p(T) = \begin{bmatrix} a_0 & a_1 & a_2 & \dots & a_{d-1} \\ & a_0 & a_1 & \dots & a_{d-1} \\ & & \ddots & \ddots & \\ & & & a_0 & a_1 \\ & & & & a_0 & a_1 \end{bmatrix}^{d \times d} \oplus \begin{bmatrix} a_0 & a_1 & a_2 \\ & a_0 & a_1 \\ & & a_0 \end{bmatrix} \oplus \begin{bmatrix} a_0 & a_1 \\ & a_0 \end{bmatrix} \oplus |a_0| \oplus |a_0|$

$p(T) \mapsto p(J_d), \quad p(T) \in A(T), p(J_d) \in A(J_d)$
 $A(J_d) \mapsto A(T)$

Jordan Forms

October-07-11
10:09 AM

Jordan Block

A Jordan block is a matrix $J(\lambda, k) = \lambda I_k + J_k = \begin{pmatrix} \lambda & 1 & \dots & \\ & \ddots & \ddots & \vdots \\ & & \lambda & 1 \\ & & & \lambda \end{pmatrix}$

Jordan Form

A Jordan form is a direct sum of Jordan blocks

From the nilpotent case, we get

Corollary

If $T \in \mathcal{L}(V)$ and $p_T(x) = (x - \lambda)^n$ then $m_T(x) = (x - \lambda)^d$ where $\ker(T - \lambda I)^{d-1} \subset \ker(T - \lambda I)^d = \ker(T - \lambda I)^{d+1}$ and T is similar to $T \sim J(\lambda, n_1) \oplus J(\lambda, n_2) \oplus \dots \oplus J(\lambda, n_s)$, $d = n_1 \leq n_2 \leq \dots \leq n_s$

Moreover,

$$|\{u_j = i\}| = 2n\text{ul}(T - \lambda I)^i - n\text{ul}(T - \lambda I)^{i-1} - n\text{ul}(T - \lambda I)^{i+1}$$

Lemma

If $T \in \mathcal{L}(V)$, $\lambda \in \mathbb{F}$ then $N_j = \ker(T - \lambda I)^j$ and $R_j = \text{range}(T - \lambda I)^j$ are invariant subspaces for T (and for any A s.t. $AT = TA$)

Proof of Corollary

$p_T(x) = (x - \lambda)^n \Leftrightarrow p_{T-\lambda I}(x) = x^n \Leftrightarrow T - \lambda I$ is nilpotent

Goal

The goal is to prove that if $p_T(x)$ splits into linear terms $p_T(x) = \prod_{i=1}^k (x - \lambda_i)^{e_i}$ then V splits as a direct sum $V = V_1 \oplus V_2 \oplus \dots \oplus V_k$ where $V_i = \ker(T - \lambda_i I)^{e_i}$

Then T is similar to

$$T \sim (T|_{V_1}) \oplus (T|_{V_2}) \oplus \dots \oplus (T|_{V_k}) = T_1 \oplus T_2 \oplus \dots \oplus T_k$$

$$(T_j - \lambda_j I)^{e_j} V_j = \{0\}$$

$$\text{So } (T_j - \lambda_j I)^{e_j} = 0$$

$$(T_j - \lambda_j I) \sim J(\lambda_j, n_{j,1}) \oplus \dots \oplus J(\lambda_j, n_{j,s_j})$$

Proof of Lemma

$x \in N_j$, then $(T - \lambda I)^j x = 0$

$$AT = TA \text{ then } (T - \lambda I)^j Ax = A(T - \lambda I)^j x = 0$$

$$\therefore Ax \in \ker(T - \lambda I)^j$$

If $y \in \text{Ran}(T - \lambda I)^j$, $y = (T - \lambda I)^j x$

$$Ay = A(T - \lambda I)^j x = (T - \lambda I)^j (Ax) \in \text{ran}(T - \lambda I)^j$$

$$J_d, \ker J_d = \text{sp}\{e_1, \dots, e_i\}$$

$$\text{ran } J_d = \text{sp}\{e_{n-i}, e_{n-i+1}, \dots, e_n\}$$

Jordan Form Theorem

October-12-11
9:32 AM

Lemma

$T \in \mathcal{L}(V)$ s.t. $(T - \lambda I)^d = 0$ then if $p \in \mathbb{F}[x]$,
 $p(T)$ is invertible
 \Leftrightarrow
 $p(\lambda) \neq 0$

Lemma

$T \in \mathcal{L}(V), \lambda \in \sigma(T)$
Let $N_i = \ker(T - \lambda I)^i$
 $R_i = \text{ran}(T - \lambda I)^i, i \geq 0$
Suppose $\{0\} = N_0 \subsetneq N_1 \subsetneq \dots \subsetneq N_d = N_{d+1}$

Then $N_{d+j} = N_d \forall j \geq 1$
and $V = R_0 \supset R_1 \supset \dots \supset R_d = R_{d+j} \forall j \geq 1$
and $V = N_d \dot{+} R_d$

Lemma

$T \in \mathcal{L}(V)$
 $\ker(T - \lambda I)^{d-1} \subsetneq \ker(T - \lambda I)^d = \ker(T - \lambda I)^{d+1}$
Then $m_T(x) = (x - \lambda)^d n(x)$ where $n(\lambda) \neq 0$

Theorem

$T \in \mathcal{L}(V)$
Assume $p_T(x)$ splits into linear factors

$$p_T(x) = \prod_{i=1}^s (x - \lambda_i)^{e_i}$$

$$\text{Let } m_T(x) = \prod_{i=1}^s (x - \lambda_i)^{d_i}$$

$V_i = \ker(T - \lambda_i I)^{d_i}$
Then $V = V_1 \dot{+} V_2 \dot{+} \dots \dot{+} V_s$

Corollary

If $p_T(x)$ splits
 $V = V_1 \dot{+} \dots \dot{+} V_s$
 $T_i = T|_{V_i} \in \mathcal{L}(V_i)$
then $(T_i - \lambda_i I)^{d_i} = 0$
 $T \sim T_1 \oplus T_2 \oplus \dots \oplus T_s$

Proof of Lemma

$T - \lambda I$ is nilpotent
 $T - \lambda I \sim J_{n_1} \oplus \dots \oplus J_{n_s}$
 $T \sim J(\lambda, n_1) \oplus \dots \oplus J(\lambda, n_s)$

Expand p around $x = \lambda$
 $p(x) = a_0(= p(\lambda)) + a_1(x - \lambda) + a_2(x - \lambda)^2 + \dots + a_n(x - \lambda)^n$
 $p(T) = p(\lambda)I + a_1(T - \lambda I) + \dots + a_n(T - \lambda I)^n = p(\lambda)I + (T - \lambda I)q(T)$
 $(T - \lambda I)q(T)$ is strictly upper triangular
Invertible $\Leftrightarrow p(\lambda) \neq 0$

Example

$$T = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 3 \end{pmatrix}$$

$N_1 = \text{sp}\{e_1\}, R_1 = \text{sp}\{e_1, e_2, e_4, e_5, e_6\}$
 $N_2 = \text{sp}\{e_1, e_2\}, R_2 = \text{sp}\{e_1, e_4, e_5, e_6\}$
 $N_3 = \text{sp}\{e_1, e_2, e_3\}, R_3 = \text{sp}\{e_3, e_5, e_6\}$
 $N_4 = \text{sp}\{e_1, e_2, e_3\}, R_3 = \text{sp}\{e_3, e_5, e_6\}$
 \vdots

Proof of Lemma

$N_{d+1} = N_d$, Proceed by induction
Assume $N_{d+j} = N_{d+j-1}$
take $v \in N_{d+j+1}$
 $\therefore (T - \lambda I)v \in N_{d+j} = N_{d+j-1}$
 $\therefore (T - \lambda I)^{d+j-1}(T - \lambda I)v = 0 = (T - \lambda I)^{d+j}v \Rightarrow v \in N_{d+j}$
 $\dim(N_i) + \dim(R_i) = n$
 $\therefore N_i \subsetneq N_{i+1} \Leftrightarrow R_i \supset R_{i+1}$
So $R_{d+j} = R_d \forall j \geq 1$

Claim

$N_d \cap R_d = \{0\}$
Take $v \in R_d \therefore \exists x \in V$ s.t. $v = (T - \lambda I)^d x$
 $v \in N_d \therefore 0 = (T - \lambda I)^d v = (T - \lambda I)^{2d} x$
 $\therefore x \in N_{2d} = N_d$
So $v = (T - \lambda I)^d x = 0$

$N_d \cap R_d = \{0\}$
So $\dim N_d + R_d = \dim N_d + \dim R_d = n$
 $\therefore N_d \dot{+} R_d = V$

Proof of Lemma

Factor $m_T(x) = (x - \lambda)^e n(x)$ where $n(\lambda) \neq 0$
Let $N_d = \ker(T - \lambda I)^d$
From Lemma, $n(T)|_{N_d}$ is invertible on $\mathcal{L}(V)$

Claim: $e \geq d$
Take $v \in N_d \setminus N_{d-1} \therefore (T - \lambda I)^{d-1}v \neq 0$
 $\therefore n(T)(T - \lambda I)^{d-1}v \neq 0$
 $\therefore n(T)(T - \lambda I)^{d-1} \neq 0$
 $\therefore e \geq d$ because $0 = m_T(T) = n(T)(T - \lambda I)^e$

Claim $e = d$
Since $0 = m_T(T)v = (T - \lambda I)^e n(T)v$
 $\Rightarrow n_T(T)v \in N_e = N_d$ (since $e \geq d$)
 $\Rightarrow (T - \lambda I)^d n(T)v = 0$
 $\Rightarrow (T - \lambda I)^d n(T) = 0$
 $m_T|_{(x - \lambda)^d n(x)}$ or $e = d$

Proof of Theorem

Let $R_1 = \text{ran}(T - \lambda_1 I)^{d_1}$, Know $V = V_1 \dot{+} R_1$
Claim: $V_i \subseteq R_1$ for $i \geq 2$
 $[(x - \lambda_i)^{d_i}]|_{\lambda_1} = (\lambda_1 - \lambda_i)^{d_i} \neq 0$

V_1 and R_1 are invariant for T and hence invariant for $(T - \lambda_i I)^{d_i}$
 $(T - \lambda_i I)^{d_i} \Big|_{V_1}$ is invertible

Take $v \in V_i, i \geq 2$. Write $v = n + r, n \in N_1, r \in R_1$
 $0 = (T - \lambda_i I)^{d_i} v = (T - \lambda_i I)^{d_i} n + (T - \lambda_i I)^{d_i} r = 0 + 0$
 (Because of direct sum, both terms are 0)
 Since $(T - \lambda_i I) \Big|_{V_1}$ is invertible, $n = 0 \therefore v = r \in R_1$

Now we can prove the theorem by induction on $n = \dim V$
 $n = 1: T = |\lambda|$
 $\lambda_1 = \lambda, V_1 = V$ Done

Assume result for $m < n$

$$V = V_1 \dot{+} R_1, T = T \Big|_{V_1} \dot{+} T \Big|_{R_1} = T_1 \oplus S$$

$$(T_1 - \lambda_1 I)^{d_1} = 0$$

S acts in $R_1, \dim R_1 < n$

$$T \sim \begin{pmatrix} T_1 & 0 \\ 0 & S \end{pmatrix} \text{ on } V = N_1 \dot{+} R_1$$

$$p_T(x) = p_{T_1}(x)p_S(x)$$

$$p_{T_1}(x) = (x - \lambda_1)^{e_1}, e_1 = \dim V_1$$

$$p_S(x) = (x - \lambda_2)^{e_2}(x - \lambda_3)^{e_3} \dots (x - \lambda_s)^{e_s}$$

By induction Hypothesis

$$R_1 = V_2 \dot{+} V_3 \dot{+} \dots \dot{+} V_s$$

$$\therefore \ker(S - \lambda_i I)^{d_i} = \ker(T - \lambda_i I)^{d_i} \subseteq R_i$$

Applications of Jordan Forms

October-14-11
9:43 AM

Jordan Form Theorem

\mathbb{F} algebraically closed (or $p_T(x)$ splits into linear terms)

$$T \in \mathcal{L}(V), p_T(x) = \prod_{i=1}^s (x - \lambda_i)^{e_i}$$

Then T is similar to

$$S \oplus_{k_i} \oplus_{j=1}^{n_{i,j}} J(\lambda_i, n_{i,j})$$

where $n_{i1} \geq n_{ik_i} \geq \sum_{j=1}^{k_i} n_{ij} = e_i$

Moreover, for each i, $|\{n_{i,j} = r\}| = 2 \text{nul}(T - \lambda_i I)^r - \text{nul}(T - \lambda_i I)^{r+1} - \text{nul}(T - \lambda_i I)^{r-1}$

Note

Jordan blocks can be used to answer similarity-invariant questions.

Proof of Jordan Form Theorem

Already been done

$V = V_1 \dot{+} V_2 \dot{+} \dots \dot{+} V_s$ where $V_i = \ker(T - \lambda_i I)^{e_i}$

Each V_i is invariant for T, and $T_i = T|_{V_i}$, then $(T_i - \lambda_i I) = 0$

$$\therefore T_i \sim \sum_{j=1}^{k_i} J(\lambda_i, n_{i,j}), \quad \sum_{j=1}^{k_i} n_{i,j} = \dim V_i = e_i$$

Cardinality of $\#\{n_{i,j} = r\}$ was done

Example

Which $A \in \mathcal{M}_3(\mathbb{C})$ satisfy $A^3 = I$?

If $A^3 = I$ and $A \sim B$ $B = SAS^{-1}$ then $B^3 = SA^3S^{-1} = SS^{-1} = I$

Look for similarity classes of solutions

$$\text{Say } A \sim \sum_{i=1}^3 J(\lambda_i, k_i)$$

$$A^3 \sim \sum_{i=1}^3 J(\lambda_i, k_i)^3$$

Look at $J(\lambda, k)^3 = (\lambda I + J_k)^3 = \lambda^3 I + 3\lambda^2 J_k + 3\lambda J_k^2 + J_k^3$

Need $\lambda^3 = 1$ and $3\lambda^2 = 0$ or $k = 1$

$\therefore \lambda \in \{1, e^{i\pi/3}, e^{-i\pi/3}\}$ and $k = 1$

So A is diagonalizable $A \sim \text{diag}(\lambda_1, \lambda_2, \lambda_3)$, $\lambda_i^3 = 1$

Count similar classes:

All λ_i same 3

2 same 1 other 3×2

3 different 1

= 10

Example

Find all A with $p_A(x) = (x - 4)^4(x + 1)^3$ and $m_A(x) = (x - 4)^3(x + 1)^2$

$\Rightarrow \dim V = 7 = \deg p_A$

$\text{nul}(A - 4I)^4 = \text{nul}(A - 4I)^3$

$\text{nul}(A + I)^3 = \text{nul}(A + I)^2$

Size of largest Jordan block is 3 (from $m_A(x)$)

$\Rightarrow A \sim J(4, 3) \oplus J(4, 1) \oplus J(-1, 2) \oplus J(-1, 1)$

Example

Find all A with $p_A(x) = (x + 2)^4(x - 1)^3$

and $m_{A(x)} = (x + 2)^2(x - 1)$

$\dim V = 4 + 3 = 7 = \deg p_A$

$\sigma(A) = \{-2, 1\}$

$\text{nul}((A + 2I)^7) = \text{nul}((A + 2I)^2) = 4$

$\text{nul}(A - I)^7 = \text{nul}(A - I)^1 = 3$

$A \sim J(-2, 2) \oplus J(-2, k_2) \oplus J(-2, k_3)$

$2 + k_2 + k_3 = 4$

$\oplus J(1, 1) \oplus J(1, 1) \oplus J(1, 1)$

Two choices $k_2 = 2$ or $k_2 = k_3 = 1$

Gives

$$\begin{vmatrix} -2 & 1 \\ 0 & -2 \end{vmatrix} \oplus \begin{vmatrix} -2 & 1 \\ 0 & -2 \end{vmatrix} \oplus I_3$$

or

$$\begin{vmatrix} -2 & 1 \\ 0 & -2 \end{vmatrix} \oplus | -2 | \oplus | -2 | \oplus I_3$$

The similarity classes of these are the solutions

Example

Which matrices have square roots?

Suppose $A \sim \sum_{i=1}^n J(\lambda_i, k_i)$

Then $A^2 \sim \sum_{i=1}^n J(\lambda_i, k_i)^2$

$$J(\lambda, k)^2 = \begin{vmatrix} \lambda & 1 & \dots \\ & \ddots & \ddots \\ & & \lambda \end{vmatrix}^2 = \begin{vmatrix} \lambda^2 & 2\lambda & 1 & \dots & 0 \\ & \ddots & \ddots & \ddots & \vdots \\ & & & & \lambda \end{vmatrix}$$

$\sigma(B) = \{\lambda^2\}$. If $\lambda \neq 0$ then $(B - \lambda^2 I) = \begin{vmatrix} 0 & 2\lambda & 1 & \dots & 0 \\ & \ddots & \ddots & \ddots & \vdots \\ & & & & 0 \end{vmatrix}$

$(B - \lambda^2 I)^{k-1} = \begin{vmatrix} 0 & 0 & \dots & 0 & (2\lambda)^{(k-1)} \\ & \ddots & \ddots & \ddots & \vdots \\ & & & & 0 \end{vmatrix}$

Jordan form for B is $J(\lambda^2, k)$

Conversely, if $\lambda \neq 0$ $J(\lambda^2, k)$ has a square root.

$$S \begin{vmatrix} \lambda^2 & 1 & 0 & \dots & 0 \\ & \ddots & \ddots & \ddots & \vdots \\ & & & & \lambda \end{vmatrix} S^{-1} = \begin{vmatrix} \lambda^2 & 2\lambda & 1 & \dots & 0 \\ & \ddots & \ddots & \ddots & \vdots \\ & & & & \lambda \end{vmatrix} = \begin{vmatrix} \lambda & 1 & \dots \\ & \ddots & \ddots \\ & & & & \lambda \end{vmatrix}^2$$

$$S^{-1} \begin{vmatrix} \lambda & 1 & \dots & \\ & \ddots & \ddots & \\ & & & \lambda \end{vmatrix} S$$

$$\lambda = 0$$

$$J_k^2 = \begin{vmatrix} 0 & 0 & 1 & \dots & 0 \\ \vdots & & & & \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{vmatrix} \sim \begin{vmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{vmatrix} \oplus \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{vmatrix}$$

If $k \geq 2$

$$J_k^2 \sim J_{\lfloor \frac{k}{2} \rfloor} \oplus J_{\lfloor \frac{k}{2} \rfloor}$$

So if A is a square, the nilpotent part of A must come in pairs of size differing by 0 or 1

Plus we can have as many J_1 s as we want

So e.g. $A \sim J(1,7) \oplus J(2,9) \oplus J(0,5) \oplus J(0,4) \oplus J(0,3) \oplus J(0,3) \oplus J(0,2) \oplus J(0,1) \oplus J(0,1)$

Is a square

The Algebra A(T)

October-17-11
9:30 AM

Generalized Eigenspace

$$V_i = \ker(T - \lambda_i)^{e_i}$$

Idempotent

A map E is idempotent iff $E^2 = E$
Projections are idempotent

Proposition

$$T \in \mathcal{L}(V), p_T(x) \text{ splits, } p_T(x) = \prod_{i=1}^s (x - \lambda_i)^{e_i}$$

Let $V_i = \ker(T - \lambda_i)^{e_i}$

Then the idempotents E_i in $\mathcal{L}(V)$ given by
 $V = V_1 \oplus V_2 \oplus \dots \oplus V_s$

$$E_i(v) = E_i\left(\sum_{j=1}^s v_j\right) = v_i, 1 \leq i \leq s \text{ belong to } A(T)$$

Chinese Remainder Theorem

$m_1, m_2, \dots, m_s \in \mathbb{N}$ relatively prime
($\gcd(m_i, m_j) = 1$ for $i \neq j$)

Then $x \equiv a_i \pmod{m_i}$ has a unique solution

$$x \equiv a \left(\text{mod } \prod_{i=1}^s m_i \right) \text{ for every choice of } a_i$$

$$\mathbb{Z} \rightarrow \mathbb{Z}/m\mathbb{Z} \rightarrow \mathbb{Z}/m_1\mathbb{Z} \oplus \mathbb{Z}/m_2\mathbb{Z} \oplus \dots \oplus \mathbb{Z}/m_s\mathbb{Z}$$

$$n \mapsto n \pmod{m}$$

$$\mapsto (n \pmod{m_1}, n \pmod{m_2}, \dots, n \pmod{m_s})$$

CRT says

$$\mathbb{Z}/m\mathbb{Z} \rightarrow \mathbb{Z}/m_1\mathbb{Z} \oplus \mathbb{Z}/m_2\mathbb{Z} \oplus \dots \oplus \mathbb{Z}/m_s\mathbb{Z}$$

is a bijection.

Chinese Remainder Theorem for Polynomials

If $m_i(x) \in \mathbb{F}[x], 1 \leq i \leq s, \gcd(m_i, m_j) = 1, i \neq j$
then if $p_i \in \mathbb{F}[x]$, the equation $p \equiv p_i \pmod{m_i}$ has
a unique solution modulo $m = m_1 m_2 \dots m_s$

Theorem

$$T \in \mathcal{L}(V), p_T \text{ splits } m_T = \prod_{i=1}^s (x - \lambda_i)^{a_i}$$

$$\text{Then } A(T) \cong A(T|_{V_1}) \oplus A(T|_{V_2}) \oplus \dots \oplus A(T|_{V_s})$$

$$A(T) \leftrightarrow \mathbb{F}[x]/(m_T)$$

$$A(T|_{V_1}) \oplus A(T|_{V_2}) \oplus \dots \oplus A(T|_{V_s})$$

$$\leftrightarrow \mathbb{F}[x]/(m_1) \oplus \dots \oplus \mathbb{F}[x]/(m_s)$$

The Algebra A(T) Description

$$T \in \mathcal{L}(V)$$

$$A(T) = \text{span}\{I, T, T^2, \dots, T^{n-1}, \dots\}$$

$$p_T(x) = x^n + \dots$$

$$\text{Cayley-Hamilton Theorem: } p_T(T) = 0$$

$$T^n = - \sum_{i=0}^{n-1} a_i T^i \in \text{span}\{I, T, \dots, T^{n-1}\}$$

$$T^{n+k} = - \sum_{i=0}^{n-1} a_i T^{i+k} \in \text{span}\{I, \dots, T^{n+k-1}\} = \text{span}\{I, \dots, T^{n-1}\}$$

by induction.

$$\text{In fact } m_T(T) = 0, m_T | p_T \text{ deg } m_T = d \leq n$$

$$T^d = \sum_{i=0}^{d-1} b_i T^i$$

$$\text{Same argument shows } A(T) = \text{span}\{I, T, \dots, T^{d-1}\} \dim A(T) = d = \text{deg } m_T$$

$$p, q \in \mathbb{F}[x] \quad p(T) = q(T) \Leftrightarrow (p - q)(T) = 0 \Leftrightarrow m_T | (p - q) \Leftrightarrow p \equiv q \pmod{m_T}$$

$\mathbb{F}[x] \rightarrow A(T): p \mapsto p(T)$ is a homomorphism; It is linear and multiplicative.

$\mathbb{F}[x] \rightarrow \mathbb{F}[x]/(m_T): p \mapsto [p]$ is a homomorphism

$\mathbb{F}[x]/(m_T) \rightarrow A(T): [p] \mapsto p(T)$ is an isomorphism.

Proof 1 of Proposition

$$\text{Let } m_T(x) = \prod_{i=1}^s (x - \lambda_i)^{d_i}$$

$$V_j = \ker(T - \lambda_j I)^{d_j}$$

So for a polynomial $p(T)$ to satisfy $p(T)v = 0 \forall v_j \in V_j$ need $(x - \lambda_j)^{d_j} | p$

$$\text{Let } q_i(x) = \prod_{j \neq i} (x - \lambda_j)^{d_j}$$

Then $q_i(T)v_j = 0 \forall v_j \in V_j, j \neq i$

Look at $q_i(T)|_{V_i}: T|_{V_i} = \lambda_i I + N_i, N_i$ nilpotent

$$q_i(T)|_{V_i} = q_i(T|_{V_i}) \Rightarrow q_i(\lambda_i) = \prod_{j \neq i} (\lambda_i - \lambda_j)^{d_j} \neq 0$$

By Lemma, $q_i(T)|_{V_i}$ is invertible. Moreover, the inverse is a polynomial of T

$$\left(\text{recall, } N = T - \lambda_i I \text{ nilpotent } q_i(N) = a_0(I + Nr(N)) \Rightarrow q_i(N)^{-1} \right.$$

$$\left. = \frac{1}{a_0} (I - Nr(N) + N^2 r(N)^2 - \dots) \text{ terminates } N^d = 0 \right)$$

So there is a polynomial $r_i \in \mathbb{F}[x]$ s.t. $e_i(T) = q_i(T)r_i(T)|_{V_i} = I|_{V_i}$

$$\text{Let } e_i(x) = q_i(x)r_i(x)$$

$$\text{Let } E_i = e_i(T) \in A(T)$$

$$v_j \in V_j, j \neq i, \quad E_i v_j = r_i(T)q_i(T)v_j = 0$$

$$E_i v_i = v_i$$

$$\therefore E_i \left(\sum_{j=1}^s v_j \right) = v_i$$

$$E_i^2 v = E_i v = v_i \Rightarrow E_i^2 = E_i$$

Proof 2 of Proposition

Consider q_1, \dots, q_s, q_i defined as before

$$\gcd(q_1, q_2, \dots, q_s) = 1 \Rightarrow \sum E_i = I$$

By the Euclidian Algorithm $\exists r_i \in \mathbb{F}[x]$ s.t. $\sum_{i=1}^s q_i r_i = 1$

Let $e_i = q_i r_i$, and $E_i = e_i(T)$

$$E_i v = E_i(v_1 + \dots + v_s) = r_i(T)q_i(T)(v_1 + \dots + v_s) = E_i v_i \in V_i \quad (q_i(T)v_j = 0, j \neq i)$$

$$v = Iv = \left(\sum_{i=1}^s E_i \right) v = \sum_{i=1}^s E_i v_i$$

Direct sum $V = \sum_{i=1}^s V_i \therefore$ unique decomposition

$$v_i = E_i v_i, \quad i = 1, 2, \dots, s$$

$$\therefore E_i^2 = E_i \text{ has range } V_i \text{ and kernel } \sum_{j \neq i} V_j$$

Example of CRT

$$m = 6, m_1 = 2, m_3 = 3$$

$\mathbb{Z} \rightarrow \mathbb{Z}/6\mathbb{Z}$

\mathbb{Z}	$\mathbb{Z}/6\mathbb{Z}$	$(\mathbb{Z}/2\mathbb{Z}, \mathbb{Z}/3\mathbb{Z})$
0	[0]	(0,0)
1	[1]	(1, 1)
2	[2]	(0, 2)
3	[3]	(1, 0)
4	[4]	(0, 1)
5	[5]	(1, 2)
\vdots	\vdots	\vdots

Proof 3 of Proposition

By Proof 2 we get $e_i = q_i r_i \in \mathbb{F}[x]$ s. t. $\sum_{i=1}^s e_i(x) = 1$

Let $m_i(x) = (x - \lambda_i)^{d_i}$, $\gcd(m_i, m_j) = 1 \forall i \neq j$

Let $m = m_1(x)m_2(x) \dots m_s(x) = m_T(x)$

Now $e_i \equiv 0 \pmod{m_j}, j \neq i$

$$1 = \sum_{j=1}^s e_j = e_i \pmod{m_i}$$

$$\therefore e_i \equiv \begin{cases} 0 \pmod{m} & j \neq i \\ 1 \pmod{m_i} & i = j \end{cases}$$

To solve $\{p \equiv p_i \pmod{m_i} \mid i \leq i \leq s\}$

$$\text{Let } p = \sum_{i=1}^s p_i e_i(x), \quad p \equiv p_i(x) \cdot 1 + \sum_{j \neq i} p_j(x) \cdot 0 \equiv p_i \pmod{m_i}$$

$$p \equiv q \pmod{m_i} \mid i \leq i \leq s$$

$$\Leftrightarrow m_i \mid (p - q) \mid 1 \leq i \leq s \Leftrightarrow m_i \mid (p - q) \Leftrightarrow p \equiv q \pmod{m}$$

Jordan Form Application

October-19-11
9:25 AM

Proposition

$T \in \mathcal{L}(V)$, p_T splits

Then T can be expressed uniquely as $T = D + N$ where D is diagonalizable and N is nilpotent and $DN = ND$.

Cyclic Vectors

$T \in \mathcal{L}(V)$ has a **cyclic vector** x if $\text{span}\{x, Tx, T^2x, \dots\} = V$

T is **cyclic** if it has a cyclic vector.

T has a cyclic vector iff $m_T = p_T$

Theorem

$T \in \mathcal{L}(V)$ TFAE

- 1) T is cyclic
- 2) $m_T = p_T$
- 3) T has a single Jordan block for each eigenvalue

Remark

1 \Leftrightarrow 2 is always true, does not require $p_T(x)$ to split.

Example use of Jordan Form

$$T \in \mathcal{L}(V), m_T = \prod (x - \lambda_i)^{d_i}$$

$$A(T) \cong \mathbb{F}[x]/(m_T) \cong \bigoplus \mathbb{F}[x]/((x - \lambda_i)^{d_i})$$

$$V_i = \ker(T - \lambda_i I)^{d_i}$$

$$V = V_1 \dot{+} V_2 \dot{+} \dots \dot{+} V_s$$

$$T_i = T|_{V_i}, m_{T_i} = (x - \lambda_i)^{d_i}$$

$$T \sim T_1 \oplus T_2 \oplus \dots \oplus T_s$$

$$p(T) \sim p(T_1) \oplus p(T_2) \oplus \dots \oplus p(T_s)$$

$$\text{but } p(T_i) = q(T_i) \text{ iff } p \equiv q \pmod{(x - \lambda_i)^{d_i}}$$

Express $p(x)$ as a Taylor around λ_i

$$p(x) = a_0 + a_1(x - \lambda_i) + a_2(x - \lambda_i)^2 + \dots$$

$$T_i \sim \sum_{j=1}^{k_i} \lambda_i I + J_{n_{ij}}$$

$$J = \begin{bmatrix} 3 & 1 & 0 & 0 \\ 0 & 3 & 1 & 0 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

$$p(x) = 1 + 2x^2 + x^3$$

$$p(3) = 1 + 29 + 27 = 46$$

$$p'(x) = 4x + 3x^2$$

$$p'(3) = 12 + 27 = 39$$

$$p''(x) = 4 + 6x, p''(3) = 22$$

$$p^{(3)}(x) = 6$$

$$\begin{aligned} p(x) &= p(3) + p'(3)(x - 3) + \frac{p''(3)}{2!}(x - 3)^2 + \frac{p^{(3)}(3)}{3!}(x - 3)^3 \\ &= 49 + 39(x - 3) + 11(x - 3)^2 + (x - 3)^3 \end{aligned}$$

$$p(J) = \begin{bmatrix} 46 & 39 & 11 & 1 \\ 0 & 46 & 39 & 11 \\ 0 & 0 & 46 & 39 \\ 0 & 0 & 0 & 49 \end{bmatrix}$$

Proof of Proposition

$$T \sim \sum_{i=1}^s T_i \sim \sum_{i=1}^s \sum_{j=1}^{k_i} \lambda_i I + J_{n_{ij}}$$

$$D \sim \sum_{i=1}^s \sum_{j=1}^{k_i} \lambda_i I$$

$$D = \sum_{i=1}^s \lambda_i E_i, E_i \text{ idempotent } \text{ran}(E_i) = V_i, \ker(E_i) = \sum_{j \neq i} V_j$$

D is a polynomial in T , $D = \sum \lambda_i E_i = (\sum \lambda_i e_i)(T)$

$$\therefore TD = DT$$

D is diagonalizable

$$N = T - D \sim \sum_{i=1}^s \sum_{j=1}^{k_i} J_{n_{ij}} \text{ is nilpotent}$$

N is also in $A(T)$

Uniqueness

Suppose $T = D_1 + N_1$, D_1 diag, N_1 nilpotent $D_1 N_1 = N_1 D_1$

D_1 commutes with $D_1 + N_1 = T \therefore D_1$ commutes with $A(T)$

$\therefore D_1$ commutes with D, N

Similarly, N_1 commutes with D, N

D_1 commutes with E_i . If $v_i \in V_i, v_i = E_i v_i$

$$D_1 v_i = D_1 E_i v_i = E_i D_1 v_i \in \text{ran } E_i = v_i$$

So V_i is invariant for D_1 (and N_1)

$$D_1 = D_1|_{V_1} \oplus D_1|_{V_2} \oplus \dots \oplus D_1|_{V_s}$$

$$D = \lambda_1 I|_{V_1} \oplus \lambda_2 I|_{V_2} \oplus \dots \oplus \lambda_s I|_{V_s}$$

Each $D_1|_{V_i}$ is diagonalizable so $(D_1 - \lambda_i I)|_{V_i}$ is diagonalizable

$\therefore D_1 - D$ is diagonalizable $\sim \text{diag}(\mu_1, \mu_2, \dots, \mu_s)$

$$D_1 + N_1 = T = D + N$$

$$\therefore D_1 - D = N - N_1$$

$$(N - N_1)^{2n} = \sum_{j=0}^{2n} (-1)^j \binom{2n}{j} N^j N_1^{2n-j} = 0$$

(Because N, N_1 commute, first =)

(Second =) $j \geq n, N_j = 0, j \leq n \Rightarrow 2n - j \geq n \therefore N_1^{2n-j} = 0$

$$0 = (D_1 - D)^{2n} \sim \text{diag}(\mu_1^{2n}, \mu_2^{2n}, \dots, \mu_n^{2n}) \therefore \mu_i^{2n} = 0 \Rightarrow \mu_i = 0 \Rightarrow D_1 = D$$

$$\therefore N_1 = T - D_1 = N$$

■

Cyclic Vectors

$$\text{If } m_T(x) = x^d + a_{d-1}x^{d-1} + \dots + a_0$$

$$0 = T^d + a_{d-1}T^{d-1} + \dots + a_1T + a_0I$$

$$T^d = -a_{d-1}T^{d-1} - \dots - a_1T - a_0I$$

$$\therefore T^d x \in \text{sp}\{x, Tx, \dots, T^{d-1}x\}$$

So $\text{sp}\{x, Tx, \dots\} = \text{sp}\{x, Tx, \dots, T^{d-1}x\}$, where $d = \deg m_T(x)$

$$\dim \text{sp}\{x, Tx, \dots, T^{d-1}x\} \leq d$$

A necessary condition for T to be cyclic is $\deg m_T = n$, i. e. $m_T = p_T$

Note that $m_T = p_T \Leftrightarrow$ there is a single Jordan block for each eigenvalue.

$$m_T(x)$$

$$= \prod_{i=0}^s (x - \lambda_i)^{d_i}, \text{ where } d_i \text{ is the size of the largest Jordan block for } \lambda_i$$

$$T \sim \sum_{i=1}^s (\lambda_i I + J_{d_i})$$

A Jordan block with basis $\{e_1, \dots, e_k\}$ has a cyclic vector e_k

Let $v_i \in V_i$ be a cyclic vector for $T|_{V_i}$

$$\text{Let } v = v_1 + v_2 + \dots + v_s$$

Claim: v is cyclic for T

$$E_i \in A(T) \text{ So } v_i = E_i v \in A(T)v = \text{sp}\{v, Tv, \dots\}$$

$$\therefore T^k v_i \in A(T)v \Rightarrow V_i \subseteq A(T)v \Rightarrow V = \sum V_i = A(T)v$$

Linear Recursion Revisited

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9:31 AM

Linear Recursion Formulae

Given x_0, x_1, \dots, x_{k-1} and the linear recursion $x_{k+n} + a_{n-1}x_{k+n-1} + a_{n-2}x_{k+n-2} + \dots + a_0x_n = 0$
Find a formula for x_k

$$\text{Let } A = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ -a_0 & -a_1 & \dots & \dots & -a_{n-1} \end{pmatrix}$$

$$\begin{pmatrix} x_k \\ x_{k+1} \\ \vdots \\ x_{k+n-1} \end{pmatrix} = A^k \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_{n-1} \end{pmatrix}$$

$$p_A(x) = \begin{vmatrix} x & -1 & 0 & \dots & 0 \\ 0 & x & -1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & x & \dots & -1 \\ a_0 & a_1 & \dots & \dots & x + a_{n-1} \end{vmatrix} = \begin{vmatrix} x & 0 & 0 & \dots & 0 \\ 0 & x & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & x & \dots & 0 \\ a_0 & a_1 + \frac{a_0}{x} & \dots & \dots & x + a_{n-1} + \frac{a_{n-2}}{x} + \dots + \frac{a_0}{x^{n-1}} \end{vmatrix} = x^n + a_{n-1}x^{n-1} + a_{n-2}x^{n-2} + \dots + a_0$$

$$\text{Factor } p_A(x) = \prod_{i=1}^s (x - \lambda_i)^{d_i}$$

Case 1: n distinct roots $\therefore n$ is diagonalizable

$A \sim \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$

$$\text{Let } v_i = \begin{pmatrix} 1 \\ \lambda_i \\ \lambda_i^2 \\ \vdots \\ \lambda_i^{n-1} \end{pmatrix} \Rightarrow Av_i = \begin{pmatrix} \lambda_i \\ \lambda_i^2 \\ \vdots \\ \lambda_i^{n-1} \\ -a_0 - a_1\lambda_i - \dots - a_{n-1}\lambda_i^{n-1} \end{pmatrix}$$

$$-a_0 - a_1\lambda_i - \dots - a_{n-1}\lambda_i^{n-1} = \lambda_i^n - p_A(\lambda_i) = \lambda_i^n$$

$$Av_i = \begin{pmatrix} \lambda_i \\ \lambda_i^2 \\ \vdots \\ \lambda_i^{n-1} \\ \lambda_i^n \end{pmatrix} = \lambda_i v_i$$

So v_1, \dots, v_n is the basis that diagonalizes A .

$$\text{Express } \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_{n-1} \end{pmatrix} = b_1 v_1 + \dots + b_n v_n$$

$$\begin{pmatrix} x_k \\ x_{k+1} \\ \vdots \\ x_{k+n-1} \end{pmatrix} = A^k \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_{n-1} \end{pmatrix} = A^k (b_1 v_1 + \dots + b_n v_n) = b_1 \lambda_1^k v_1 + b_2 \lambda_2^k v_2 + \dots + b_n \lambda_n^k v_n = \begin{pmatrix} b_1 \lambda_1^k + b_2 \lambda_2^k + \dots + b_n \lambda_n^k \\ \vdots \\ \vdots \end{pmatrix}$$

$$\text{So } \boxed{x_k = b_1 \lambda_1^k + \dots + b_n \lambda_n^k}$$

The set of possible sequences we get is the linear span of $(1, \lambda_i, \lambda_i^2, \lambda_i^3, \dots)$

Note

If $p \in \mathbb{C}[x]$ has repeated roots, say $p(x) = (x - \lambda)^2 q(x)$

Then $p'(x) = 2(x - \lambda)q(x) + (x - \lambda)^2 q'(x) = (x - \lambda)r(x)$

If $p(x) = (x - \lambda)q(x), q(\lambda) \neq 0$

$p'(x) = q(x) + (x - \lambda)q'(x)$

$p'(\lambda) = q(\lambda) \neq 0$

So p, p' have a common factor $(x - \lambda)$ iff λ is a root of p of multiplicity ≥ 2

$\therefore p$ has simple roots $\Leftrightarrow \text{gcd}(p, p') = 1$

Case 2

Repeated roots:

$$p_A(x) = \prod_{i=1}^s (x - \lambda_i)^{d_i}$$

A has a cyclic vector e_n

$$A^2 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -a_0 & -a_1 & \dots & -a_{n-1} \end{pmatrix} \begin{vmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{vmatrix} = A \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ * \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ * \end{pmatrix}$$

∴ only one Jordan block for each eigenvalue

$$A \sim \sum_{i=1}^s \oplus J(\lambda_i, d_i)$$

Pick $v_{i,0} \in \ker(A - \lambda_i I)^{(d_i)}$ but not in $\ker(A - \lambda_i I)^{d_i-1}$

Let $v_{i,j} = (A - \lambda_i I)^j v_{i,0}$, $1 \leq j \leq d_i - 1$

$\{v_{i,0}, \dots, v_{i,d_i-1}\}$ is a basis for Jordan block $\lambda_i I + J_{d_i}$

So $\{v_{i,j}; 1 \leq i \leq s, 0 \leq j \leq d_i\}$ is a basis for V

$$\text{Write } \begin{pmatrix} x_0 \\ \vdots \\ x_{n-1} \end{pmatrix} = \sum b_{ij} v_{ij}$$

What is $A^k v_{ij}$?

$$\lambda I + J_d = \begin{pmatrix} \lambda & 1 & 0 & 0 \\ 0 & \lambda & 1 & 0 \\ 0 & 0 & \lambda & 1 \\ 0 & 0 & 0 & \lambda \end{pmatrix}, v_{i,0} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}, v_{i,j} = \begin{pmatrix} \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} \lambda & 1 & 0 & 0 \\ 0 & \lambda & 1 & 0 \\ 0 & 0 & \lambda & 1 \\ 0 & 0 & 0 & \lambda \end{pmatrix}^k = (\lambda I + J_d)^k = \sum_{i=0}^k \binom{k}{i} \lambda^{k-i} J_d^i = \sum_{i=0}^{d-1} \binom{k}{i} \lambda^{k-i} J_d^i$$

$$= \begin{pmatrix} \lambda^k & k\lambda^{k-1} & \dots & \binom{k}{d-1} \lambda^{k+1-d_i} \\ 0 & \lambda^k & \dots & \binom{k}{d-2} \lambda^{k+1-d_i} \\ \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & \dots & \lambda^k \end{pmatrix}$$

$$A^k v_{i,0} = \lambda^k v_{i,0} + k\lambda^{k-1} v_{i,1} + \dots + \binom{k}{d-1} \lambda^{k+1-d_i} v_{i,d_i-1}$$

$$A^k v_{i,j} = \lambda^k v_{i,j} + k\lambda^{k-1} v_{i,j+1} + \dots + \binom{k}{?} \lambda^{k-?} v_{i,d_i-1}$$

$$\begin{pmatrix} x_0 \\ \vdots \\ x_{n-1} \end{pmatrix} = \sum b_{ij} v_{ij}$$

$$\begin{pmatrix} x_k \\ \vdots \\ x_{k+n-1} \end{pmatrix} = A^k \begin{pmatrix} x_0 \\ \vdots \\ x_{n-1} \end{pmatrix} = \sum b_{ij} A^k v_{ij} = \sum b_{ij} (\lambda^k v_{ij} + k\lambda^{k-1} v_{i,j+1} + \dots)$$

$$x_k = \sum_{i,j} b_{i,j} (\lambda_i v_{i,j}^{(1)} + k\lambda^{k-1} v_{i,j+1}^{(1)} + \dots) = \sum_{i,j} \lambda_i^k (c_{i,0} + c_{i,1}k + c_{i,2}k^2 + \dots + c_{i,d_i-1}k^{d_i-1}) = \sum_i \lambda_i^k q_i(k), \deg q_i < d_i$$

General Solution

$$x_k = \sum_i \lambda_i^k q_i(k)$$

has n unknowns $q_i(x) = c_{i,0} + c_{i,1}\lambda + \dots + c_{i,(d_i-1)}\lambda^{d_i-1}$

Know x_0, \dots, x_{n-1} solve for c_i

Solution space is spanned by

$$(1, \lambda_i, \lambda_i^2, \lambda_i^3, \dots)$$

$$(0, \lambda_i, 2\lambda_i^2, 3\lambda_i^3, \dots)$$

$$(0, \lambda_i, 2^{d_i-1}\lambda_i^2, 3^{d_i-1}\lambda_i^3, \dots)$$

Markov Chains

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11:25 AM

Discrete State Space

A discrete state space Σ is a finite set of possible states.

A **discrete** process provides probabilities for transition between states at discrete time intervals.

A process is **stationary** if the transition probabilities are time independent.

A discrete stationary process is called a **Markov process**.

Regular Markov Process

A Markov process is regular if there is an N so $(A^N)_{ij} > 0 \forall i, j$

i.e. It is possible over time to move from any state to any other.

Lemma

$A = (a_{ij}) \in \mathcal{L}(V)$

Let $\rho(A) = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{ij}|$ (max of row sum)

Then $\sigma(A) \subseteq \{\lambda : |\lambda| \leq \rho(A)\}$

Theorem

$A = (a_{ij})$ is a transition matrix.

Then $1 \in \sigma(A) \subseteq \mathbb{D} = \{\lambda : |\lambda| \leq 1\}$

Moreover, if A is regular then $\sigma(A) \subseteq \{1\} \cup \mathbb{D} = \{1\} \cup \{\lambda : |\lambda| < 1\}$ and $\text{nul}(A - I) = \text{nul}(A - I)^2 = 1$

Euclidean Norm

$$\|A\|_2 = \sqrt{\sum_{i=1}^n \sum_{j=1}^n a_{ij}^2}$$

Usual Euclidean norm on \mathbb{R}^{n^2}

Claim

$$\|AB\|_2 \leq \|A\|_2 \|B\|_2$$

Proof

$$\|AB\|_2^2 = \sum_{i=1}^n \sum_{j=1}^n \left(\sum_{k=1}^n a_{ik} b_{kj} \right)^2 \leq \sum_{i=1}^n \sum_{j=1}^n \left(\sum_{k=1}^n a_{ik}^2 \right) \left(\sum_{l=1}^n b_{lj}^2 \right)$$

By Cauchy-Schwarz inequality

$$= \left(\sum_{i=1}^n \sum_{k=1}^n a_{ik}^2 \right) \left(\sum_{j=1}^n \sum_{l=1}^n b_{lj}^2 \right) = \|A\|_2^2 \|B\|_2^2$$

Corollary

If A is a regular transition matrix, then A^m converges to $L = vu^t$ where $Av = v$, v has entries $\sum_i v_i = 1$ and $u^t = (1, 1, \dots, 1)$

This is the idempotent in $\mathcal{A}(A)$ with range $\ker(A - I)$.

Moreover, if w is any probability vector then

$$\lim_{n \rightarrow \infty} A^n w = v$$

Label the states $\Sigma = \{1, 2, \dots, n\}$. The probability of moving from state j to state i is $p_{ij} \geq 0$. So $\sum_{i=1}^n p_{ij} = 1 \forall j$

Let $A = |p_{ij}|_{n \times n} = \begin{bmatrix} p_{11} & \dots & p_{1n} \\ p_{21} & \dots & p_{2n} \\ \vdots & \dots & \vdots \\ p_{n1} & \dots & p_{nn} \end{bmatrix}$ Column sums are 1

What is the limiting behaviour as time $\rightarrow \infty$?

Initial state $p_0 = \begin{pmatrix} \alpha_1 \\ \dots \\ \alpha_n \end{pmatrix}$ At time 1 $p_1 = Ap_0, p_{n+1} = Ap_n \forall n \geq 1$

Interested in $\lim_{n \rightarrow \infty} A^n p_0$

Example

A microorganism has 3 possible reproductive states: Male, Female, and Neuter.

Male one day \rightarrow M 2/3 time, N 1/3 time next day

Female one day \rightarrow F 1/2 time, N 1/2 time next day

Neuter one day \rightarrow M 1/6, F 1/2, N 1/3

$$A = \begin{bmatrix} \frac{2}{3} & 0 & \frac{1}{6} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{3} & \frac{1}{2} & \frac{1}{3} \end{bmatrix}. \text{ Initially } p_0 = \begin{bmatrix} m_0 \\ f_0 \\ n_0 \end{bmatrix}, p_n = A^n p_0$$

$$A^T \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{2}{3} & 0 & \frac{1}{3} \\ 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{6} & \frac{1}{2} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \text{ In general } A^t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

so 1 is always an eigenvalue since $\sigma(A^T) = \sigma(A)$

$$p_A(x) = (x-1) \left(x^2 - \frac{1}{2}x - \frac{1}{12} \right), \quad \sigma(A) = \left\{ 1, \frac{1 \pm \sqrt{7}}{4} \right\} \therefore \text{Diagonalizable}$$

$$A = S^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1 + \sqrt{7}}{4} & 0 \\ 0 & 0 & \frac{1 - \sqrt{7}}{4} \end{bmatrix} S \text{ As } n \rightarrow \infty, \quad A^n = S^{-1} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} S = L$$

$L = L^2$ is the idempotent in $\mathcal{A}(A)$ with range $\text{span}(v)$ where $Av = v$ and v is a probability vector.

$$\ker(A - I) = \left[\begin{array}{ccc|c} -\frac{1}{3} & 0 & \frac{1}{6} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{3} & \frac{1}{2} & -\frac{2}{3} & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 2 & 0 & -1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 2 \end{array} \right] = 0$$

Normalize $\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ to get the probability vector $v = \begin{bmatrix} 0.2 \\ 0.4 \\ 0.4 \end{bmatrix}$

Have vectors v, v_2, v_3 a basis s.t.

$$Av = v, \quad Av_2 = \frac{1 + \sqrt{7}}{4} v_2, \quad Av_3 = \frac{1 - \sqrt{7}}{4} v_3$$

If $p_0 = a_1 v + a_2 v_2 + a_3 v_3$

$$p_n = A^n p_0 = a_1 v + \left(\frac{1 + \sqrt{7}}{4} \right)^n v_2 + \left(\frac{1 - \sqrt{7}}{4} \right)^n v_3 \rightarrow a_1 v$$

$$u = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, A^T u = u \text{ and } u^T A = u^T$$

$$u^T p_0 = m_0 + f_0 + n_0 = 1$$

$$u^T p_n = u^T (A^n p_0) = (u^T A^n) p_0 = u^T p_0 = 1, \text{ and } p_n = \begin{bmatrix} m_n \geq 0 \\ f_n \geq 0 \\ n_n \geq 0 \end{bmatrix} \text{ because } a_{ij} \geq 0$$

So p_n is a probability vector.

$$a_1 v = p_n = \lim_{n \rightarrow \infty} A^n p_0, \quad 1 = u^T (a_1 v) = a_1 \Rightarrow a_1 = 1$$

Therefore in the limit as $n \rightarrow \infty$ is 20% M, 40% F, 40% N

Proof of Lemma

Suppose $\lambda \in \sigma(A), Av = \lambda v, v \neq 0$

$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$. Pick i_0 such that $|v_{i_0}| \geq |v_i| \forall 1 \leq i \leq n$

$$|\lambda v_{i_0}| = \left| \sum_{j=1}^n a_{i_0 j} v_j \right| \leq \sum_{j=1}^n |a_{i_0 j}| |v_j| \leq \left(\sum_{j=1}^n |a_{i_0 j}| \right) |v_{i_0}| \leq \rho(A) |v_{i_0}|$$

$$\therefore |\lambda| \leq \rho(A)$$

Proof of Theorem

$u^T = (1, 1, \dots, 1)$ then $u^T A = u^T$ because column sums are all 1. So $A^T u = u$, or $1 \in \sigma(A^T) = \sigma(A)$
 $\rho(A^T) = \max\{1, 1, \dots, 1\} = 1 \therefore \sigma(A) = \sigma(A^T) \subseteq \mathbb{D}$ by Lemma

Proved first part, now prove that $(1, \dots, 1)^T$ is the only eigenvector for 1 or -1

A is regular so $\exists N$ such that $A^N = (c_{ij}), c_{ij} > 0$

Observe that A^{N+1} has strictly positive entries.

Suppose $|\lambda| = 1, A^T u = \lambda u, u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix} \neq 0$

Repeat argument in Lemma for $(A^N)^T$ and $(A^{N+1})^T$

$(A^N)^T = (c_{ij})^T$ has row sums = 1

Pick i_0 s.t. $|u_{i_0}| \geq |u_i| \forall i$

$|u_{i_0}| = |\lambda^N| |u_{i_0}| = 1 \left| \sum_{i=1}^n c_{i i_0} u_i \right| \leq 2 \sum_{i=1}^n c_{i i_0} |u_i| \leq 3 \left(\sum_{i=1}^n c_{i i_0} \right) |u_{i_0}| = 4 |u_{i_0}|$

1: Since $\lambda^N u = (A^N)^T u$

2: Since $c_{i i_0} > 0$ do not need absolute values about them.

3: An equality iff $u_i = u_{i_0} \forall i$

4: $(A^N)^T$ has row sums 1

This is an equality therefore if $u_{i_0} > 0$ then $u_i \geq 0 \forall i$.

3 must be made equal so $u_i = u_{i_0} \forall i$ so 2 is also an equality.

$\therefore u_i = u_{i_0} \Rightarrow u \in \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix} \right\}$

$\therefore \lambda u = A^T u = u \Rightarrow \lambda = 1$

So $\sigma(A) \subseteq \{1\} \cup \mathbb{D}$

$\text{nul}(A - I) = \text{nul}(A^T - I) = 1$

\therefore Single Jordan block for 1

$A \sim (I_k + J_k) \oplus \sum_{i=1}^s J(\lambda_i, k_i), |\lambda_i| < 1$

$I_k + J_k = S^{-1} A S$

$(S^{-1} A S)^m = (I + J_k)^m \oplus \sum_{i=1}^s J(\lambda_i, k_i)^m,$

For $|\lambda| < 1$

$J(\lambda, k)^m = (\lambda I_k + J_k)^m = \lambda^m I_k + \binom{m}{1} \lambda^{m-1} J_k + \binom{m}{2} \lambda^{m-2} J_k^2 + \dots + \binom{m}{k-1} \lambda^{m+1-k} J_k^{k-1}$
 $= \begin{pmatrix} \lambda^m & m\lambda^{m-1} & \dots & \binom{m}{k-1} \lambda^{m+1-k} \\ & \ddots & & \vdots \\ & & \ddots & \\ & & & \lambda^m \end{pmatrix} \rightarrow 0 \text{ as } m \rightarrow \infty$

$(I_k + J_k)^m = \begin{pmatrix} 1 & m & \dots & \binom{m}{k-1} \\ & \ddots & & \vdots \\ & & \ddots & \\ & & & 1 \end{pmatrix}$

$m = 1: (1) \rightarrow (1)$

$m \geq 2: \binom{m}{1} \|(I + J_k)^2\| \geq m \rightarrow \infty$

On the other hand

$\|(S^{-1} A S)^m\|_2 = \|S^{-1} A^m S\|_2 \leq \|S^{-1}\|_2 \|A^m\|_2 \|S\|_2$

A^m is a transition matrix so

$\sum_{i=1}^n b_{ij} = 1 \geq b_{ij} \geq 0$

$b_{ij}^2 \leq b_{ij}$

So $\|A^m\|_2^2 = \sum_{j=1}^n \sum_{i=1}^n b_{ij}^2 \leq \sum_{j=1}^n \sum_{i=1}^n b_{ij} = n$

$\left\| (I + J_k)^m + \sum_{i=1}^s J(\lambda_i, k_i)^m \right\| = \|S^{-1} A S\| \leq \sqrt{n} \|S\|_2 \|S^{-1}\|_2$

$\left\| (I + J_k)^m + \sum_{i=1}^s J(\lambda_i, k_i)^m \right\| \geq m \text{ If } \text{nul}(A - I)^2 \geq 2$

$\therefore \text{nul}(A - I)^2 = 1$

Proof of Corollary

The last argument shows that

$(S^{-1} A S)^m = (1) \oplus \sum_{i=1}^s J(\lambda_i, k_i)^m \rightarrow (1) \oplus 0$

This is the idempotent in $A(T)$ with range $\ker(T - I)$

$A^m = S T^m S^{-1} \rightarrow S((1) \oplus 0) S^{-1} = L$

L is the idempotent in $A(A)$ with range $\ker(A - I)$

So $\ker L = \text{span}\{\ker(A - \lambda_i)^{d_i}, 1 \leq i \leq s\}$

Let $v \in \ker(A - I)$

Know $u = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$ is an eigenvector for A^T , eigenvalue 1

So $u^T A = u^T$. Look at $A^m \left(\frac{1}{n}u\right)$

$$u^T \left(A^m \frac{1}{n}u\right) = (u^T A^m) \frac{1}{n}u = u^T \frac{1}{n}u = \frac{n}{n} = 1$$

$\frac{1}{n}u$ is a probability vector (w prob. vector $\Leftrightarrow w_i \geq 0, u^T w = \sum w_i = 1$)

$$u^T \left(A^m \frac{1}{n}u\right) = 1$$

$$(A^m)_{ij} \geq 0 \Rightarrow \left(A^m \frac{1}{n}u\right)_i \geq 0 \forall i$$

$$\text{Eventually } (A^m)_{ij} > 0 \Rightarrow \left(A^m \frac{1}{n}u\right) > 0$$

$$L \frac{1}{n}u = \lim_{m \rightarrow \infty} A^m \frac{1}{n}u = cv, \quad \text{probability vector}$$

$$\text{ran } L = \ker(A - I) = Iv$$

Normalize v so that $u^T v = 1 \Rightarrow \therefore c = 1$

$$A^m \left(\frac{1}{n}u\right) \rightarrow v$$

$$v = Av = A^m v = (b_{ij}) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

For m large $m_{ij} > 0, v_i \geq 0$

$$\therefore v_i = \sum_{j=1}^n b_{ij} v_j > 0$$

$L \in A(A)$

$$LA = \lim_{m \rightarrow \infty} A^m A = \lim_{m \rightarrow \infty} A^{m+1} = L$$

$$AL = \lim_{m \rightarrow \infty} A^{m+1} L$$

Write

$$L = |\alpha_1 \& \alpha_2 \& \dots \& \alpha_n|, \alpha_i \in \mathbb{R}^n$$

$$L = AL = |A\alpha_1 \& A\alpha_2 \& \dots \& A\alpha_n|$$

$$\therefore A\alpha_i = \alpha_i, \text{ so } \alpha_i = c_i v$$

Similarly,

$$L = \begin{pmatrix} \beta_1^T \\ \beta_2^T \\ \vdots \\ \beta_n^T \end{pmatrix}, \beta_i \in \mathbb{R}^n$$

$$L = LA = \begin{pmatrix} \beta_1^T A \\ \beta_2^T A \\ \vdots \\ \beta_n^T A \end{pmatrix}$$

$$\therefore \beta_i^T A = \beta_i^T \text{ or } A^T \beta_i = \beta_i$$

$$\therefore \beta_i = d_i u, u = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$$

So each row of L has all entries the same.

$$\text{If } v = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \Rightarrow L = c \begin{pmatrix} v_1 & v_1 & \dots & v_1 \\ v_2 & v_2 & \dots & v_2 \\ \vdots & \vdots & \ddots & \vdots \\ v_n & v_n & \dots & v_n \end{pmatrix}$$

L is a transition matrix $\therefore c = 1$

$$L = \begin{pmatrix} v_1 & v_1 & \dots & v_1 \\ v_2 & v_2 & \dots & v_2 \\ \vdots & \vdots & \ddots & \vdots \\ v_n & v_n & \dots & v_n \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \begin{pmatrix} 1 & 1 & \dots & 1 \end{pmatrix}$$

$$w = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} \text{ probability vector}$$

$$\lim_{m \rightarrow \infty} A^m w = Lw = (vu^T)w = v(u^T w) = v$$

Markov Chain Example

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9:30 AM

Example: Hardy-Weinberg Law

A certain gene has a dominant form G and a recessive form g. Each individual has either GG, Gg, or gg. At time 0, the probability distribution of these types is (p_0, q_0, r_0) .

Assume:

- 1) The distribution is the same for both sexes
- 2) This gene does not affect reproductive capability

p_0 of time, father is GG. Probabilities for offspring in terms of mother's type:

GG Gg gg

$$\begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

q_0 of time, father is Gg. Probability of offspring is

GG Gg gg

$$\begin{bmatrix} \frac{1}{2} & \frac{1}{4} & 0 \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{4} & \frac{1}{2} \end{bmatrix}$$

r_0 of time, father is gg. Probability of offspring is

$$\begin{bmatrix} 0 & 0 & 0 \\ 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 1 \end{bmatrix}$$

Total probability:

$$p_0 \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 1 \\ 0 & 0 & 0 \end{bmatrix} + q_0 \begin{bmatrix} \frac{1}{2} & \frac{1}{4} & 0 \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \\ 0 & \frac{1}{4} & \frac{1}{2} \end{bmatrix} + r_0 \begin{bmatrix} 0 & 0 & 0 \\ 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 1 \end{bmatrix} = \begin{bmatrix} p_0 + \frac{1}{2}q_0 & \frac{1}{2}p_0 + \frac{1}{4}q_0 & 0 \\ \frac{1}{2}q_0 + r_0 & \frac{1}{2}p_0 + \frac{1}{2}q_0 + \frac{1}{2}r_0 & p_0 + \frac{1}{2}q_0 \\ 0 & \frac{1}{4}q_0 + \frac{1}{2}r_0 & \frac{1}{2}q_0 + r_0 \end{bmatrix} = M$$

Let $\alpha_0 = p_0 + \frac{1}{2}q_0$, $\beta_0 = \frac{1}{2}q_0 + r_0$

$$M = \begin{bmatrix} \alpha_0 & \frac{1}{2}\alpha_0 & 0 \\ \beta_0 & \frac{1}{2} & \alpha_0 \\ 0 & \frac{1}{2}\beta_0 & \beta_0 \end{bmatrix}$$

To find the new probability distribution for the next generation, apply this to the probability distribution of females.

$$\begin{bmatrix} \alpha_0 & \frac{1}{2}\alpha_0 & 0 \\ \beta_0 & \frac{1}{2} & \alpha_0 \\ 0 & \frac{1}{2}\beta_0 & \beta_0 \end{bmatrix} \begin{bmatrix} p_0 \\ q_0 \\ r_0 \end{bmatrix} = \begin{bmatrix} \alpha_0(p_0 + \frac{1}{2}q_0) \\ \beta_0 p_0 + \frac{1}{2}q_0 + \alpha_0 r_0 \\ \beta_0(\frac{1}{2}q_0 + r_0) \end{bmatrix} = \begin{bmatrix} \alpha_0^2 \\ 2\alpha_0\beta_0 \\ \beta_0^2 \end{bmatrix}$$

Get a new transition matrix for a new generation (by applying the above with $\begin{bmatrix} \alpha_0^2 \\ 2\alpha_0\beta_0 \\ \beta_0^2 \end{bmatrix}$ substituted

for $\begin{bmatrix} p_0 \\ q_0 \\ r_0 \end{bmatrix}$).

$$\alpha_1 = p_1 + \frac{1}{2}q_1 = \alpha_0^2 + \frac{1}{2}2\alpha_0\beta_0 = \alpha_0(\alpha_0 + \beta_0) = \alpha_0$$

$$\beta_1 = r_1 + \frac{1}{2}q_1 = \beta_0^2 + \alpha\beta = \beta_0$$

So the new transition matrix

$$\begin{bmatrix} \alpha_1 & \frac{1}{2}\alpha_1 & 0 \\ \beta_1 & \frac{1}{2} & \alpha_1 \\ 0 & \frac{1}{2}\beta_1 & \beta_1 \end{bmatrix} = \begin{bmatrix} \alpha_0 & \frac{1}{2}\alpha_0 & 0 \\ \beta_0 & \frac{1}{2} & \alpha_0 \\ 0 & \frac{1}{2}\beta_0 & \beta_0 \end{bmatrix}$$

\therefore system is Markov.

In 2nd generation, new probabilities:

$$\begin{bmatrix} p_2 \\ q_2 \\ r_2 \end{bmatrix} = \begin{bmatrix} \alpha_0 & \frac{1}{2}\alpha_0 & 0 \\ \beta_0 & \frac{1}{2} & \alpha_0 \\ 0 & \frac{1}{2}\beta_0 & \beta_0 \end{bmatrix} \begin{bmatrix} \alpha_0 \\ 2\alpha_0\beta_0 \\ \beta_0^2 \end{bmatrix} = \begin{bmatrix} \alpha_0^3 + \alpha_0^2\beta_0 \\ \alpha_0^2\beta_0 + \alpha_0\beta_0^2 \\ \alpha_0\beta_0^2 + \beta_0^3 \end{bmatrix} = \begin{bmatrix} \alpha_0^2(\alpha_0 + \beta_0) \\ \alpha_0\beta_0(\alpha_0 + \beta_0) \\ \beta_0^2(\alpha_0 + \beta_0) \end{bmatrix} = \begin{bmatrix} \alpha_0^2 \\ 2\alpha_0\beta_0 \\ \beta_0^2 \end{bmatrix} = \begin{bmatrix} p_1 \\ q_1 \\ r_1 \end{bmatrix}$$

Stabilizes after 1 generation.

Inner Product Space

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Inner Product

An inner product on a vector space V over $\mathbb{F} = \mathbb{C}$ or \mathbb{R} is a function $\langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{F}$ s.t.

- $\langle \alpha v + \beta w, u \rangle = \alpha \langle v, u \rangle + \beta \langle w, u \rangle$
Linear in first variable
- $\langle v, w \rangle = \overline{\langle w, v \rangle}$
- $\langle v, v \rangle > 0$ if $v \neq 0$
Positive Definite

$2 \Rightarrow$

$$\langle u, \alpha v + \beta w \rangle = \alpha \langle u, v \rangle + \beta \langle u, w \rangle$$

Norm

The norm on $(V, \langle \cdot, \cdot \rangle)$ is $\|v\| = \sqrt{\langle v, v \rangle}$

Theorem

$v, u \in V, \alpha \in \mathbb{F}$

- $\|\alpha v\| = |\alpha| \|v\|$
- $\|v\| \geq 0, \|v\| = 0 \Leftrightarrow v = 0$
- Cauchy-Schwarz inequality
 $|\langle u, v \rangle| \leq \|u\| \cdot \|v\|$
Equality $\Leftrightarrow u, v$ collinear
- Triangle inequality
 $\|u + v\| \leq \|u\| + \|v\|$
Equality $\Rightarrow u, v$ collinear

Conjugate in 2nd Variable

$2 \Rightarrow$

$$\langle u, \alpha v + \beta w \rangle = \langle \alpha v + \beta w, u \rangle = \alpha \langle v, u \rangle + \beta \langle w, u \rangle = \alpha \langle v, u \rangle + \beta \langle w, u \rangle = \alpha \langle u, v \rangle + \beta \langle u, w \rangle$$

Conjugate linear in second variable.

Sesquilinear form (1/2 linear)

Examples

$$1) V = \mathbb{C}^n, \langle (x_i), (y_i) \rangle = \sum_{i=1}^n x_i y_i$$

$$2) V = \mathbb{R}^n, \langle (x_i), (y_i) \rangle = \sum_{i=1}^n x_i y_i \text{ (dot product)}$$

$$3) V = \mathbb{C}^2, \langle \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \rangle = x_1 y_1 - x_1 y_2 - x_2 y_1 + 3x_2 y_2$$

Check properties:

- Linear in 1st variable
- Symmetric
- $\langle \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rangle \geq |x_1|^2 - x_1 x_2 - x_2 x_1 + 3|x_2|^2 = |x_1 - x_2|^2 + 2|x_2|^2 \geq 0$
And equals 0 iff $x_1, x_2 = 0$, So positive definite.

$$4) V = C[0,1] \text{ (Continuous functions from } [0,1] \text{ to } [0,1])$$

$$\langle f, g \rangle = \int_0^1 f(x)g(x)dx$$

- Linear in 1st variable
- Symmetric

$$3. \langle f, f \rangle = \int_0^1 |f(x)|^2 dx$$

If $f \neq 0, f(x_0) \neq 0$ by continuity $|f(x)| \geq \delta > 0$ on $(x_0 - r, x_0 + r)$

$$\therefore \int |f(x)|^2 dx \geq \int_{x_0-r}^{x_0+r} \delta^2 dx > 0$$

Proof of Theorem

1,2 easy

3. wlog $v \neq 0$.

$$0 \leq \|u + \alpha v\|^2 = \langle u + \alpha v, u + \alpha v \rangle = \langle u, u \rangle + \alpha \langle v, u \rangle + \alpha \langle u, v \rangle + |\alpha|^2 \langle v, v \rangle$$

Take $\alpha = t \langle u, v \rangle, t \in \mathbb{R}$

$$= \langle u, u \rangle + t |\langle u, v \rangle|^2 + t |\langle u, v \rangle|^2 + t^2 |\langle u, v \rangle|^2 \|v\|^2$$

Quadratic; minimized if $t = \frac{1}{m^2}$

$$0 \leq \|u + \alpha v\|^2 = \|u\|^2 - \frac{2}{\|v\|^2} |\langle u, v \rangle|^2 + \frac{|\langle u, v \rangle|^2 \|v\|^2}{\|v\|^4} = \|u\|^2 - \frac{|\langle u, v \rangle|^2}{\|v\|^2}$$

$$\therefore |\langle u, v \rangle|^2 \leq \|u\|^2 \|v\|^2$$

Equality $\Rightarrow 0 = \left\| u - \frac{\langle u, v \rangle}{\|v\|^2} v \right\|^2 \Rightarrow u$ is a multiple of v

- $\|x + y\|^2 = \langle x + y, x + y \rangle = \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle = \|x\|^2 + 2\text{Re}(\langle x, y \rangle) + \|y\|^2 \leq \|x\|^2 + 2\|x\|\|y\| + \|y\|^2 = (\|x\| + \|y\|)^2$
equality $\Leftrightarrow x, y$ collinear and $\langle x, y \rangle \geq 0$

Example

$$\left| \sum_{i=1}^n x_i y_i \right| \leq \left(\sum_{i=1}^n |x_i|^2 \right)^{1/2} \left(\sum_{i=1}^n |y_i|^2 \right)^{1/2}$$

Example

$$\left| \int_0^1 f(x)g(x)dx \right| \leq \left(\int_0^1 |f(x)|^2 dx \right)^{1/2} \left(\int_0^1 |g(x)|^2 dx \right)^{1/2}$$

Orthogonality

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Orthogonal

Say u is orthogonal to v ($u \perp v$) if $\langle u, v \rangle = 0$

Orthonormal

A set $\{e_i\}_{i \in J}$ is orthonormal if

$$\langle e_i, e_j \rangle = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

If $M \subseteq V$, let $M^\perp = \{v \in V : \langle v, m \rangle = 0 \forall m \in M\}$

Remarks

- If $u \perp v$, then $\|u + v\|^2 = \langle u + v, u + v \rangle = \|u\|^2 + 2\operatorname{Re} \langle u, v \rangle + \|v\|^2 = \|u\|^2 + \|v\|^2$
Pythagorean Law
- M^\perp is a subspace
If $u, v \in M^\perp, \alpha, \beta \in \mathbb{C}, m \in M$
 $\langle \alpha u + \beta v, m \rangle = \alpha \langle u, m \rangle + \beta \langle v, m \rangle = 0$

Lemma

Let $\{e_1, \dots, e_n\}$ be an orthonormal (o.n.) set, and $x \in \operatorname{span}\{e_1, \dots, e_n\}$ then

$$x = \sum_{i=1}^n \langle x, e_i \rangle e_i = \sum_{i=1}^n \alpha_i e_i$$

If $y \in \sum_{i=1}^n \beta_i e_i$, then $\langle x, y \rangle = \sum_{i=1}^n \alpha_i \beta_i$

and $\|x\| = \sqrt{\sum_{i=1}^n |\alpha_i|^2}$

Note

If $\{e_1, \dots, e_n\}$ are orthonormal, and $v \in V$, then

$$v - \sum_{i=1}^n \langle v, e_i \rangle e_i \perp \operatorname{span}\{e_1, \dots, e_n\}$$

Gram-Schmidt Process

Start with a set of vectors $\{v_1, v_2, \dots, v_m\}$

Build an o.n. set with the same span.

- Throw out v_j if $v_j \in \operatorname{span}\{v_1, \dots, v_{j-1}\}$
So wlog $\{v_1, \dots, v_m\}$ is independent

- Let $e_1 = \frac{v_1}{\|v_1\|}$

$$\text{Let } e_2 = \frac{v_2 - \langle v_2, e_1 \rangle e_1}{\|v_2 - \langle v_2, e_1 \rangle e_1\|}$$

...

- If e_1, \dots, e_{k-1} are defined and o.n. Let

$$e_k = \frac{v_k - \sum_{i=1}^{k-1} \langle v, e_i \rangle e_i}{\|v_k - \sum_{i=1}^{k-1} \langle v, e_i \rangle e_i\|}$$

$$\operatorname{span}\{e_1, \dots, e_k\} = \operatorname{span}\{v_1, \dots, v_k\}$$

Lemma

If $\{e_i\}$ are orthonormal, then they are linearly independent.

Lemma

Every finite dimensional subspace $M \subseteq V$ has an orthonormal basis.

Proof of Lemma

Write $x = \sum_{i=1}^n \alpha_i e_i$

$$\langle x, e_j \rangle = \left\langle \sum_{i=1}^n \alpha_i e_i, e_j \right\rangle = \sum_{i=1}^n \alpha_i \langle e_i, e_j \rangle = \alpha_j$$

$$\langle x, y \rangle = \left\langle \sum_{i=1}^n \alpha_i e_i, \sum_{j=1}^n \beta_j e_j \right\rangle = \sum_{i=1}^n \sum_{j=1}^n \alpha_i \beta_j \langle e_i, e_j \rangle = \sum_{i=1}^n \alpha_i \beta_i$$

Example

$H = C[0,1]$ with

$$\langle f, g \rangle = \int_0^1 f(x) \overline{g(x)} dx$$

Let $e_n(x) = e^{2\pi i n x}, n \in \mathbb{Z}$

$$\langle e_n, e_m \rangle = \int_0^1 e^{2\pi i n x} \overline{e^{2\pi i m x}} dx = \int_0^1 e^{2\pi i (n-m)x} dx$$

$$= \begin{cases} 1, & n = m \\ \frac{1}{2\pi i (n-m)} e^{2\pi i (n-m)x} \Big|_0^1 = 1 - 1 = 0, & n \neq m \end{cases}$$

So $\{e_n, n \in \mathbb{Z}\}$ is orthonormal

If $c \in C[0,1]$ get a series

$$\sum_{n=-\infty}^{\infty} \langle f, e_n \rangle e_n = \sum_{n=-\infty}^{\infty} \hat{f}(n) e^{2\pi i n x}$$

Fourier Series

Proof of Lemma

If $0 = \sum_{i=1}^n \alpha_i e_i$

then $0 = \|0\| = \left\| \sum_{i=1}^n \alpha_i e_i \right\| = \sum_{i=1}^n |\alpha_i|^2$

$\therefore \alpha_i = 0 \forall i$

Proof of Lemma

Take a basis $\{v_1, \dots, v_k\}$ for M and apply the Gram-Schmidt Process to get an orthonormal basis.

Proof of Theorem(Projection)

1.

$$\operatorname{ran} P = \operatorname{span}\{e_1, \dots, e_n\} = M$$

$$\ker P = \{v : \langle v, e_i \rangle = 0 \text{ for } 1 \leq i \leq n\} = \{e_1, \dots, e_n\}^\perp$$

$$= (\operatorname{span}\{e_1, \dots, e_n\})^\perp = M^\perp$$

If $w \in M, w = \sum_{i=1}^n \alpha_i e_i$

$$Pw = \sum_{i=1}^n \langle w, e_i \rangle e_i = \sum_{i=1}^n \alpha_i e_i = w$$

$$P^2 v = P(Pv) = Pv$$

\therefore Projection onto M

2.

$$v \in V, Pv \in M$$

$$\langle v - Pv, e_i \rangle = 0 \text{ for } 1 \leq i \leq n$$

$$\therefore v - Pv \in M^\perp$$

$$v = Pv + (v - Pv)$$

$$\|v\|^2 = \|Pv\|^2 + \|v - Pv\|^2 \text{ (Pythagorean)}$$

Suppose $m \in M$

$$v - m = (Pv - m) + (v - Pv)$$

$$\therefore \|v - m\|^2 = \|Pv - m\|^2 + \|v - Pv\|^2 \geq \|v - Pv\|^2$$

$$\text{equality} \Leftrightarrow m = Pv$$

$\therefore Pv$ is the unique closest point

$\therefore Pv$ is the only projection onto M because $Pv =$ the closest point on M ■

$I - P$ is written P^\perp and P^\perp is the projection onto M^\perp

Every finite dimensional subspace $M \subseteq V$ has an orthonormal basis.

Projection

V inner product space. $P \in \mathcal{L}(V)$ is a projection if $P = P^2$ (idempotent) s.t. $\ker P \perp \text{ran } P$

Theorem (Projection)

Let M be a finite dimensional subspace of V with orthonormal basis $\{e_1, \dots, e_n\}$. Define $P \in \mathcal{L}(V)$ by

$$Pv = \sum_{i=1}^n \langle v, e_i \rangle e_i$$

Then:

- 1) P is the projection of V onto M
(i.e. $\text{ran } P = M, \ker P = M^\perp, P = P^2$)
- 2) $v \in V, \|v\|^2 = \|Pv\|^2 + \|v - Pv\|^2$
- 3) Pv is the unique closest point in M closest to v

Corollary - Bessel's Inequality

If V is an inner product space and $\{e_n : n \in S\}$ is orthonormal then

$$\sum_{n \in S} |\langle v, e_n \rangle|^2 \leq \|v\|^2 \quad \forall v \in V$$

Corollary

$f \in C[0,1], \{e^{2\pi i n x} : n \in \mathbb{Z}\}$ orthonormal

So if $a_n = \int_0^1 f(x) e^{2\pi i n x} dx$

$$\text{then } \sum_{h=-\infty}^{\infty} |a_n|^2 \leq \int_0^1 |f(x)|^2 dx$$

$\therefore Pv$ is the unique closest point

$\therefore Pv$ is the only projection onto M because $Pv =$ the closest point on M ■

$I - P$ is written P^\perp and P^\perp is the projection onto M^\perp

Proof of Corollary

If S is finite, not problem

Let $M = \text{sp}\{e_n : n \in S\}$

$$Pv = \sum_{n \in S} \langle v, e_n \rangle e_n$$

$$\text{and } \|v\|^2 \geq \|Pv\|^2 = \sum_{n \in S} |\langle v, e_n \rangle|^2$$

If S is infinite for each finite $F \subseteq S$ let $M_F = \text{sp}\{e_n, n \in F\}$

P_F , projection onto M_F

$$\text{Then } \|v\|^2 \geq \|P_F v\|^2 = \sum_{n \in F} |\langle v, e_n \rangle|^2$$

$$\therefore \|v\|^2 \geq \sup_{F \subseteq S, F \text{ finite}} \sum_{n \in F} |\langle v, e_n \rangle|^2 = \sum_{n \in S} |\langle v, e_n \rangle|^2$$

At most $\|v\|^2$ coefficients $\langle v, e_n \rangle$ have $|\langle v, e_n \rangle| \geq 1$

Otherwise \exists finite $N > \|v\|^2$ and $|F| = N$ s.t. $|\langle v, e_n \rangle| \geq 1, n \in F$

$$\Rightarrow \sum_{n \in F} |\langle v, e_n \rangle|^2 = N > \|v\|^2$$

At most $4^k \|v\|^2$ coefficients with $|\langle v, e_n \rangle| \geq \frac{1}{2^k}$

$$F_k = \left\{ n : |\langle v, e_n \rangle| \geq \frac{1}{2^k} \right\}$$

$$\|v\|^2 \geq \sum_{F_k} |\langle v, e_n \rangle|^2 \geq \frac{|F_k|}{4^k}$$

$$\therefore |F_k| \leq 4^k \|v\|^2$$

$$\text{So } \{n : \langle v, e_n \rangle \neq 0\} = \bigcup_{k \geq 0} \left\{ k : |\langle v, e_n \rangle| \geq 2^{-k} \right\}$$

Is countable

List them n_1, n_2, n_3, \dots

$$\sum_{i=1}^{\infty} |\langle v, e_{n_i} \rangle|^2 = \lim_{k \rightarrow \infty} \sum_{i=1}^k |\langle v, e_{n_i} \rangle|^2$$

$$\therefore \sum_{n \in S} |\langle v, e_n \rangle|^2 \leq \|v\|^2$$

Canonical Forms in Inner Product Spaces

November-02-11
9:33 AM

Theorem

If V is a complex inner product space, $\dim V < \infty$, $T \in \mathcal{L}(V)$. Then there is an orthonormal basis $\beta = \{e_1, \dots, e_n\}$ such that $|T|_\beta$ is upper triangular.

Adjoint

V inner product space, $T \in \mathcal{L}(V)$
The adjoint of T is the linear map T^* such that $\langle T^*v, w \rangle = \langle v, Tw \rangle \forall v, w \in V$

Fix an orthonormal basis $\xi = \{e_1, \dots, e_n\}$

$$|T|_\xi = |t_{ij}|_{n \times n}$$

$$t_{ij} = \langle Te_j, e_i \rangle$$

$$\text{Then } |T^*|_\xi = |t_{ji}|_{n \times n}$$

Proposition

If $S, T \in \mathcal{L}(V)$ then

- 1) $(S^*)^* = S$
- 2) $(\alpha S + \beta T)^* = \alpha S^* + \beta T^*$
- 3) $I^* = I$
- 4) $(ST)^* = T^*S^*$

Hermitian (Self-Adjoint)

$T \in \mathcal{L}(V)$ is Hermitian or self-adjoint if $T = T^*$

$$\text{If } T = |t_{ij}| = T^* = |t_{ji}|$$

$$\text{Then } t_{ji} = t_{ij} \text{ and } t_{ii} = t_{ii} \in \mathbb{R}$$

If we check that $|T|_\beta = |T^*|_\beta$ then it has $|T|_\xi = |T^*|_\xi$ on every basis.

Reason:

$$T = T^* \Leftrightarrow \langle Tu, v \rangle = \langle u, Tv \rangle \forall u, v \in V$$

This is basis independent.

Theorem

If $T \in \mathcal{L}(V)$, V finite and a \mathbb{C} inner product space, and $T = T^*$, then there is an orthonormal basis ξ such that

$$|T|_\xi = \begin{pmatrix} d_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & d_n \end{pmatrix} \text{ is diagonal with } d_i \in \mathbb{R}$$

So $\sigma(T) \subseteq \mathbb{R}$ and $\ker(T - \lambda_i I) \perp \ker(T - \lambda_j I)$ if $\lambda_i \neq \lambda_j \in \sigma(T)$

Corollary

If V is a finite \mathbb{R} -inner product space. $T \in \mathcal{L}(V)$ s.t. $T = T^*$ then there is an orthonormal basis ξ such that

$$|T|_\xi = \begin{pmatrix} d_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & d_n \end{pmatrix} \text{ is diagonal}$$

Proof of Theorem

Since \mathbb{C} is algebraically closed, $p_T(x)$ splits into linear terms. Hence there is a basis $\{v_1, \dots, v_n\}$ such that T is upper triangular with respect to $\{v_i\}$

Apply Gram-Schmidt process to $\{v_1, \dots, v_n\}$ to an orthonormal basis $\{e_1, \dots, e_n\}$

$$Tv_1 = t_{11}v_1$$

$$\text{Since } e_1 = \frac{v_1}{\|v_1\|}, Te_1 = t_{11}e_1$$

$$Tv_2 = t_{22}v_2 + t_{12}v_1$$

$$e_2 = \frac{v_2 - \langle v_2, e_1 \rangle e_1}{\|v_2 - \langle v_2, e_1 \rangle e_1\|} = a_1v_1 + a_2v_2$$

$$Te_2 = a_1Tv_1 + a_2Tv_2 \in \text{span}\{v_1, v_2\}$$

T upper Δ with respect to $\{v_1, \dots, v_n\}$ means $M_k = \text{span}\{v_1, v_2, \dots, v_k\}$ is invariant for T

But $\text{span}\{e_1, \dots, e_k\} = \text{span}\{v_1, \dots, v_k\}$

$$\therefore Te_k \in M_k \left(\text{i.e. } Te_k = \sum_{i=1}^k b_{ik}e_i \right)$$

So $|T|_\beta$ is upper triangular.

What is T^* ?

Fix an orthonormal basis $\xi = \{e_1, \dots, e_n\}$

$$|T|_\xi = |t_{ij}|_{n \times n}$$

$$Te_j = \sum_{i=1}^n t_{ij}e_i \Rightarrow \langle Te_j, e_i \rangle = t_{ij}$$

$$\langle T^*e_j, e_i \rangle = \langle e_j, Te_i \rangle = \langle Te_i, e_j \rangle = t_{ji}$$

$$\text{So } |T^*|_\xi = |t_{ji}|$$

Conjugate transpose of T

So we can define a linear transformation

$$T^* \in \mathcal{L}(V) \text{ with } |T^*|_\xi = |t_{ji}|$$

Need to check that the identity holds for all vectors $v, w \in T$

$$\text{Take } v = \sum_{i=1}^n \alpha_i e_i, \quad w = \sum_{j=1}^n \beta_j e_j$$

Calculate

$$\langle T^*v, w \rangle = \left\langle T^* \sum_{i=1}^n \alpha_i e_i, \sum_{j=1}^n \beta_j e_j \right\rangle = \sum_{i=1}^n \sum_{j=1}^n \alpha_i \beta_j \langle T^*e_i, e_j \rangle = \sum_{i=1}^n \sum_{j=1}^n \alpha_i \beta_j \langle Te_j, e_i \rangle$$

$$= \sum_{i=1}^n \sum_{j=1}^n \alpha_i \beta_j \langle Te_j, e_i \rangle = \left\langle T \sum_{j=1}^n \beta_j e_j, \sum_{i=1}^n \alpha_i e_i \right\rangle = \langle Tw, v \rangle = \langle v, Tw \rangle$$

So T^* is a well defined linear map.

Proof of Proposition

1.

Fix an orthonormal basis ξ

$$|S|_\xi = |s_{ij}|$$

$$|S^*|_\xi = |s_{ji}|$$

$$|S^{**}|_\xi = |s_{ij}| = |S|_\xi$$

2.

$$|\alpha S|_\xi = |\alpha s_{ij}|$$

$$|(\alpha S)^*|_\xi = |\alpha s_{ji}| = \alpha |s_{ji}| = \alpha |S^*|_\xi$$

$$|T|_\xi = |t_{ij}|$$

$$|\alpha S + \beta T|_\xi = |\alpha s_{ij} + \beta t_{ij}|_\xi$$

$$|(\alpha S + \beta T)^*|_\xi = |\alpha s_{ji} + \beta t_{ji}| = \alpha |s_{ji}| + \beta |t_{ji}| = \alpha |S^*|_\xi + \beta |T^*|_\xi$$

3.

$$I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & 1 \end{pmatrix} = I^*$$

4.

$$S = |s_{ij}|_{n \times n}, \quad T = |t_{ij}|_{n \times n}$$

$$S^* = |s_{ji}|, \quad T^* = |t_{ji}|$$

$$ST = \left| \sum_{k=1}^n s_{ik}t_{kj} \right|_{n \times n}$$

$$\therefore (ST)^* = \left| \sum_{k=1}^n s_{jk}t_{ki} \right|$$

$$T^*S^* = \left| \sum_{k=1}^n t_{ki} s_{jk} \right| = (ST)^* \blacksquare$$

Proof of Theorem

Since V is a \mathbb{C} -vector space there is an orthonormal basis ξ such that $|T|_{\xi}$ is upper triangular.

$$|T|_{\xi} = \begin{vmatrix} t_{11} & \cdots & t_{1n} \\ \vdots & \ddots & \vdots \\ 0 & \cdots & t_{nn} \end{vmatrix} = |T^*|_{\xi} = \begin{vmatrix} t_{11} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ t_{n1} & \cdots & t_{nn} \end{vmatrix}$$

If $i < j, t_{ij} = 0$ If $i = j, t_{ii} = t_{ii} \in \mathbb{R}$

$$\therefore |T|_{\xi} = \begin{vmatrix} t_{11} & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & t_{nn} \end{vmatrix}, t_{ii} \in \mathbb{R}$$

$\sigma(T) = \{t_{ii} : 1 \leq i \leq n\} \subseteq \mathbb{R}$

$\ker(T - \lambda_i I) = \text{sp}\{e_j : t_{jj} = \lambda_i\}$ are pairwise orthogonal. ■

Proof of Corollary

Fix an orthonormal basis $\beta, T = |t_{ij}|_{\beta} = |t_{ji}|_{\beta}$

Think of T as acting on \mathbb{C}^n

$$T = T^* \text{ so by Theorem } p_T(x) = \prod_{i=1}^n (x - \lambda_i) \text{ and } \lambda_i \in \mathbb{R}$$

So p_T splits in $\mathbb{R}[x]$

$\therefore T$ is triangularizable over $\mathbb{R} \exists \zeta$ s. t. $|T|_{\zeta}$ is upper triangular

Apply Gram-Schmidt to basis to get an orthonormal basis ξ and $|T|_{\xi}$ is upper Triangular and self adjoint, so the same argument shows $|T|_{\xi}$ is diagonal. ■

Unitary Maps

November-04-11

Unitary and Orthogonal Maps

V, W \mathbb{C} -inner product spaces.

$U \in \mathcal{L}(V, W)$ is called **unitary** iff it is invertible and preserves inner product: $\langle Uv_1, Uv_2 \rangle_W = \langle v_1, v_2 \rangle_V$

If V, W are \mathbb{R} -inner product spaces, call such a map **orthogonal**.

Theorem

If $\dim V = \dim W < \infty$, $U \in \mathcal{L}(V, W)$, TFAE

- 1) U is unitary
- 2)
 - a. U preserves inner product
 - b. U is isometric (preserves norm)
- 3)
 - a. U sends every orthonormal basis of V to an orthonormal basis for W
 - b. U sends some orthonormal basis of V to an orthonormal basis of W

Remark

If $V = \mathbb{C} = \text{sp}\{e_1\}, W = \mathbb{C}^2 = \text{sp}\{f_1, f_2\}$

$T(\alpha e_1) = \alpha f_1$ preserves inner product but not onto so not invertible.

Proposition

$U \in \mathcal{L}(V, W)$ is unitary \Leftrightarrow

$U^*U = I_V$ and $UU^* = I_W \Leftrightarrow$

$U^{-1} = U^*$

Unitarily Equivalent

Say two transformations $S \in \mathcal{L}(V)$ and $T \in \mathcal{L}(W)$ are **unitarily equivalent** iff \exists unitary $U \in \mathcal{L}(V, W)$ s.t. $T = USU^{-1} = USU^*$

Corollary

If T is self-adjoint ($T = T^*$) then $T \cong D$ (T unitarily equivalent to D) where D is diagonalizable with real entries.

Just a restatement of theorem that T is diagonalizable with respect to an orthonormal basis $\{f_1, \dots, f_n\}$ say $Tf_i = d_i f_i$, $d_i \in \mathbb{R}$

Say $T = [t_{ij}]$ in $\{e_1, \dots, e_n\}$ orthonormal basis. Let $Ue_i = f_i$ $1 \leq i \leq n$

Then U is unitary (takes one orthonormal basis to another) and

$(U^*TU)e_i = U^*Tf_i = U^*d_i f_i = d_i e_i$

($U^* = U^{-1}$, so $U^*f_i = e_i$)

$\therefore D = U^*TU = \text{diag}(d_1, d_2, \dots, d_n)$

Proof of Theorem

1 \Rightarrow 2a By definition

2a \Rightarrow 2b

$$\|Uv\|^2 = \langle Uv, Uv \rangle = \langle v, v \rangle = \|v\|^2$$

2b \Rightarrow 2a

Assignment 5 #5a

$$\langle Uv_1, v_2 \rangle = \frac{1}{4} (\|v_1 + v_2\|^2 - \|v_1 - v_2\|^2 + i\|v_1 + iv_2\|^2 - i\|v_1 - iv_2\|^2)$$

2a \Rightarrow 3a

If $\{e_1, \dots, e_n\}$ is an orthonormal basis for V , Let $f_i = Ue_i$

$\langle f_i, f_j \rangle = \langle Ue_i, Ue_j \rangle = \langle e_i, e_j \rangle = \delta_{ij} \therefore \{f_i\}$ is orthonormal

Since $\dim W = \dim V$, $\{f_i\}$ is an orthonormal basis.

3a \Rightarrow 3b Obvious

3b \Rightarrow a

Let $\{e_1, \dots, e_n\}$ be an orthonormal basis such that $f_i = Ue_i$ is an orthonormal basis for W .

U takes a basis for V to a basis for W $\therefore U$ is invertible

$$\text{Let } v_1 = \sum \alpha_i e_i, v_2 = \sum \beta_j e_j$$

$$\langle v_1, v_2 \rangle = \sum_{i=1}^n \alpha_i \beta_i$$

$$Uv_1 = \sum \alpha_i f_i, \quad Uv_2 = \sum \beta_j f_j$$

$$\therefore \langle Uv_1, Uv_2 \rangle = \left\langle \sum \alpha_i f_i, \sum \beta_j f_j \right\rangle = \sum \alpha_i \beta_i = \langle v_1, v_2 \rangle$$

So it preserves inner product. $\therefore U$ is unitary ■

Proof of Proposition

3rd and 2nd statements are clearly equivalent.

\Rightarrow

Let $v_1, v_2 \in V, w_i = Uv_i$

$$\langle v_1, U^*w_2 \rangle = \langle Uv_1, w_2 \rangle = \langle Uv_1, Uv_2 \rangle = \langle v_1, v_2 \rangle = \langle v, U^{-1}w_2 \rangle$$

$$\langle v_1, U^*w_2 - U^{-1}w_2 \rangle = 0 \quad \forall v_1 \in V$$

$$\therefore U^*w_2 = U^{-1}w_2, \forall w_2 \in UV = V \text{ i.e. } U^* = U^{-1}$$

\Leftarrow

U is invertible and

$$\langle Uv_1, Uv_2 \rangle = \langle U^*Uv_1, v_2 \rangle = \langle v_1, v_2 \rangle \text{ preserves } \langle, \rangle \quad \blacksquare$$

Normal Maps

November-07-11
9:40 AM

Definition

$N \in \mathcal{L}(V)$ is normal if $N^*N = NN^*$

Theorem

$T \in \mathcal{L}(V)$ is normal \Leftrightarrow

There is an orthonormal basis which diagonalizes T.

Corollary

If T is normal and

$$\sigma(T) = \{\lambda_1, \dots, \lambda_s\} \text{ then } m_T(x) = \prod_{i=1}^s (x - \lambda_i)$$

and $V_i = \ker(T - \lambda_i I)$ are pairwise orthogonal

Corollary

If U is unitary, then

$$\sigma(U) \subseteq \mathbb{T} = \{\lambda: |\lambda| = 1\}$$

and U is diagonalizable w.r.t. some o.n. basis.

Corollary

If N is normal $\sigma(N) = \{\lambda_1, \dots, \lambda_s\}$ and $V_i = \ker(N - \lambda_i I)$

The idempotent $E_i \in \mathcal{A}(N)$ onto V_i is the orthogonal projection of V onto V_i . Moreover $N = \sum_{i=1}^s \lambda_i E_i$

Corollary

If p is a polynomial, N normal write $N = \sum_{i=1}^s \lambda_i E_i$, E_i as above

$$\text{Then } p(N) = \sum_{i=1}^s p(\lambda_i) E_i$$

Rank 1 Matrices

Suppose $T \in \mathcal{L}(V, W)$ and $\text{rank}(T) = 1$

Let $K = \ker T \subseteq V$

$$n = \dim V = \text{nul}(T) + \text{rank}(T) = \dim K + 1$$

$$\therefore \dim K = n - 1$$

Pick a unit vector $e \in V$, $e \perp K$. Let $w = Te$ ($\neq 0$ since $e \notin K$)

$$V = K \oplus K^\perp = K \oplus \mathbb{F}e$$

If $v \in V$, $v = k + \lambda e$, $k \in K$, $\lambda \in \mathbb{F}$

$$Tv = T(k + \lambda e) = \lambda Te = \lambda w$$

Think of $e = \begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{pmatrix}$ as a $n \times 1$ matrix

So $e \in \mathcal{L}(\mathbb{F}, V)$ by $e(\lambda) = \lambda e$

$e^* = |\alpha_1, \alpha_2, \dots, \alpha_n| \in \mathcal{L}(V, \mathbb{F})$ is a $1 \times n$ matrix

$$\text{If } v \in V, \quad v = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

$$e^*v = |\alpha_1, \alpha_2, \dots, \alpha_n| \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} = \sum_{i=1}^n \alpha_i v_i = \langle v, e \rangle$$

$$e^*(k + \lambda e) = 0 + \lambda \|e\|^2 = \lambda$$

$$we^* = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix} |\alpha_1, \alpha_2, \dots, \alpha_n| = \begin{pmatrix} w_1 \alpha_1 & w_1 \alpha_2 & \dots & w_1 \alpha_n \\ w_2 \alpha_1 & w_2 \alpha_2 & \dots & w_2 \alpha_n \\ \vdots & \vdots & \ddots & \vdots \\ w_n \alpha_1 & w_n \alpha_2 & \dots & w_n \alpha_n \end{pmatrix}$$

$$we^* \in \mathcal{L}(\mathbb{F}, W) \cdot \mathcal{L}(V, \mathbb{F}) = \mathcal{L}(V, W)$$

$$(we^*)(k + \lambda e) = \lambda w = T(k + \lambda e)$$

$$T = we^* = Tee^*$$

Example of Normal Maps

1. $T = T^*$ are normal ($TT = TT$)

2. Unitaries are normal ($U^*U = I = UU^*$)

3. If D is diagonal w.r.t an orthonormal basis

$$D = \text{diag}(d_1, d_2, \dots), D^* = (d_1, d_2, \dots, d_n)$$

$$D^*D = DD^* = \text{diag}(|d_1|^2, |d_2|^2, \dots, |d_n|^2)$$

Proof of Theorem

\Leftarrow Example 3

\Rightarrow If T is normal then $\|Tx\| = \|T^*x\| \forall x \in V$ because:

$$\|Tx\|^2 = \langle Tx, Tx \rangle = \langle x, T^*Tx \rangle = \langle x, TT^*x \rangle = \langle T^*x, T^*x \rangle = \|T^*x\|^2$$

Choose an orthonormal basis $\{e_1, \dots, e_n\}$ so that $|T|_\beta$ is upper Δ

$$T = \begin{pmatrix} t_{11} & t_{12} & \dots & t_{1n} \\ 0 & t_{22} & \dots & t_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & t_{nn} \end{pmatrix}, T^* = \begin{pmatrix} t_{11} & 0 & \dots & 0 \\ t_{12} & t_{22} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ t_{1n} & t_{2n} & \dots & t_{nn} \end{pmatrix}$$

$$\|Te_1\|^2 = \|t_{11}e_1\|^2 = |t_{11}|^2$$

$$\|Te_1\|^2 = \|T^*e_1\|^2 = \|t_{11}e_1 + t_{12}e_2 + \dots + t_{1n}e_n\|^2 = \sum_{j=1}^n |t_{1j}|^2 = |t_{11}|^2 + \sum_{j=2}^n |t_{1j}|^2$$

$$\therefore t_{1j} = 0 \text{ for } 2 \leq j \leq n$$

$$\text{Repeat } \|Te_2\| = |t_{22}| = \|T^*e_2\| = \sqrt{\sum_{j=2}^n |t_{2j}|^2}$$

$$\therefore t_{2j} = 0 \text{ } 3 \leq j \leq n$$

$\therefore T$ is diagonal ■

Proof of Corollary

Since T is diagonalizable wrt some basis, $m_T(x) = \prod (x - \lambda_i)$ has only simple roots.

Say $\{e_i\}_{i=1}^n$ orthonormal, $Te_i = d_i e_i$

$$V_j = \ker(T - \lambda_j I) = \text{sp}\{e_i: d_i = \lambda_j\}$$

$\therefore V_j$ are pairwise \perp

Proof of Corollary

U normal \therefore diagonalizable

Say $Ue_i = d_i e_i$, $\{e_i\}$ orthonormal

$$\|Ue_i\| = \|e_i\| = 1$$

$$\|Ue_i\| = |d_i| \|e_i\| = |d_i|$$

$$\therefore |d_i| = 1$$

Proof of Corollary

E_i is the projection onto V_i

The range of E_i is V_i and

$$\ker(E_i) = \sum_{j \neq i} V_j = V_i^\perp$$

$$V_i = \text{sp}\{e_k: d_k = \lambda_i\}$$

$$\sum_{j \neq i} V_j = \text{sp}\{e_k: d_k \neq \lambda_i\} = V_i^\perp$$

$$NE_i = E_i N = \lambda_i E_i$$

$$\text{So } N = N \left(\sum_{i=1}^s E_i \right) = \sum_{i=1}^s \lambda_i E_i$$

Example

Orthogonal projection on to $\mathbb{F}e$

$Te = e$ so

$$T = ee^* = \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} |\alpha_1 \dots \alpha_n| = |\alpha_i \alpha_j|$$

Polar Decomposition

November-09-11
9:30 AM

Complex

$$z \in \mathbb{C}, z = re^{i\theta}, \quad r = |z|, |e^{i\theta}| = 1$$

Positive

$T \in \mathcal{L}(V), V \subset \mathbb{C}$ -vector space is **positive** if $T = T^*$ and $\sigma(T) \subseteq [0, \infty)$
Write $T \geq 0$

Proposition

If $T \in \mathcal{L}(V)$ then $T^*T \geq 0$

Square Root

T^*T can be diagonalized with orthonormal basis $\xi = \{e_1, e_2, \dots, e_n\}$
 $|T^*T|_\xi = \text{diag}(d_1, d_2, \dots, d_n), \quad d_i \geq 0$

$\sqrt{d_i}$ the square root of d_i

$$|A|_\xi = \text{diag}(\sqrt{d_1}, \sqrt{d_2}, \dots, \sqrt{d_n}) \text{ and } A^2 = T^*T$$

i.e. A is the square root of T^*T call this $|T|$ (absolute value of T)

Fact (Homework)

The square root of T^*T is unique

Want to write $T = U|T|$

Partial Isometry

A partial isometry is a map $U \in \mathcal{L}(V, W)$ such that $U|_{\ker U^\perp}$ is isometric (preserves norm)

Examples

$U: \mathbb{C}^2 \rightarrow \mathbb{C}^3$ by $U(x, y) = (x, y, 0)$

$U^*: \mathbb{C}^3 \rightarrow \mathbb{C}^2$ by $U^*(x, y, z) = (x, y)$ –not unitary

U unitary is a partial isometry

Proposition

$U \in \mathcal{L}(V, W)$ TFAE

1. U is a partial isometry
2. U^*U is a projection (onto $(\ker U)^\perp$)
3. UU^* is a projection (onto $\text{ran } U$)
4. $U = UU^*U$

Theorem (Polar Decomposition)

If $T \in \mathcal{L}(V, W)$ then there is a unique partial isometry U with $\ker U = \ker T$ such that $T = U|T|$ ($|T| = \sqrt{T^*T}$)

S-Numbers

The s-numbers of $T \in \mathcal{L}(V, W)$ are the eigenvalues of $|T|$ (including multiplicity) in decreasing order.

Geometry of how T acts

$$|T| = \text{diag}(s_1, s_2, \dots, s_n) \text{ wrt } \{e_1, e_n\}$$

If considering the action on a unit sphere, T stretches it onto an ellipsoid (axis length defined by s-numbers). U is a partial rotation in space.

Proof of Proposition

$$(T^*T)^* = T^*T^{**} = T^*T$$

$$\text{If } T^*Tx = \lambda x, \|x\| = 1$$

$$\lambda = \langle \lambda x, x \rangle = \langle T^*Tx, x \rangle = \langle Tx, Tx \rangle = \|Tx\|^2 \geq 0$$

$$\therefore T^*T \geq 0$$

Proof of Proposition

$$1 \Rightarrow 2$$

$$\ker U \supseteq \ker U^*U$$

$$x \in \ker U^*U \Rightarrow 0 = \langle U^*Ux, x \rangle = \langle Ux, Ux \rangle = \|Ux\|^2$$

$$\therefore x \in \ker U, \ker U \subseteq \ker U^*U$$

$$\therefore \ker U = \ker U^*U$$

$$\text{If } x \perp \ker U \text{ then } \|Ux\| = \|x\|$$

$$\langle x, x \rangle = \|x\|^2 = \|Ux\|^2 = \langle Ux, Ux \rangle = \langle U^*Ux, x \rangle$$

$$\text{ran } (U^*U) \perp \ker U \text{ since } y \in \ker U:$$

$$\langle U^*Ux, y \rangle = \langle Ux, Uy \rangle = \langle Ux, 0 \rangle = 0$$

$$x, y \in (\ker U)^\perp$$

$$\langle U^*Ux, y \rangle = \langle Ux, Uy \rangle = \langle x, y \rangle \text{ (because of isomorphism)}$$

$$U^*Ux \in (\ker U)^\perp$$

Take orthonormal basis $\{e_1, \dots, e_k\}$ for $(\ker U)^\perp$

$$\langle U^*Ue_i, e_j \rangle = \langle e_i, e_j \rangle = \delta_{ij}$$

$$\therefore U^*Ue_i = \sum_j \langle U^*Ue_i, e_j \rangle e_j = e_i$$

$$\therefore U^*Ux = x \text{ for } x \in (\ker U)^\perp$$

$$\therefore U^*U \text{ is the projection onto } (\ker U)^\perp$$

$$2 \Rightarrow 1, \text{ if } x \in (\ker U)^\perp$$

$$\|Ux\|^2 = \langle Ux, Ux \rangle = \langle U^*Ux, x \rangle = \langle x, x \rangle = \|x\|^2$$

$$1 \Rightarrow 3$$

Claim:

If U is a partial isometry so is U^*

Claim

$$\ker U^* = (\text{ran } U)^\perp$$

Proof of Claim

If $y \perp \text{ran } U$, then $0 = \langle y, Ux \rangle \forall x \in V$

$$0 = \langle U^*y, x \rangle, \text{ Take } x = U^*y$$

$$0 = \langle U^*y, U^*y \rangle = \|U^*y\|^2$$

$$\text{If } y \in \ker U^*, x \in V$$

$$\langle y, Ux \rangle = \langle U^*y, x \rangle = 0$$

$$\therefore y \perp \text{ran } U$$

$$\therefore \ker U^* \perp \text{ran } U \blacksquare$$

On the $\text{ran } U$

$$U^*(Ux) = P_{\ker U}^\perp Ux$$

$y \in \text{ran } U$ replace x by U^*Ux becomes $x - U^*Ux \in \ker U$

$$0 = Ux - UU^*Ux \Rightarrow Ux = UU^*Ux \text{ (2} \Rightarrow 4)$$

$$y = Ux, x = U^*Ux, U^*y = U^*Ux = x$$

$$y = Ux, \quad x = U^*Ux$$

$$U^*y = x$$

$$\|U^*y\| = \|x\| = \|Ux\| = \|y\|$$

U^* is a partial isometry

\Leftrightarrow

$$UU^* = U^{**}U^* \text{ is a projection}$$

$$4 \Rightarrow 2$$

$$U = UU^*U$$

$$\therefore U^*U = U^*UU^*U = (U^*U)^2$$

Self adjoint, idempotent \therefore projection

Proof of Polar Decomposition Theorem

Diagonalize $|T| = \text{diag}(s_1, s_2, \dots, s_n), \quad s_1 \geq s_2 \geq \dots \geq s_n \geq 0$

Claim

$$\|Tx\| = \||T|x\| \quad \forall x \in V$$

Proof

$$\||T|x\|^2 = \langle |T|x, |T|x \rangle = \langle |T|^2x, x \rangle = \langle T^*Tx, x \rangle = \langle Tx, Tx \rangle = \|Tx\|^2$$

■

$$\ker |T| = \ker T = \text{sp}\{e_i : s_i = 0\}$$

$$\text{ran } |T| = \text{sp}\{e_i : s_i > 0\} = (\ker T)^\perp$$

Define U on $\text{ran } |T|$ by $U(|T|x) = Tx$

U is isometric on $\text{ran } |T|$ by

Claim

Define $U|_{\ker T} = 0$

$$U\left(\sum_{i=1}^k a_i e_i\right) = U\left(\sum_{i=1}^k a_i e_i\right), \sum_{i=1}^k a_i e_i \in \text{ran } T$$

U is a partial isometry $T = U|T|$

Remark

$\{e_1, \dots, e_k\}$ orthonormal basis for $(\ker T)^\perp$. Let $f_i = Ue_i, 1 \leq i \leq k$
 f_i are orthonormal in W

$$|T| = \sum_{i=1}^k s_i e_i e_i^*, e_i e_i^* \text{ is projection to } \mathbb{C}e_i$$

$$T = U|T| = \sum_{i=1}^k s_i (f_i e_i^*), \text{rank 1 projection sends } e_i \mapsto f_i$$

$$U = \sum_{i=1}^k f_i e_i^*$$

Least Square Approximation

November-11-11
9:30 AM

An experiment is run to test whether the output, y is a linear function of the input variables: x_1, \dots, x_n

Run the experiment m times ($m \gg n$) to get a bunch of data.

x_1	x_2	...	x_n	y_n
x_{11}	x_{12}		x_{1n}	y_1
\vdots	\vdots	\vdots	\vdots	\vdots
x_{m1}	y_m

Looking for $a_1, \dots, a_n \in \mathbb{R}$ or \mathbb{C} so that

$$\sum_{j=1}^n a_j x_{ij} \approx y_i \text{ for } 1 \leq i \leq m$$

$$\text{minimize}_{a_1, \dots, a_n} \left(\sqrt{\sum_{i=1}^m \left| y_i - \sum_{j=1}^n a_j x_{ij} \right|^2} \right)$$

$$\text{Let } X_1 = \begin{bmatrix} x_{11} \\ x_{12} \\ \vdots \\ x_{1m} \end{bmatrix}, \dots, X_j = \begin{bmatrix} x_{j1} \\ x_{j2} \\ \vdots \\ x_{jm} \end{bmatrix}, \quad 1 \leq j \leq n, \quad Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

Problem becomes

$$\text{minimize}_{a_1, \dots, a_n} \left\| Y - \sum_{j=1}^n a_j X_j \right\|_2 = \text{dist}(Y, \text{span}\{X_1, \dots, X_n\}) = \left\| Y - P_{\text{sp}\{X_j\}} Y \right\|_2$$

We must choose a_1, \dots, a_n so that $\sum_{j=1}^n a_j X_j = P_{\text{sp}\{X_j\}} Y$

These are the scalars such that $\left\langle Y - \sum_{j=1}^n a_j X_j, X_i \right\rangle = 0, \quad 1 \leq i \leq n$

$$\left\langle Y - \sum_{j=1}^n a_j X_j, X_i \right\rangle = \langle Y, X_i \rangle - \sum_{j=1}^n a_j \langle X_j, X_i \rangle = X_i^* Y - \sum_{j=1}^n a_j X_i^* X_j$$

$$\text{Let } X = [X_1, \dots, X_n], \text{ then } X^* Y = \begin{bmatrix} X_1^* \\ X_2^* \\ \vdots \\ X_n^* \end{bmatrix} Y = \begin{bmatrix} X_1^* Y \\ X_2^* Y \\ \vdots \\ X_n^* Y \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^n a_j X_1^* X_j \\ \sum_{j=1}^n a_j X_2^* X_j \\ \vdots \\ \sum_{j=1}^n a_j X_n^* X_j \end{bmatrix}$$

$$X^* X = \begin{bmatrix} X_1^* \\ X_2^* \\ \vdots \\ X_n^* \end{bmatrix} [X_1 \ X_2 \ \dots \ X_n] = \begin{bmatrix} X_1^* X_1 & \dots & X_1^* X_n \\ \vdots & \ddots & \vdots \\ X_n^* X_1 & \dots & X_n^* X_n \end{bmatrix}$$

$$\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^n a_j X_1^* X_j \\ \sum_{j=1}^n a_j X_2^* X_j \\ \vdots \\ \sum_{j=1}^n a_j X_n^* X_j \end{bmatrix} = X^* X a = X^* Y$$

If X_1, \dots, X_n are linearly independent then X has rank n .

Claim

$$\text{rank}(X^* X) = \text{rank } X$$

Proof

$$\text{rank}(X) = \dim(\text{domain}) - \text{nul}(X) = n - \text{nul}(X)$$

Example

x_1	x_2	y	ax
7	3	1.6	1.86
9	2	2.1	1.94
5	5	2.0	2.02
4	6	2.2	2.10
3	1	0.8	0.73
3	2	1.1	0.98

$$X^* X = \begin{bmatrix} 189 & 97 \\ 97 & 79 \end{bmatrix}, X^* Y = \begin{bmatrix} 54.6 \\ 35.2 \end{bmatrix}$$

$$(X^* X)^{-1} = \begin{bmatrix} 0.0143 & -0.0176 \\ -0.0176 & 0.0324 \end{bmatrix}$$

$$a = \begin{bmatrix} 0.161 \\ 0.243 \end{bmatrix}$$

$$\text{rank}(X^*X) = n - \text{nul } X^*X$$

If $x \in \ker X$ then $X^*Xx = X^*0 = 0$, so $x \in \ker X^*X$

If $x \in \ker X^*X$, $0 = \langle X^*Xx, x \rangle = \langle Xx, Xx \rangle = \|Xx\|^2$, so $x \in \ker X$

■

∴ If X_1, \dots, X_n is linearly independent then X^*X is invertible. d

$$X^*Xa = X^*Y$$

$$\therefore a = (X^*X)^{-1}X^*Y$$

Sesquilinear Forms

November-11-11
10:09 AM

Sesquilinear Form

$V \subset \mathbb{C}$ vector space.

A function $F: V \times V \rightarrow \mathbb{C}$ is a sesquilinear form if it is linear in the first variable and conjugate linear in the second variable.

$$F(a_1v_1 + a_2v_2, w) = a_1F(v_1, w) + a_2F(v_2, w)$$

$$F(v, a_1w_1 + a_2w_2) = \overline{a_1}F(v, w_1) + \overline{a_2}F(v, w_2)$$

Definitions

Say F is **Hermitian** if $F(w, v) = \overline{F(v, w)}$

F is **non-negative** if F is Hermitian and $F(v, v) \geq 0$

F is **positive** if $F \geq 0$ and $F(v, v) > 0$ for $v \neq 0$

Theorem

If $F: V \times V \rightarrow \mathbb{C}$ is sesquilinear form, then there is a unique $T_F \in \mathcal{L}(V)$ such that $F(v, w) = \langle T_F v, w \rangle$ for $v, w \in V$

Moreover, the map $F \mapsto T_F$ is a linear isomorphism from the vector space of sesquilinear forms onto $\mathcal{L}(V)$

Principal Axis Theorem

If $F(x, y)$ is a Hermitian sesquilinear form then \exists an orthonormal basis $\{e_1, \dots, e_n\}$ and $d_i \in \mathbb{R}$ s.t.

$$F\left(\sum_{i=1}^n \alpha_i e_i, \sum_{i=1}^n \beta_i e_i\right) = \sum_{i=1}^n d_i \alpha_i \overline{\beta_i}$$

e_i are principal axes.

Symmetric Quadratic Form

A symmetric quadratic form on \mathbb{R}^n is

$$q(x_1, \dots, x_n) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j, \quad \text{where } a_{ij} = a_{ji} \in \mathbb{R}$$

Any quadratic form in \mathbb{R}^n

$$q(x) = \sum_{i,j} b_{ij} x_i x_j$$

Replace b_{ij} by $a_{ij} = \frac{b_{ij} + b_{ji}}{2}$ now it is symmetric.

Diagonalization

Again, this quadratic form can be diagonalized

$$A = [a_{ij}] = A^*$$

\exists o.n. basis $\{e_1, \dots, e_n\}$ of \mathbb{R}^n consisting of eigenvalues

$$Ae_i = d_i e_i, \quad 1 \leq i \leq n, \quad d_i \in \mathbb{R}$$

$$e_i = \begin{bmatrix} c_{1i} \\ c_{2i} \\ \vdots \\ c_{ni} \end{bmatrix}, \quad U = [e_1 \ e_2 \ \dots \ e_n] = [c_{ij}]_{n \times n}, \quad U \text{ orthogonal}$$

$$U^* A U = \text{diag}(d_1, \dots, d_n) = D$$

$$q(x_1, \dots, x_n) = \left\langle A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \right\rangle = \left\langle U D U^* \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \right\rangle$$

$$= \left\langle D U^* \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, U^* \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \right\rangle$$

$$U^* \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} e_1^* \\ \vdots \\ e_n^* \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} \langle x, e_1 \rangle \\ \vdots \\ \langle x, e_n \rangle \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n c_{i1} x_i \\ \vdots \\ \sum_{i=1}^n c_{in} x_i \end{bmatrix}, \quad c_{ij} \in \mathbb{R}$$

$$q(x_1, \dots, x_n) = \sum_{j=1}^n d_j \left(\sum_{i=1}^n c_{ij} x_i \right)^2$$

Proof

Fix an orthonormal basis $\xi = \{e_1, \dots, e_n\}$ for V . F sesquilinear form.

Need $\langle T e_j, e_i \rangle = F(e_j, e_i)$, $1 \leq i, j \leq n$

Let $|T|_\xi = |t_{ij}|_{n \times n}$ where $t_{ij} = \langle T e_j, e_i \rangle$

T is the unique map on $\mathcal{L}(V)$ such that $\langle T e_j, e_i \rangle = F(e_j, e_i)$, $1 \leq i, j \leq n$

$$\text{Let } v = \sum_{i=1}^n \alpha_i e_i, \quad w = \sum_{i=1}^n \beta_i e_i$$

$$\langle T v, w \rangle = \sum_{i=1}^n \sum_{j=1}^n \alpha_j \beta_i \langle T e_j, e_i \rangle = \sum_{i=1}^n \sum_{j=1}^n \alpha_j \beta_i F(e_j, e_i) = \sum_{i=1}^n \beta_i F\left(\sum_{j=1}^n \alpha_j e_j, e_i\right)$$

$$= F\left(\sum_{j=1}^n \alpha_j e_j, \sum_{i=1}^n \beta_i e_i\right) = F(v, w)$$

Show T_F is uniquely determined by F , $F \mapsto T_F$ is linear.

$$T_F = 0 \Leftrightarrow F = 0 \therefore 1 \text{ to } 1$$

Onto if $T \in \mathcal{L}(V)$, define $F(v, w) = \langle T v, w \rangle$ is sesquilinear

So $F \mapsto T$, onto

Proof of Principal Axis Theorem

$$F(x, y) = \langle Ax, y \rangle = \langle x, A^* y \rangle$$

$$F(x, y) = F(y, x) = \langle Ay, x \rangle = \langle x, Ay \rangle$$

$\therefore A = A^*$ is Hermitian

A is diagonalizable w.r.t orthonormal basis

$$\xi = \{e_1, \dots, e_n\}$$

$$|A|_\xi = \text{diag}(d_1, \dots, d_n), \quad d_i \in \mathbb{R}$$

$$F\left(\sum_{i=1}^n \alpha_i e_i, \sum_{i=1}^n \beta_i e_i\right) = \left\langle A \sum_{i=1}^n \alpha_i e_i, \sum_{i=1}^n \beta_i e_i \right\rangle = \left\langle \sum_{i=1}^n d_i \alpha_i e_i, \sum_{i=1}^n \beta_i e_i \right\rangle = \sum_{i=1}^n d_i \alpha_i \overline{\beta_i}$$

Conics

November-14-11
10:07 AM

Ellipse

Take two points F_1, F_2 , with separation $2c$. Pick $a > c$
Ellipse is $\{P = (x, y) : |P - F_1| + |P - F_2| = 2a\}$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$b^2 = a^2 - c^2, \quad c^2 = a^2 - b^2$$

Hyperbola

Take two points F_1, F_2 with separation $2c$
Hyperbola is $\{P = (x, y) : |PF_1| - |PF_2| = 2a\}$

$$F_1 = (-c, 0), \quad F_2 = (c, 0)$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

$$c^2 = a^2 + b^2$$

Parabola

Focus and line. The set of points equidistant to focus and line.

Formula of an Ellipse

Translate so $F_1 = (-c, 0), F_2 = (c, 0)$

$$\{(x, y) : |(x + c, y)| + |(x - c, y)| = 2a\} = \{(x, y) : \sqrt{(x + c)^2 + y^2} + \sqrt{(x - c)^2 + y^2} = 2a\}$$

$$\sqrt{(x + c)^2 + y^2} = 2a - \sqrt{(x - c)^2 + y^2}$$

$$(x + c)^2 + y^2 = 4a^2 - 4a\sqrt{(x - c)^2 + y^2} + (x - c)^2 + y^2$$

$$4a\sqrt{(x - c)^2 + y^2} = 4a^2 - 4cx$$

$$x^2 - 2cx + c^2 + y^2 = a^2 - 2cx + \frac{c^2 x^2}{a^2}$$

$$\frac{a^2 - c^2}{a^2} x^2 + y^2 = a^2 - c^2$$

$$\frac{x^2}{a^2} + \frac{y^2}{a^2 - c^2} = 1$$

General Conic

$$ax^2 + bxy + cy^2 + dx + ey + f = 0$$

$ax^2 + bxy + cy^2$ is the quadratic form

$$A = \begin{bmatrix} a & \frac{b}{2} \\ \frac{b}{2} & c \end{bmatrix}$$

$$\left\langle A \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle = ax^2 + bxy + cy^2$$

Diagonalize w.r.t. orthonormal basis:

$$\text{Eigenvectors } v_1 = \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix}, \quad v_2 = \begin{pmatrix} \alpha_2 \\ \beta_2 \end{pmatrix}$$

$$Av_1 = \lambda_1 v_1$$

$$Av_2 = \lambda_2 v_2$$

$$U = \begin{pmatrix} \alpha_1 & \alpha_2 \\ \beta_1 & \beta_2 \end{pmatrix} \text{ orthogonal matrix}$$

$$U^* = \begin{pmatrix} \alpha_1 & \beta_1 \\ \alpha_2 & \beta_2 \end{pmatrix}$$

$$U^*AU = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = D, \quad A = UDU^*$$

So

$$ax^2 + bxy + cy^2 = \left\langle A \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle = \left\langle UDU^* \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle = \left\langle DU^* \begin{pmatrix} x \\ y \end{pmatrix}, U^* \begin{pmatrix} x \\ y \end{pmatrix} \right\rangle$$

$$= \left\langle D \begin{pmatrix} \alpha_1 x + \beta_1 y \\ \alpha_2 x + \beta_2 y \end{pmatrix}, \begin{pmatrix} \alpha_1 x + \beta_1 y \\ \alpha_2 x + \beta_2 y \end{pmatrix} \right\rangle = \lambda_1 (\alpha_1 x + \beta_1 y)^2 + \lambda_2 (\alpha_2 x + \beta_2 y)^2$$

$$\lambda_1 \lambda_2 = \det D = \det A$$

$$\lambda_1 \lambda_2 > 0 \text{ ellipse}$$

$$\lambda_1 \lambda_2 = 0 \text{ parabola}$$

$$\lambda_1 \lambda_2 < 0 \text{ hyperbola}$$

$$\text{Write } \begin{pmatrix} d \\ e \end{pmatrix} = d' \begin{pmatrix} \alpha_1 \\ \beta_1 \end{pmatrix} + e' \begin{pmatrix} \alpha_2 \\ \beta_2 \end{pmatrix}$$

$$dx + ey = d'(\alpha_1 x + \beta_1 y) + e'(\alpha_2 x + \beta_2 y)$$

The equation

$$ax^2 + bxy + cy^2 + dx + dy + f = 0$$

becomes

$$\lambda_1 (\alpha_1 x + \beta_1 y)^2 + \lambda_2 (\alpha_2 x + \beta_2 y)^2 + d'(\alpha_1 x + \beta_1 y) + e'(\alpha_2 x + \beta_2 y) + f = 0$$

$$\lambda_1 \left(\alpha_1 x + \beta_1 y + \frac{d'}{2\lambda_1} \right)^2 + \lambda_2 \left(\alpha_2 x + \beta_2 y + \frac{e'}{2\lambda_2} \right)^2 = \left(\frac{d'^2}{2\lambda_1} + \frac{e'^2}{2\lambda_2} - f \right) = f'$$

$$\lambda_1 (\alpha_1 x + \beta_1 y)^2 + \lambda_1 \frac{2d'}{2\lambda_1} (\alpha_1 x + \beta_1 y) + \frac{d'^2}{4\lambda_1} + \lambda_2 (\alpha_2 x + \beta_2 y)^2 + \alpha_2 \frac{2e'}{2\lambda_2} (\alpha_2 x + \beta_2 y) + \frac{e'^2}{4\lambda_2}$$

Translate to eliminate constants

$$\frac{d'}{2\lambda_1}, \frac{e'}{2\lambda_2}$$

Rotate by U to get

$$\lambda_1 x'^2 + \lambda_2 y'^2 = f'$$

$$\frac{x'^2}{\alpha^2} + \frac{y'^2}{\beta^2} = 1$$

Duality

November-16-11
10:00 AM

Dual Space

If V is a vector space over \mathbb{F} then the dual space of V is $V^* = \mathcal{L}(V, \mathbb{F})$. Elements of V^* are called **linear functionals**.

Fix a basis $\beta = \{v_1, \dots, v_i, \dots, v_n\}$ for V

Define $\delta_j \in V^*$ by $\delta_j \left(\sum_{i=1}^n \alpha_i v_i \right) = \alpha_j$

$$\delta_j(v_i) = \begin{cases} 0, & i \neq j \\ 1, & i = j \end{cases} = \delta_{ij}$$

Kronecker Delta

Proposition

$\dim V^* = \dim V$ and $\{\delta_1, \dots, \delta_n\}$ is a basis for V^*
(Called the **dual basis** of $\{v_1, \dots, v_n\}$)

Note

$V^{**} = \mathcal{L}(V^*, \mathbb{F})$

If $v \in V$ define $v \in V^{**}$ by $v(\varphi) := \varphi(v)$, $\varphi \in V^*$

$$v(a\varphi + b\psi) = (a\varphi + b\psi)(v) = a\varphi(v) + b\psi(v) = av(v) + bv(\psi)$$

Thus there is a natural linear map

$$i: V \rightarrow V^{**} \text{ by } i(v) = v$$

This is linear.

Theorem

The natural map $i: V \rightarrow V^{**}$ is an isomorphism.

Remark

This fails dramatically for infinite dimensional vector spaces.

Example

Let $c_{00} = \{\text{sequences } (x_1, x_2, x_3, \dots) \mid x_i = 0 \text{ except for finitely often}\}$
 $e_i = (0, \dots, 0, 1, 0, \dots)$ is a basis for c_{00}

$$\varphi \in c_{00}^*, \quad \varphi(e_i) = \alpha_i, \quad \varphi = \sum \alpha_i \delta_i$$

$$c_{00}^* = S = \{\text{all sequences } (\alpha_1, \alpha_2, \dots)\}$$

$$\dim S = 2^{\aleph_0}$$

S^* is humongous.

Isomorphism

Since we have an isomorphism $i: V \rightarrow V^{**}$ we say $V^{**} = V$ and identify $i(v)$ with v .

V is **reflexive**

Dual Space Basis

Suppose $\varphi \in V^*$

Let $\varphi(v_i) = \beta_i$, $1 \leq i \leq n$

$$\psi = \sum_{j=1}^n \beta_j \delta_j \in V^*$$

$$\psi(v_i) = \sum_{j=1}^n \beta_j \delta_j(v_i) = \beta_i$$

A linear map is determined by what it does to a basis, so $\varphi = \psi$

Proof of Proposition

I expressed every $\varphi \in V^*$ as a linear combination of $\delta_1, \dots, \delta_n$ which are linearly independent.

$$0 = \sum_{i=1}^n a_i \delta_i$$

$$0 = \left(\sum_{i=1}^n a_i f_i \right) (v_j) = a_j$$

$$\Rightarrow a_1 = a_2 = \dots = a_n = 0$$

So $\delta_1, \dots, \delta_n$ are linearly independent $\text{span } V^* \therefore$ is a basis.

$$\dim V^* = n = \dim V \blacksquare$$

Proof of Theorem

Fix a basis v_1, \dots, v_n for V

Construct the dual basis $\delta_1, \dots, \delta_n$ for V^*

Construct the dual dual basis $\varepsilon_1, \dots, \varepsilon_n$ for V^{**}

$$v_i(\delta_j) = \delta_j(v_i) = \delta_{ij}$$

$$\varepsilon_i(\delta_j) = \delta_{ij}$$

So v_i and ε_i agree on a basis $\therefore v_i = \varepsilon_i$

$$\text{So } i \left(\sum_{j=1}^n a_j v_j \right) = \sum_{j=1}^n a_j \varepsilon_j \text{ is 1-1 and onto } \blacksquare$$

Duality on Inner Product Spaces

November-18-11
9:31 AM

Theorem

Let V be an inner product space. Then for each $\varphi \in V^*$ there is a unique $w \in V$ s.t. $\varphi(v) = \langle v, w \rangle \forall v \in V$

The map which sends $\varphi \mapsto w$ is a conjugate linear map of V^* onto V .

Corollary

V inner product space, we convert V^* to an inner product space by

$$\left\langle \sum_{i=1}^n \alpha_i \delta_i, \sum_{i=1}^n \beta_i \delta_i \right\rangle = \sum_{i=1}^n \alpha_i \beta_i$$

If $\varphi \in V^*$ then $\|\varphi\|_{V^*} = \sup_{\|v\| \leq 1, v \in V} |\varphi(v)|$

Notation

$$\left\langle \sum_{i=1}^n \alpha_i e_i, \sum_{j=1}^n \beta_j \delta_j \right\rangle = \sum_{j=1}^n \beta_j \delta_j \left(\sum_{i=1}^n \alpha_i e_i \right)$$

Definition

Let V be a finite dimensional vector space.
If $S \subseteq V$ let $S^\perp = \{\varphi \in V^* : \varphi(s) = 0 \forall s \in S\}$
This is the **annihilator** of S

Proposition

$S \subseteq V$ then

- S^\perp is a subspace of V^*
- $S^{\perp\perp} = \text{span}(S)$
- $\dim S^\perp + \dim S^{\perp\perp} = \dim V$

Relationship between perps.

H inner product space

H^* conjugate linear isometric $v \dots$ to H

$\varphi \in H^*, \exists! y \in H$ s.t. $\varphi(x) = \langle x, y \rangle, \varphi \rightarrow y$ conjugate linear

$M \subset H, M^\perp = H(-)M = \{y : \langle x, y \rangle = 0 \forall x \in M\}$

$M^\perp = M^0 = \{\varphi : \varphi(x) = 0 \forall x \in M\}$

Proof

Let $\xi = \{e_1, \dots, e_n\}$ be an orthonormal basis for V . Let $\delta_1, \dots, \delta_n$ be the dual basis for V^*
If $\varphi \in V^*$, let $\varphi(e_i) = \beta_i, 1 \leq i \leq n$

So $\varphi = \sum_{i=1}^n \beta_i \delta_i$ because $\left(\sum_{j=1}^n \beta_j \delta_j \right)(e_i) = \beta_i$

Want $w \in V$ s.t. $\langle e_i, w \rangle = \beta_i, 1 \leq i \leq n$

$$\left\langle e_i, \sum_{i=1}^n \beta_i e_i \right\rangle = \beta_i$$

So define $T: V^* \rightarrow V$ by

$$T \left(\sum_{i=1}^n \beta_i \delta_i \right) = \sum_{i=1}^n \beta_i e_i$$

$$T\varphi = w = \sum_{i=1}^n \beta_i e_i$$

$$\langle v, w \rangle = \left\langle \sum_{i=1}^n \alpha_i e_i, \sum_{i=1}^n \beta_i e_i \right\rangle = \sum_{i=1}^n \alpha_i \beta_i = \varphi(v)$$

T is not linear-it is conjugate linear. T is 1-1 and onto ■

Proof of Corollary

Clearly this makes V^* an inner product space

Let $\varphi = \sum_{j=1}^n \beta_j \delta_j \in V^*$

$$\|\varphi\|_{V^*} = \sqrt{\sum_{j=1}^n |\beta_j|^2}$$

If $v \in V, v = \sum_{i=1}^n \alpha_i e_i$

$$|\varphi(v)| = \left| \left\langle \sum_{i=1}^n \alpha_i e_i, \sum_{j=1}^n \beta_j \delta_j \right\rangle \right| = \left| \sum_{i=1}^n \alpha_i \beta_i \right| \leq \sqrt{\sum_{i=1}^n |\alpha_i|^2} \sqrt{\sum_{i=1}^n |\beta_i|^2} = \|v\|_V \|\varphi\|_{V^*}$$

So get:

$$\sup_{\substack{v \in V \\ \|v\| \leq 1}} |\varphi(v)| \leq \sup_{\|v\| \leq 1} \|v\| \|\varphi\|_{V^*} = \|\varphi\|_{V^*}$$

To get equality, take

$$v = \frac{\sum_{i=1}^n \beta_i e_i}{\sqrt{\sum_{i=1}^n |\beta_i|^2}}, \quad \varphi(v) = \frac{\sum_{i=1}^n \beta_i \beta_i}{\sqrt{\sum_{i=1}^n |\beta_i|^2}} = \sqrt{\sum_{i=1}^n |\beta_i|^2} = \|\varphi\|_{V^*}$$

Proof of Proposition

1.

$0 \in S^\perp$

If $\varphi, \psi \in S^\perp, s \in S, \alpha, \beta \in F$

$$(\alpha\varphi + \beta\psi)(s) = \alpha\varphi(s) + \beta\psi(s) = 0$$

2.

$S^{\perp\perp}$ is a subspace of $V^{**} = V$ which contains S because $s \in S, \varphi \in S^\perp$

$$i(s) \sim s(\varphi) = \varphi(s) = 0$$

So $S^{\perp\perp} \supseteq \text{span}(S)$

Suppose $v \notin \text{span}(S)$

Take a basis for S , say v_1, \dots, v_k ($\dim S = k$) and extend to a basis $v_1, \dots, v_k, v, v_{k+2}, \dots, v_n$
Note, used v in the basis.

Let $\delta_1, \dots, \delta_n$ be the dual basis of V^*

$$\delta_{k+1}(v_i) = 0, \quad 1 \leq i \leq k \Rightarrow \delta_{k+1} \in S^\perp$$

$$\delta_{k+1}(v) = 1 \neq 0, \quad \therefore v \notin S^{\perp\perp}$$

So $S^{\perp\perp} \subseteq \text{span } S \therefore$ equal

3.

Claim:

$$S^\perp = \text{span}\{\delta_{k+1}, \dots, \delta_n\}, \quad j \geq k+1: \delta_j(v_i) = 0 \text{ for } 1 \leq i \leq k \Rightarrow \delta_j \in S^\perp$$

$$\text{So } \text{span}\{\delta_{k+1}, \dots, \delta_n\} \subseteq S^\perp$$

$$\text{Let } \varphi = \sum_{j=1}^n \beta_j \delta_j \in S^\perp$$

$$0 = \varphi(v_i) = \beta_i \Rightarrow \varphi \in \text{span}\{\delta_{k+1}, \dots, \delta_n\}, \quad i \leq k$$

$$\dim S = k, \dim S^\perp = n - k, n + n - k = n$$

Transpose

November-21-11
9:39 AM

Transpose Map

If $T \in \mathcal{L}(V, W)$ define the **transpose** of T to be the map $T^t \in \mathcal{L}(W^*, V^*)$ by
 $(T^t \varphi)(v) = \varphi(Tv)$
 $T^t \varphi = \varphi \circ T \in \mathcal{L}(V, \mathbb{F})$

Claim

T^t is a linear map

Claim

"transpose" is a linear map
 $(\alpha S + \beta T)^t = \alpha S^t + \beta T^t$

Theorem

$T \in \mathcal{L}(V, W), T^t \in \mathcal{L}(W^*, V^*)$

1. If $\beta = \{v_1, \dots, v_m\}$ basis for $V, \beta' = \{\delta_1, \dots, \delta_m\}$ for V^*
 $\mathcal{C} = \{w_1, \dots, w_n\}$ basis for $W, \mathcal{C}' = \{\varepsilon_1, \dots, \varepsilon_n\}$ for W^*

If $|T|_{\beta}^{\mathcal{C}} = |t_{ij}|_{m \times n}$, then $|T^t|_{\mathcal{C}'}^{\beta'} = |t_{ji}|_{n \times m}$

2. $T \mapsto T^t$ is a linear isomorphism of $\mathcal{L}(V, W)$ onto $\mathcal{L}(W^*, V^*)$
3. $\text{ran } T^t = (\ker T)^\perp$ and $\ker T^t = (\text{ran } T)^\perp$
4. $\text{rank } T^t = \text{rank } T$

Proof of Claim

$$T^t(\alpha\varphi + \beta\psi)(v) = (\alpha\varphi + \beta\psi)(Tv) = \alpha\varphi(Tv) + \beta\psi(Tv) = (\alpha T^t\varphi + \beta T^t\psi)(v)$$

Proof of Claim

$\varphi \in W^*, v \in V$

$$\begin{aligned} (\alpha S + \beta T)^t(\varphi)(v) &= \psi((\alpha S + \beta T)(v)) = \psi(\alpha S v + \beta T v) = \alpha\varphi(Sv) + \beta\psi(Tv) \\ &= \alpha(S^t\varphi)(v) + \beta(T^t\psi)(v) = (\alpha S^t + \beta T^t)(\varphi)(\psi) \end{aligned}$$

Proof of Theorem

1

$$(|T^t|_{\mathcal{C}'}^{\beta'})_{ij} = a_{ij} \text{ where } (T^t \varepsilon_j)(v_i) = \left(\sum_{k=1}^m a_{kj} \delta_k \right)(v_i) = a_{ij}$$

$$(T^t \varepsilon_j)(v_i) = \varepsilon_j(Tv_i) = \varepsilon_j \left(\sum_{k=1}^n t_{ki} w_k \right) = t_{ji}$$

$$\therefore |T^t|_{\mathcal{C}'}^{\beta'} = |t_{ji}| = (|T|_{\beta}^{\mathcal{C}})^t$$

The matrix of the transpose is the transpose of the matrix.

2

$E_{ij} = |b_{kl}|$ where $b = 1$ if $k = i, j = l$ and $b = 0$ otherwise

E_{ij} is a basis for $\mathcal{L}(V, W)$. $E_i = w_i \delta_j$

$E_{ij}^t = E_{ji}$ sends a basis for $\mathcal{L}(W^*, V^*)$ to a basis for $\mathcal{L}(V, W)$. \therefore 1-1 and onto.

3

$$\varphi \in \ker T^t \in W^* \Leftrightarrow 0 = T^t \varphi \in V^*$$

$$\Leftrightarrow 0 = T^t \varphi(v) \forall v \in V = \varphi(Tv) \Leftrightarrow \varphi \in (\text{ran } T)^\perp$$

$$\therefore v \in \ker T = \ker T^{tt} = (\text{ran } T^t)^\perp$$

$$\therefore (\ker T)^\perp = (\text{ran } T^t)^{\perp\perp} = \text{ran } T^t$$

4

$$\text{rank } T^t = \dim \text{ran } T^t = \dim(\ker T)^\perp = \dim V - \dim \ker T = \text{rank } T$$

Since

$M \subseteq V$, basis for M , extend for V . Dual space $\delta_1, \dots, \delta_n$

$$M^\perp = \text{sp}(\delta_{k+1}, \dots, \delta_n) \Rightarrow \dim M^\perp = n - \dim M$$

Quotient Spaces

November-21-11
10:02 AM

Quotient Space

V vector space, M subspace of V

Say $v_1 \equiv v_2$ iff $v_1 - v_2 \in M$

$\frac{V}{M}$ is the set of equivalence classes $v = v + M$

Make $\frac{V}{M}$ into a vector space by

$$tv = t(v + M) = tv + M$$

$$v + w = (v + M) + (w + M)$$

$\frac{V}{M}$ is called the **quotient space** of V by M .

The map $\Pi: V \rightarrow \frac{V}{M}$ by $\Pi(v) = v + M$ is called the **quotient map**.

Proposition

$\Pi \in \mathcal{L}\left(V, \frac{V}{M}\right)$ is surjective and $\ker \Pi = M$.

Theorem

If M is a subspace of V then $M^* \cong \frac{V^*}{M^\perp}$ (isomorphic to) and $\left(\frac{V}{M}\right)^* \cong M^\perp$

Relations

$$V^* \rightarrow_R M^*$$

$$V^* \rightarrow_q \left(\frac{V^*}{M^\perp}\right) \rightarrow_R M^*$$

$R(\varphi + M^\perp) = R\varphi$ well defined because of

$$\varphi_1, \varphi_2 \in \varphi, \quad \varphi_1 - \varphi_2 = \psi \in M^\perp$$

$$\varphi_2|_M = \varphi_1|_M + \psi|_M = \varphi_1|_M$$

$$\therefore R \mathbf{1} - \mathbf{1}$$

Proof of Well Definition

If $v_1 \equiv v_2$ then $v_1 - v_2 = m \in M$

$$\therefore tv_1 - tv_2 = tm \in M$$

$$\therefore tv_1 \equiv tv_2$$

So tv is independent of choice of representative.

If $v_1 \equiv v_2, w_1 \equiv w_2$ say $w_1 - w_2 = n \in M$

$$v_2 + w_2 = v_1 + m + w_1 + n = (v_1 + w_1) + (m + n), \quad (m + n) \in M$$

$$\therefore v_2 + w_2 \equiv v_1 + w_1$$

So $v + w = (v + M) + (w + M)$ is well defined.

Proof of Proposition

Π is linear, surjective by definition.

$$\ker \Pi = \{v : v \neq 0\} = \{v : v \in M\} = M$$

Proof of Theorem

Let $\Pi: V \rightarrow \frac{V}{M}$ be the quotient map, then $\Pi^t: \left(\frac{V}{M}\right)^* \rightarrow V^*$

$$\ker \Pi^t = (\text{ran } \Pi)^\perp = \{0\}$$

$\therefore \Pi^t$ is injective

$$\text{ran } \Pi^t = (\ker \Pi)^\perp = M^\perp$$

So Π^t maps $\left(\frac{V}{M}\right)^*$ 1-1 and onto M^\perp . \therefore Linear isomorphism

The connection is given by:

Take $\varphi \in \left(\frac{V}{M}\right)^*$, $\Pi^t \varphi = \varphi \circ \Pi \in V^*$

$$(\varphi \circ \Pi)(m) = \varphi(0) = 0 \quad \forall m \in M$$

$$\text{So } \left(\frac{V^*}{M^\perp}\right)^* \cong M^{\perp\perp} = M$$

$$\therefore \frac{V^*}{M^\perp} = \left(\frac{V^*}{M^\perp}\right)^{**} \cong M^*$$

If $\varphi \in V^*$ the restriction map $R\varphi = \varphi|_M$ is a linear map of V^* onto M^*

$$\ker R = \{\varphi : \varphi|_M = 0\} = M^\perp$$

Convex Sets

November-23-11
9:33 AM

Convexity

A subset C of \mathbb{R} or \mathbb{C} is convex if $\forall c_1, c_2 \in C \forall 0 \leq t \leq 1, (1-t)c_1 + tc_2 \in C$

Hyperplane

H is a hyperplane if $\exists \varphi \in V^*, \varphi \neq 0$ such that $H = \{v : \text{Re } \varphi(v) = a\}$

A **half space** is a set of form $H^+ = \{v : \text{Re } \varphi(v) \geq a\}$

Note: H and H^+ are convex.

Proposition

- The intersection of convex sets is convex.
- If $S \subseteq V, \text{conv}(S)$ is the smallest convex set containing S

$$\left\{ \sum_{i=1}^r t_i s_i : r \in \mathbb{N}, s_i \in S, t_i \geq 0, \sum_{i=1}^r t_i = 1 \right\}$$

Theorem (Carathéodory)

If V is a real vector space of dimension $n, S \subseteq V$ then every point in $\text{conv}(S)$ is a convex combination of $n + 1$ points in S

Remark

- If V is a complex vector space of dimensions n , then it is a real vector space of dimension $2n$. So $2n + 1$ points are needed.
- In \mathbb{R}^n take $S = \{0, e_1, e_2, \dots, e_n\}$ the point

$$\frac{1}{n+1}0 + \sum_{i=1}^n \frac{1}{n+1} e_i \in S \text{ requires } n+1 \text{ points.}$$

Corollary

If $S \subseteq V$ is compact, $\dim V = n < \infty$ then $\text{conv}(S)$ is compact.

Remark: From Calculus

A set $C \subseteq \mathbb{R}^n$ is sequentially compact if every sequence $\{c_n : n \geq 1\}$ of points in C has a convergent subsequence $\lim_{k \rightarrow \infty} c_{n_k} = c, c \in C$

Heine-Bore Theorem

$C \subseteq \mathbb{R}^n$ is compact $\Leftrightarrow C$ is closed and bounded

Extreme Value theorem

If C compact, $f: C \rightarrow \mathbb{R}$ is continuous then f attains its maximum and minimum values.

Proof of Proposition

1. $C_i, i \in I$ are convex sets in V

$$C = \bigcap_{i \in I} C_i, \quad c_1, c_2 \in C, \quad 0 \leq t \leq 1$$

$$c_1, c_2 \in C_i \Rightarrow (1-t)c_1 + tc_2 \in C_i \quad \forall i \\ \therefore c_1, c_2 \in C$$

2.

$\text{conv}(S)$ exists - it is the intersection of all convex sets containing S

Claim

$$\sum_{i=1}^r t_i s_i \in \text{conv}(S), \quad s_i \in \text{conv}(S)$$

Suppose

$$v_k = \sum_{i=1}^k \left(\frac{t_i}{\sum_{j=1}^k t_j} \right) s_i \in \text{conv}(S)$$

True for $k = 1$

If true for k then

$$v_{k+1} = \left(\frac{\sum_{i=1}^k t_i}{\sum_{i=1}^{k+1} t_i} \right) v_k + \left(\frac{t_{k+1}}{\sum_{i=1}^{k+1} t_i} \right) s_{k+1} \in \text{conv}(S)$$

Convex combinations of 2 points of $\text{conv}(S)$

$$\text{By induction } v_r = \sum_{i=1}^r t_i s_i \in \text{conv}(S)$$

$$\text{If } \sum_{i=1}^r t_i s_i, \sum_{j=1}^{r'} t'_j s'_j, \quad t_i t'_j \geq 0, \quad \sum_{i=1}^r t_i = 1 = \sum_{j=1}^{r'} t'_j$$

$$\text{For } 0 \leq u \leq 1, \quad (1-u) \sum_{i=1}^r t_i s_i + u \sum_{j=1}^{r'} t'_j s'_j = 1$$

So the convex combination of two convex combination of two convex combinations of points in S is a convex combinations of points in S

$$\therefore \left\{ \sum_{i=1}^r t_i s_i : r \geq 1, t_i \geq 0, \sum_{i=1}^r t_i = 1, s_i \in S \right\} \text{ is the smallest convex set } \supseteq S$$

Proof of Theorem

$$\text{Take a point } v \in \text{conv}(S). \text{ Can write } v = \sum_{i=1}^r t_i s_i, \quad s_i \in S, t_i \geq 0, \sum_{i=1}^r t_i = 1$$

Claim

If $r \geq n + 2$, we can find another convex combination equal to v using fewer of the $\{s_i\}$'s.

wlog, $t_i > 0$ (if $t_{i_0} = 0$ throw s_{i_0} out of the set)

The set $\{s_1 - s_r, s_2 - s_r, \dots, s_{r-1} - s_r\}$ has $r - 1 \geq n + 1$ elements \Rightarrow linearly dependent.

$\therefore \exists a_i \in \mathbb{R}$, not all zero such that

$$0 = \sum_{i=1}^{r-1} a_i (s_i - s_r) = \sum_{i=1}^{r-1} a_i s_i + a_r s_r \text{ where } a_r = - \sum_{i=1}^{r-1} a_i$$

$$\text{So } \sum_{i=1}^{r-1} a_i = 0 \text{ and } 0 = \sum_{i=1}^{r-1} a_i s_i$$

$$\text{Let } J = \{i : a_i < 0\}, \quad \text{Let } \delta = \min_{i \in J} \left\{ \frac{t_i}{|a_i|} \right\} = \frac{t_{i_0}}{|a_{i_0}|}, \text{ for some } i_0 \in J$$

$$v = \sum_{i=1}^r t_i s_i + \delta \sum_{i=1}^{r-1} a_i s_i = \sum_{i=1}^r (t_i + \delta a_i) s_i$$

$$i \in J: t_i + \delta a_i \geq t_i + \frac{t_i}{|a_i|} a_i = t_i - t_i = 0$$

$$i \notin J: t_i + \delta a_i \geq t_i \geq 0$$

$$\sum_{i=1}^r (t_i + \delta a_i) = \sum_{i=1}^r t_i + \delta \sum_{i=1}^{r-1} a_i = 1 + \delta 0 = 1$$

This new combination does not need s_{i_0} because the coefficient is 0. So we have reduced r to $r - 1$.

Proof of Corollary

Every $v \in \text{conv}(S)$ is the convex combination of $n + 1$ points in S

$$S^{n+1} = \{(s_1, s_2, \dots, s_{n+1}) : s_i \in S\}, \quad \Delta_{n+1} = \left\{ (t_1, \dots, t_{n+1}) : t_i \geq 0, \sum_{i=1}^{n+1} t_i = 1 \right\}$$

$$S^{n+1} \times \Delta_{n+1} \subseteq V^{n+1} \times \mathbb{R}^{n+1}, S^{n+1} \text{ compact}$$

$$f: S^{n+1} \times \Delta_{n+1} \rightarrow V_{n+1}, \quad f((s_1, s_2, \dots, s_{n+1}, t_1, t_2, \dots, t_{n+1})) = \sum_{i=1}^{n+1} t_i s_i$$

f is continuous

The continuous image of a compact set is compact (by EVT)

$$\text{conv}(S) = f(S^{n+1} \times \Delta_{n+1}) \text{ is compact}$$

Convexity

November-25-11
9:32 AM

Theorem

Let V be a finite dimensional inner product space ($\mathbb{F} = \mathbb{R}$ or \mathbb{C}).
 $C \subseteq V$ closed convex set, $p \in V, p \notin C$
 Then there is a unique point $c_0 \in C$ closest to p .
 Let $\varphi(x) = \langle x, p - c_0 \rangle$
 Then $\operatorname{Re} \varphi(p) > \operatorname{Re} \varphi(c_0) \geq \operatorname{Re} \varphi(c) \forall c \in C$
 i.e. $C \subseteq \{x: \operatorname{Re} \varphi(x) \leq \operatorname{Re} \varphi(c_0)\}$, this is called a **half space**

Separation Theorem

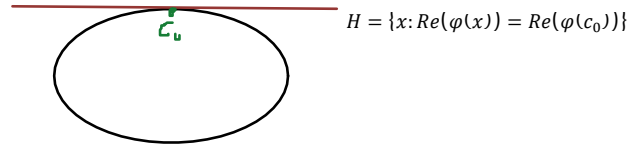
V finite dimensional vector space over \mathbb{R} or \mathbb{C}
 $C \subseteq V$ closed convex set, $p \in V, p \notin C$

Then $\exists \varphi \in V^*$ such that
 $\operatorname{Re} \varphi(p) > \sup_{c \in C} \operatorname{Re} \varphi(c)$

Corollary

If C is a closed subset of V then C is the intersection of all closed half spaces which contain it.

$\cdot p$



Proof

Define $f: C \rightarrow \mathbb{R}$ by $f(c) = \|p - c\|^2$
 f is continuous, $f(c) > 0$

Pick $c_1 \in C$ the closest point lies in $C \cap B_{\|p - c_1\|}(p)$, which is closed and bounded.
 So f achieves its minimum value by the extreme value theorem.
 So there is at least one closest point c_0

Uniqueness

Suppose $c_0, c_1 \in C$ are both closest

$$\|p - c_0\| = \|p - c_1\| = \delta \leq \|p - c\| \forall c \in C$$

But then $\frac{c_0 + c_1}{2} \in C$ and if $c_0 \neq c_1$ then $\|p - \frac{c_0 + c_1}{2}\| < \delta$, by geometry

Alternatively

$$\begin{aligned} \left\|p - \frac{c_0 + c_1}{2}\right\|^2 &= \left\langle \frac{p - c_0}{2} + \frac{p - c_1}{2}, \frac{p - c_0}{2} + \frac{p - c_1}{2} \right\rangle \\ &= \left\| \frac{p - c_0}{2} \right\|^2 + 2 \operatorname{Re} \left\langle \frac{p - c_1}{2}, \frac{p - c_0}{2} \right\rangle + \left\| \frac{p - c_1}{2} \right\|^2 \leq \frac{1}{4} \delta^2 + 2 \left\| \frac{p - c_1}{2} \right\| \left\| \frac{p - c_0}{2} \right\| + \frac{1}{4} \delta^2 = \delta^2 \end{aligned}$$

Inequality is Cauchy-Schwartz and must hold with equality

$$\therefore \frac{p - c_1}{2} = t \frac{p - c_0}{2}, t > 0, \text{ but } t = 1 \therefore c_1 = c_0$$

So the closest point is unique.

$$\varphi(x) = \langle x, p - c_0 \rangle$$

$$\varphi(p - c_0) = \|p - c_0\|^2 > 0$$

$$\varphi(p - c_0) = \varphi(p) - \varphi(c_0)$$

$$\therefore \operatorname{Re} \varphi(p) = \operatorname{Re} \varphi(c_0) + \|p - c_0\|^2 > \operatorname{Re} \varphi(c_0)$$

Claim

$$\operatorname{Re} \varphi(c) \leq \operatorname{Re} \varphi(c_0) \forall c \in C$$

If not, $\exists c_2 \in C$ s.t.

$$\operatorname{Re} \varphi(c_2) = \operatorname{Re} \varphi(c_0) + \varepsilon, \quad \varepsilon > 0$$

$$\begin{aligned} \operatorname{Re} \varphi(p - c_2) &= \operatorname{Re} \varphi(p) - \operatorname{Re} \varphi(c_2) = \operatorname{Re} \varphi(p) - \operatorname{Re} \varphi(c_0) + \varepsilon = \operatorname{Re} \varphi(p - c_0) - \varepsilon \\ &= \|p - c_0\|^2 - \varepsilon \end{aligned}$$

$$\begin{aligned} \text{Look at } f(t) &= \|p - ((1-t)c_0 + tc_2)\|^2 \\ &= \langle (1-t)(p - c_0) + t(p - c_2), (1-t)(p - c_0) + t(p - c_2) \rangle \\ &= (1-t)^2 \|p - c_0\|^2 + 2 \operatorname{Re} (t(1-t) \langle p - c_2, p - c_0 \rangle) + t^2 \|p - c_2\|^2 \\ &= (1-2t+t^2) \|p - c_0\|^2 + 2(t-t^2) \operatorname{Re} \varphi(p - c_2) + t^2 \|p - c_2\|^2 \\ &= (1-t)^2 \|p - c_0\|^2 - 2(t-t^2)\varepsilon + t^2 \|p - c_2\|^2 \end{aligned}$$

$$f'(t) = -2t \|p - c_0\|^2 - (2-4t)\varepsilon + 2t \|p - c_2\|^2$$

$$f'(0) = -2\varepsilon, \text{ decreasing}$$

So for $t > 0$, small, $f(t) < f(0)$ so c_0 is not the smallest point. ■

Proof of Separation Theorem

Pick a basis $\{v_1, \dots, v_n\}$ for V . Impose an inner product:

$$\left\langle \sum_{i=1}^n \alpha_i v_i, \sum_{i=1}^n \beta_i v_i \right\rangle = \sum_{i=1}^n \alpha_i \beta_i$$

Use previous Theorem to get $\varphi \in V^*$ such that

$$\operatorname{Re} \varphi(p) > \operatorname{Re} \varphi(c_0) = \sup_{c \in C} \operatorname{Re} \varphi(c)$$

Proof of Corollary

Let $\{A_\alpha\}$ be the set of all closed half spaces such that $H \supseteq C$

Clearly $C \subseteq \bigcap H_\alpha$

But if $p \notin C, \exists \varphi \in V^*$ s.t.

$$\operatorname{Re} \varphi(p) > \sup_{c \in C} \operatorname{Re} \varphi(c) = C$$

$H = \{x: \operatorname{Re} \varphi \leq L\}$ half space

$$C \subseteq H, p \notin H, \therefore p \notin \bigcap H_\alpha \quad \blacksquare$$

Normed Vector Spaces

November-28-11

9:30 AM

$F = \mathbb{R}, \mathbb{C}$

Norm

A norm on a vector space V over \mathbb{F} is a function $\|\cdot\|: V \rightarrow [0, \infty)$ such that

- 1) $\|v\| \geq 0$, $\|v\| = 0 \iff v = 0$ (positive definite)
- 2) $\|tv\| = |t|\|v\| \forall t \in \mathbb{F}$, (homogeneous)
- 3) $\|v + w\| \leq \|v\| + \|w\|$, (triangle inequality)

Unit Ball

B_v or $B_1(0) = \{v: \|v\| \leq 1\}$

Proposition

$(V, \|\cdot\|)$ normed vector space then B_v is convex, $0 \in B_v$, **balanced** (if $v \in B_v$, $tv \in B_v \forall |t| = 1$). Hence $|t| \leq 1$ by convexity.

Example

If V, W are normed vector spaces, then $\mathcal{L}(V, W)$ can be normed by

$$\|T\| = \sup_{\|v\|_V \leq 1} \|Tv\|_W$$

- 1) $\|Tv\| \geq 0 \Rightarrow \|T\| \geq 0$
 $\|T\| = 0 \Rightarrow \|Tv\| = 0 \forall v \Rightarrow Tv = 0 \forall v \Rightarrow T = 0$

- 2) $\|tT\| = \sup_{\|v\|_V \leq 1} \|tTv\|_W = \sup_{\|v\|_V \leq 1} |t| \|Tv\|_W = |t| \|T\|$

- 3) $S, T \in \mathcal{L}(V, W)$
 $\|S + T\| = \sup_{\|v\|_V \leq 1} \|(S + T)v\|_W \leq \sup_{\|v\|_V \leq 1} \|Sv\|_W + \|Tv\|_W$
 $\leq \sup_{\|v\|_V \leq 1} \|Sv\|_W + \sup_{\|v\|_V \leq 1} \|Tv\|_W = \|S\| + \|T\|$

Special Cases

- 1) $W = \mathbb{F}$, $\mathcal{L}(V, \mathbb{F}) = V^*$ **dual norm** on V^*
 $\|\varphi\| = \sup_{\|v\| \leq 1} |\varphi(v)|$
- 2) $W = V$, $\mathcal{L}(V, V)$ **algebra**
 $\|ST\| \leq \sup_{\|v\| \leq 1} \|S(Tv)\| \leq \sup_{\|w\| \leq \|T\|} \|Sw\| = \|T\| \sup_{\|w\| \leq 1} \|Sw\|$
 $= \|T\| \cdot \|S\|$
- 3) $T \in \mathcal{L}(V, W)$, $v \in V$
 $\|Tv\| = \left\| T \left(\frac{v}{\|v\|} \right) \right\| = \|v\| \left\| T \left(\frac{v}{\|v\|} \right) \right\| \leq \|T\| \cdot \|v\|$

Lemma

V finite dimensional normal space.

Let $T: (F^n, \|\cdot\|_2) \rightarrow V$ be a linear isomorphism

Then T is uniformly continuous

Theorem

V finite dimensional normal vector space

$T: F^n \rightarrow V$ linear isomorphism

Then \exists constants $0 < c < C < \infty$ such that

$$c\|v\| \leq \|Tv\| \leq C\|v\| \forall v \in V$$

Equivalent

Say two norms $\|\cdot\|_a$ and $\|\cdot\|_b$ are **equivalent** if $\exists 0 < c_1, c_2$ such that

$$\frac{c_1}{c_2} \|v\|_a \leq \|v\|_b \leq c_2 \|v\|_a$$

Corollary

If V is a finite dimensional normed vector space then any two norms on V are equivalent.

Convergence

Say a sequence $v_n \in V$ converges to v_0 if $\lim_{n \rightarrow \infty} \|v_n - v_0\| = 0$

Corollary says that convergence in a finite dimensional normal space is independent of choice of the norm.

So $(V, \|\cdot\|_a)$ and $(V, \|\cdot\|_b)$ have the same closed sets, hence the same open sets.

B_v is a closed balanced convex set containing 0 on the interior.

If $\|v_n\| \leq 1$, $v_n \rightarrow v_0 \Rightarrow \|v_0\| \leq 1$

($\epsilon > 0, \exists n \|v_n - v_0\| < \epsilon \therefore \|v_0\| \leq \|v_n\| + \|v_0 - v_n\| \leq 1 + \epsilon$ Let $\epsilon \rightarrow 0$ $\|\cdot\|$ is continuous in the norm

Examples

1

$$\|v\| = \sqrt{\langle v, v \rangle}$$

$V = \mathbb{C}^n$ usual inner product

B_V is unit ball in Euclidean norm

2

$V = \mathbb{C}^n$, $v = (a_1, \dots, a_n)$

$$\|v\|_\infty = \max\{|a_i|, i \leq n\}$$

Satisfies 1, 2

$$\|v + w\| = \|a_1 + b_1, \dots, a_n + b_n\|_\infty = \max\{|a_i + b_i|\} \leq \max\{|a_i| + |b_i|\} \leq \max\{|a_i|\} + \max\{|b_i|\} = \|v\|_\infty + \|w\|_\infty$$

$$B_{i_\infty(\mathbb{R})} = [-1, 1]^n = \{(a_i): |a_i| \leq 1\}$$

$$B_{i_\infty(\mathbb{C})} = \mathbb{D}^n = \{(a_i): |a_i| \leq 1\}$$

3

l_n^1 , $V = \mathbb{C}^n$ or \mathbb{R}^n

$$\|v\|_1 = \sum_{i=1}^n |a_i|$$

Satisfies 1, 2

$$\|v + w\|_1 = \sum_{i=1}^n |a_i + b_i| \leq \sum_{i=1}^n (|a_i| + |b_i|) = \|v\|_1 + \|w\|_1$$

4

l_n^p , $1 < p < \infty, V = \mathbb{F}^n$

$$\|v\|_p = \left(\sum_{i=1}^n |a_i|^p \right)^{\frac{1}{p}}$$

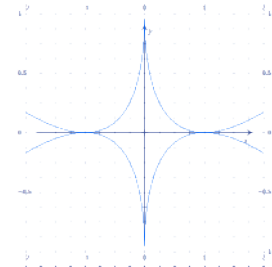
Satisfies 1, 2

Satisfies 3 but hard to prove

Ex: $p = \frac{1}{2}$

$$\|v\|_{\frac{1}{2}} = (\sqrt{|a_1|} + \sqrt{|a_2|})^2$$

Does not satisfy 3



Proof of Proposition

Balanced follows from 2

Convex follows from 3, 2

$$\|v\| \leq 1, \|w\| \leq 1, 0 \leq t \leq 1$$

$$\|tv + (1-t)w\| \leq \|tv\| + \|(1-t)w\| \leq |t| \times 1 + |1-t| \times 1 = 1$$

Proof of Lemma

Let e_1, \dots, e_n be the standard basis of F^n .

Let $v_i = Te_i$ this is a basis for V

$$w = (a_1, \dots, a_n) = \sum_{i=1}^n a_i e_i$$

$$\|Tw\| = \left\| \sum_{i=1}^n a_i v_i \right\| \leq \sum_{i=1}^n \|a_i v_i\| = \sum_{i=1}^n |a_i| \|v_i\| \leq \sqrt{\sum_{i=1}^n |a_i|^2} \sqrt{\sum_{i=1}^n \|v_i\|^2}$$

$$\|T\| = \sup_{\|w\| \leq 1} \|Tw\| \leq \sqrt{\sum_{i=1}^n \|v_i\|^2} = L$$

$$\therefore \|Tw_1 - Tw_2\| = \|T(w_1 - w_2)\| \leq \|T\| \|w_1 - w_2\| \leq L \|w_1 - w_2\|$$

This is a Lipschitz function.

If $\epsilon > 0$, let $\delta = \frac{\epsilon}{L}$, $\|w_1 - w_2\| < \delta \Rightarrow \|Tw_1 - Tw_2\| < L\delta = \epsilon$

$\therefore T$ is uniformly continuous ■

Proof of Theorem

Lemma shows $C = \|T\| < \infty$

Let $S = \{w \in F^n: \|w\|_2 = 1\}$, unit space

T is 1-1, $sTs \neq 0 \forall x \in S$

T is continuous, S is compact so by Extreme Value Theorem the minimum values is attained:

$$\inf_{w \in S} \|T \cdot w\| = \|Tw_0\| = c \neq 0$$

If $\|v_n\| \leq 1, v_n \rightarrow v_0 \Rightarrow \|v_0\| \leq 1$
 $(\epsilon > 0, \exists n, \forall m > n, \|v_m - v_n\| < \epsilon \cdot \|v_0\| \leq \|v_m\| + \|v_0 - v_n\| \leq 1 + \epsilon$ Let $\epsilon \rightarrow 0$
 $\|\cdot\|$ is continuous in the norm

$\{v: \|v\| \geq 1\}$ is closed so $\{v: \|v\| < 1\} = B_1(0)$ is open.

T is linear, S is convex

T is continuous, S is compact so by Extreme Value Theorem the minimum values is attained:

$$\inf_{w \in S} \|T \cdot w\| = \|Tw_0\| = c \neq 0$$

By Homogeneity $c\|w\|_2 \leq \|Tw\| \leq C\|w\|_2$

Proof of Corollary

Let $T: \mathbb{F}^n \rightarrow V$ isometric

Use Theorem, get $0 < c_1, C_1, c_2, C_2$

$$c_1\|w\|_2 \leq \|Tw\|_a \leq C_1\|w\|_2$$

$$c_2\|w\|_2 \leq \|Tw\|_b \leq C_2\|w\|_2$$

$$\frac{c_2}{C_1} \|Tw\|_a \leq c_2\|w\|_2 \leq \|Tw\|_b \leq C_2\|w\|_2 \leq \frac{C_2}{c_1} \|Tw\|_a \quad \blacksquare$$

Norms

November-30-11
9:30 AM

V normed vector space

$V^* = \mathcal{L}(V, \mathbb{F})$ has the dual norm

$$\|\varphi\| = \sup_{\|v\| \leq 1} |\varphi(v)|$$

V^{**} has a norm, $i: V \rightarrow V^*$, $v(\varphi) = i(v)(\varphi) = \varphi(v)$

$$\|v\|_{V^{**}} = \sup_{\|\varphi\| \leq 1} |\varphi(v)| = \sup_{\|\varphi\| \leq 1} |\varphi(v)| \leq \sup_{\|\varphi\| \leq 1} \|\varphi\|_{V^*} \|v\|_V = \|v\|_V$$

Theorem

The natural injection $i: V \rightarrow V^{**}$ is isometric.

i.e. $\|i(v)\|_{V^{**}} = \|v\|_V$

Corollary

If $v \in V$, then $\exists \varphi \in V^*$ with $\|\varphi\| \leq 1$ and $\varphi(v) = \|v\|$

Quotient Norm

If M is a subspace of a finite dimensional subspace V , put the

quotient norm on $\frac{V}{M}$ by

$$v = |v|_M = v + M = \{w: w \equiv v \text{ mod } M\} = \{w: w - v \in M\}$$

$$\|v\|_V = \inf_{m \in M} \|v + m\| = \inf_{m \in M} \|w\|: w \in |v| = \text{dist}(v, M)$$

Proposition

The quotient norm is a norm.

Question

If $M \subseteq V$ showed $M^* \cong \frac{V^*}{M^\perp}$, $M^\perp = \{\varphi \in V^*: \varphi|_M = 0\}$, $(\frac{V}{M})^* \cong M^\perp$

These are linear isomorphisms.

Are they isometric when V is normed?

Lemma

If $T \in \mathcal{L}(V, W)$ is an isometric isomorphism, then $T^t \in \mathcal{L}(W^*, V^*)$ is also in isometric isomorphism.

Theorem

V finite dimensional normed space, $M \subseteq V$ subspace. Then the linear isomorphisms

$$M^* \cong \left(\frac{V^*}{M^\perp}\right) \text{ and } \left(\frac{V}{M}\right)^* \cong M^\perp \text{ are isometric.}$$

Corollary

If $M \subseteq V$, $f \in M^*$ then $\exists \varphi \in V^*$ s.t. $\varphi|_M = f$ and $\|\varphi\| = \|f\|$

Proof of Theorem

Have $\|v\|_{V^{**}} \leq \|v\|_V \Rightarrow \sup B_V \subseteq B_{V^{**}}$

Suppose $v \in V$, $\|v\| > 1$. By the separation theorem $\exists \varphi \in V^*$ such that

$$\text{Re } \varphi(v) > \sup_{x \in B_V} \text{Re } \varphi(x) = \sup_{x \in B_V} \text{Re } \varphi(\lambda x) = \sup_{x \in B_V} \sup_{|\lambda|=1} \text{Re } \lambda \varphi(x) = \sup_{x \in B_V} |\varphi(x)| = \|\varphi\|$$

$$\text{Let } \psi = \frac{\varphi}{\|\varphi\|}, \quad \|\psi\| = 1, \quad |\psi(v)| \geq \text{Re } \psi(v) > \frac{\|\varphi\|}{\|\varphi\|} = 1$$

$$\text{So } \|v\| = \sup_{\|\varphi\|_{V^*} \leq 1} |\varphi(v)| \geq |\psi(v)| > 1$$

Thus $\|v\| > 1 \Rightarrow \|v\| > 1$

$$\therefore B_V \supseteq B_{V^{**}} \Rightarrow B_V = B_{V^{**}} \Rightarrow \|v\|_{V^{**}} = \|v\|_V$$

because $\|v\| = \inf\{t \geq 0: v \in tB_V\} = \inf\{t \geq 0: v \in tB_{V^{**}}\}$

Proof of Corollary

$$\|v\| = \|v\| = \sup_{|\varphi| \leq 1} |\varphi(v)| = \sup_{|\varphi| \leq 1} |\varphi_0(v)|, \quad \text{attained by EVT}$$

Choose $|\lambda| = 1$ such that $\lambda \varphi_0(v) = |\varphi_0(v)| = \|v\|$

Take $\varphi = \lambda \varphi_0$

Proof of Quotient Norm

$$1) \|v\| \geq 0, \|v\| = 0 \Leftrightarrow \text{dist}(v, M) = 0 \Leftrightarrow v \in M \Leftrightarrow v = 0$$

$$2) \|(tv)\| = \|tv\| = \text{dist}(tv, M) = |t| \text{dist}(v, M) = |t| \|v\|$$

$$3) \|(v+w)\| = \inf_{m \in M} \|v+w+m\| = \inf_{m_1, m_2 \in M} \|(v+m_1) + (w+m_2)\| \\ \leq \inf_{m_1 \in M} \|v+m_1\| + \inf_{m_2 \in M} \|w+m_2\| = \|v\| + \|w\|$$

So $\frac{V}{M}$ has a norm ■

Proof of Lemma

$T: V \rightarrow W$ is 1-1, onto and $\|Tv\| = \|v\| \forall v \in V$

$\therefore T(B_V) = B_W$. Now let $\varphi \in W^*$

$$\|T^t \varphi\|_{V^*} = \sup_{v \in B_V} |(T^t \varphi)(v)| = \sup_{v \in B_V} |\varphi(Tv)| = \sup_{w \in B_W} |\varphi(w)| = \|\varphi\|_{W^*}$$

So T^t is isometric

$$\ker T^t = (\text{ran } T)^\perp = W^\perp = \{0\} \therefore 1 - 1$$

$$\text{ran } T^t = (\ker T)^\perp = \{0_V\}^\perp = V^* \therefore \text{onto} \blacksquare$$

Proof of Theorem

Recall the quotient map $\Pi: V \rightarrow \frac{V}{M}$, $\pi(v) = v$, Π is onto, $\ker \Pi = M$

$$\Pi^t: \left(\frac{V}{M}\right)^* \rightarrow V^*, \quad \ker \Pi^t = (\text{ran } \Pi)^\perp = \left(\frac{V}{M}\right)^\perp = \{0\}, \quad \text{ran } \Pi^t = (\ker \Pi)^\perp = M^\perp$$

So Π^t maps $\left(\frac{V}{M}\right)^* \rightarrow M^\perp$ 1-1 and onto M^\perp \therefore linear isomorphism

$$\text{Take } f \in \left(\frac{V}{M}\right)^*, \quad \Pi^t f = \varphi = f \circ \Pi \in M^\perp$$

$$\|f\|_{\left(\frac{V}{M}\right)^*} = \sup_{\substack{v \in \frac{V}{M} \\ \|v\| \leq 1}} |f(v)| = \sup_{\substack{v \in V \\ \text{dist}(v, M) \leq 1}} |f(\Pi(v))| = \sup_{v \in V} |\varphi(v)| = \sup_{\substack{v \in V \\ \text{dist}(v, M) \leq 1}} |\varphi(v+M)| = \sup_{\substack{m \in M \\ \text{dist}(v, M) \leq 1}} |\varphi(v+M)|$$

If $\text{dist}(v, M) \leq 1$ then $\exists m \in M$ so $\|v+m\| \leq 1$ so $v \in B_V + M$

Conversely, if $v \in B_V + M$ then $\text{dist}(v, M) \leq 1$

$$\|f\|_{\left(\frac{V}{M}\right)^*} = \sup_{\substack{v \in V \\ \text{dist}(v, M) \leq 1}} |\varphi(v+M)| = \sup_{\substack{v \in V \\ \|v\| \leq 1}} |\varphi(v+m)| = \sup_{\substack{m \in M \\ \|v\| \leq 1}} |\varphi(v)| = \|\varphi\|$$

So Π^t is an isometric isomorphism of $\left(\frac{V}{M}\right)^*$ onto M^\perp

Apply that to $M^\perp \subseteq V^*$

$$\left(\frac{V^*}{M^\perp}\right) \cong (M^\perp)^\perp \subseteq V^{**} \text{ which is isomorphic to } M \subseteq V$$

So we have an isometric isomorphism

$$J: \left(\frac{V^*}{M^\perp}\right)^* \rightarrow M \text{ by new lemma } J^t: M^* \rightarrow \left(\frac{V^*}{M^\perp}\right)^{**} = \frac{V^*}{M^\perp} \blacksquare$$

Proof of Corollary

$f \in M^* \cong \frac{V^*}{M^\perp}$ is isometric isomorphism

$\exists \varphi \in V^*$ s.t. $f \leftrightarrow \varphi = \varphi + M^\perp$

$$\text{So } \varphi|_M = f, \|f\| = \|\varphi\| = \inf_{\psi \in M^\perp} \|\varphi + \psi\|$$

Since $\dim V \leq \infty$, this inf is attainable from EVT

$\|f\| = \|\varphi + \psi_0\|$, $\varphi + \psi_0$ is the desired extensions ■

$$(\varphi + \psi_0)|_M = \varphi|_M + \psi_0|_M = f + 0 = f$$

Norms in Matrices

December-02-11
9:53 AM

Matrix Norm

V normed finite dimensional.

A norm on $\mathcal{L}(V)$ usually should have an additional property

$$4) \|ST\| \leq \|S\|\|T\|$$

Trace Norm

$T \in \mathcal{L}(V)$. V finite dimensional inner product space.

Polar decomposition

$$T = UD$$

$$D = \sqrt{T^*T} \cong \text{diag}(s_1, s_2, \dots, s_n), \quad s_1 \geq s_2 \geq \dots \geq s_n \geq 0$$

S-numbers of T , $s_i = s_i(T)$

$$\|T\|_1 = \sum_{i=1}^n s_i(T)$$

- $\|T\|_1 \geq 0$, if $\|T\| = 0 \Rightarrow s_i = 0 \forall i \Rightarrow D = 0 \Rightarrow T = 0$
- $s_i(tT) = ts_i(T)$ since $tT = U(tD)$

Lemma 1

If $\{e_i\}_1^n, \{f_i\}_1^n$ are orthonormal bases for V , then

$$\sum_{i=1}^n |\langle Te_i, f_i \rangle| \leq \|T\|_1$$

Corollary

$$\|S + T\|_1 \leq \|S\|_1 + \|T\|_1$$

Hence $\|\cdot\|_1$ is a norm

Lemma 2

$T \in \mathcal{L}(V)$, $1 \leq j \leq n$

$$s_j(T) = \inf_{\text{rank}(F) \leq j-1} \|T - F\|_\infty = \text{dist}(T, \mathcal{F}_{j-1})$$

matrix of rank $\leq j-1$

Corollary

If $A, T \in \mathcal{L}(V)$, then

$$s_j(AT) \leq \|A\|_\infty s_j(T)$$

$$s_j(TA) \leq \|A\|_\infty s_j(T)$$

Corollary²

$A, T \in \mathcal{L}(V)$ then

$$\|AT\|_1 \leq \|A\|_\infty \|T\|_1 \leq \|A\|_1 \|T\|_1$$

$$\|TA\|_1 \leq \|T\|_1 \|A\|_\infty$$

Therefore $\|\cdot\|_1$ is a matrix norm

Remark

Same argument shows that

$$\|AT\|_2 \leq \|A\|_\infty \|T\|_2, \quad \|TA\|_2 \leq \|T\|_2 \|A\|_\infty$$

Theorem

The dual of $(\mathcal{L}(V), \|\cdot\|_\infty)$ is $(\mathcal{L}(V), \|\cdot\|_1)$ via a pairing

$$\varphi_T(A) = \text{Tr}(AT)$$

Remark 1

$\|\cdot\|_1$ is unitarily invariant

If $T \in \mathcal{L}(V)$, U, V unitary then $\|UTV\|_1 = \|T\|_1$

Remark 2

Ky Fan Norms

$$\|T\|_{KF_k} = \sum_{i=1}^k s_i(T)$$

is a unitarily invariant matrix norm

Theorem (Ky Fan)

Every unitarily invariant matrix norm on \mathcal{M}_n is a convex combination of the Ky Fan norms.

Examples

$$1) \|T\| = \sup_{\|v\| \leq 1} \|Tv\| < \infty \text{ by EVT}$$

Restrict to an inner product space $(V, \langle \cdot, \cdot \rangle)$

$$2) \|T\| = \|T\|_\infty = \sup_{\|v\|=1} \|Tv\|$$

Polar decomposition $T, \sqrt{T^*T} = D$ unique positive square root

D is diagonalizable. \exists orthonormal basis $\{u_1, \dots, u_n\}$

$$Du_i = s_i u_i \quad 1 \leq i \leq n, \quad s_1 \geq s_2 \geq \dots \geq s_n \geq 0$$

U partial isometry, $U: \text{ran } D \rightarrow \text{ran } T$ isometrically, $T = UD$

Let $v_i = Uu_i$ $\{v_i | s_i > 0\}$ is orthonormal

$$T = \sum_{i=1}^n s_i v_i u_i^*$$

$$\|T\|_\infty = \sup_{\|v\|=1} \|Tv\| = \sup_{\|v\|=1} \|UDv\| = \sup_{\|v\|=1} \|Dv\| = \sup_{\substack{v = \sum a_i u_i \\ \sum |a_i|^2 = 1}} \left\| \sum s_i a_i u_i \right\|$$

$$= \sup_{\sum |a_i|^2 = 1} \sqrt{\sum_{i=1}^n s_i^2 |a_i|^2} = s_1 \sup_{\sum |a_i|^2 = 1} \sqrt{\sum |a_i|^2} = s_1$$

$$3) \|T\|_2 \text{ fix an orthonormal basis } \{e_1, \dots, e_n\} = \xi$$

$$T = |T|_\xi = |t_{ij}|$$

$$\text{Define } \|T\|_2 = \sqrt{\sum_{i,j=1}^n |t_{ij}|^2}$$

Makes \mathcal{M}_n into an inner product space

$$|S| = |s_{ij}|, \quad \langle |S|, |T| \rangle = \sum_{i,j=1}^n s_{ij} t_{ij}$$

$$|T^*|_\xi = |t_{ji}|, \quad |ST^*|_\xi = \left| \sum_{k=1}^n s_{ik} t_{jk} \right| \text{ has } \sum_{k=1}^n s_{ik} t_{ik} \text{ on diagonal } (i, i)$$

$$\therefore \langle |S|, |T| \rangle = \text{tr}(ST^*)$$

$$\|ST\|_2^2 = \sum_{i=1}^n \sum_{j=1}^n \left| \sum_{k=1}^n s_{ik} t_{kj} \right|^2 \leq \sum_{i=1}^n \sum_{j=1}^n \left(\sum_{k=1}^n |s_{ik}|^2 \right) \left(\sum_{l=1}^n |t_{lj}|^2 \right)$$

$$= \left(\sum_{i=1}^n \sum_{k=1}^n |s_{ik}|^2 \right) \left(\sum_{j=1}^n \sum_{l=1}^n |t_{lj}|^2 \right) = \|S\|_2^2 \|T\|_2^2$$

If U, V are unitary

$$\|UTV\|_2^2 = \langle UTV, UTV \rangle = \text{tr}((UTV)(UTV)^*) = \text{tr}(UTV V^* T^* U^*) = \text{tr}(U T T^* U^*)$$

$$= \text{tr}(U^* U T T^*) = \text{tr}(T T^*) = \|T\|_2^2$$

So $\|UTV\|_2 = \|T\|$ (unitarily invariant norm) (so is $\|T\|_\infty$)

In particular, this definition does not depend on choice of o.n. basis.

If f_1, \dots, f_n o.n. basis ζ . Let $Ue_i = f_i$,

$$|a_{ij}| = |T|_\zeta = U|T|_\xi U^* = U|t_{ij}| U^*$$

$$\sqrt{\sum_{i,j=1}^n |a_{ij}|^2} = \|UTU^*\| = \|T\|^2 = \sqrt{\sum_{i,j=1}^n |t_{ij}|^2}$$

$T = UD$ polar decomposition, $Uu_i = v_i$, $1 \leq i \leq k$, $s_k > 0$, $s_{k+1} = 0$

extend v_1, \dots, v_k to orthonormal basis. Define $Vu_i = v_i$, $1 \leq i \leq n$ Unitary

$$T = UD = VD$$

$$\|T\|_2 = \|UD\|_2 = \|D\|_2 = \sqrt{\sum_{i=1}^n s_i^2}, \quad \text{where } |D|_U = \text{diag}(s_1, s_2, \dots, s_n)$$

Proof of Lemma 1

$T = UD$

Choose an orthonormal basis $\{u_i\}_1^n$ which diagonalizes D . $Du_i = s_i u_i$, $1 \leq i \leq n$

$$\text{Let } v_i = Uu_i, \quad 1 \leq i \leq \begin{cases} k & \text{if } s_{k+1} = 0 \\ n & \text{if } s_n > 0 \end{cases}$$

$$T = \sum_{j=1}^k s_j (v_j u_j^*)$$

$$\sum_{i=1}^n |\langle Te_i, f_i \rangle| = \sum_{i=1}^n \left| \sum_{j=1}^k s_j \langle e_i, u_j \rangle \langle v_j, f_i \rangle \right|$$

$$\leq \sum_{j=1}^k s_j \sum_{i=1}^n |\langle e_i, u_j \rangle| |\langle v_j, f_i \rangle| \leq c.s. \sum_{j=1}^k s_j \sqrt{\sum_{i=1}^n |\langle u_j, e_i \rangle|^2} \sqrt{\sum_{i=1}^n |\langle v_j, f_i \rangle|^2} = \sum_{j=1}^k s_j \|u_j\| \|v_j\| = \sum_{j=1}^k s_j$$

$$= \|T\|_1$$

Proof of Corollary

$$S + T = UE, \quad E = |S + T| = \sqrt{(S + T)^*(S + T)}$$

$$S + T = \sum_{i=1}^n s_i (S + T) v_i u_i^*, \quad \{u_i\}_1^n, \{v_i\}_1^n \text{ orthonormal}$$

$$\|S + T\|_1 = \sum_{i=1}^n s_i = \sum_{i=1}^n \langle (S + T) u_i, v_i \rangle \leq \left| \sum_{i=1}^n \langle S u_i, v_i \rangle \right| + \left| \sum_{i=1}^n \langle T u_i, v_i \rangle \right| \leq_{\text{Lemma 1}} \|S\|_1 + \|T\|_1$$

So $\Delta \leq$ holds hence $\|\cdot\|_1$ is a norm ■

Proof of Lemma 2

$$\text{Write } T = \sum_{i=1}^n s_i (v_i u_i^*), \quad \text{Let } F_j = \sum_{i=1}^{j-1} s_i (v_i u_i^*) \in \mathcal{F}_{j-1}$$

$$\text{Let } T - F_j = \sum_{i=j}^n s_i (v_i u_i^*) = U \text{diag}\{0, 0, \dots, 0, s_j, \dots, s_n\}$$

$$\|T - F_j\| = \|T - F_j\|_\infty = \max s_i (T - F_j) = s_j, \therefore \text{dist}(T, \mathcal{F}_{j-1}) \leq s_j$$

Suppose $\text{rank}(F) \leq j - 1$, $\text{nul}(F) \geq n - (j - 1) = n + 1 - j$
 $\dim(\text{sp}\{u_1, \dots, e_n\}) + \text{nul}(F) \geq j + n - (j - 1) = n + 1$
 $\therefore \dim(\text{sp}\{u_1, \dots, u_j\} \cap \ker F) \geq 1$

$$\text{Pick } x \in \text{sp}\{u_1, \dots, u_j\} \cap \ker F, \|x\| = 1, \quad x = \sum_{i=1}^j a_i u_i \in \ker F$$

$$\therefore \|T - F\| \geq \|(T - F)x\| = \|Tx\| = \left\| \sum_{i=1}^j (s_i a_i) v_i \right\| = \sqrt{\sum_{i=1}^j s_i^2 |a_i|^2} \geq s_j \sqrt{\sum_{i=1}^j |a_i|^2} = s_j \|x\|$$

$$= s_j$$

Proof of Corollary

$$s_j(AT) = \text{dist}(AT, \mathcal{F}_{j-1}) \leq \|At - Af_j\|_\infty = \|A(T - F_j)\| \leq \|A\|_\infty \|T - F_j\|_\infty = \|A\|_\infty s_j(T)$$

Other side is similar.

Proof of Corollary²

$$\|AT\|_1 = \sum_{i=1}^n s_i(AT) \leq \sum_{i=1}^n \|A\|_\infty s_i(T) = \|A\|_\infty \|T\|_1$$

Other side is similar

Proof of Theorem

Choose orthonormal basis $\xi = \{e_1, \dots, e_n\}$ matrix units E_{ij} basis for $\mathcal{L}(V)$, $1 \leq i, j \leq n$
 $\varphi \in \mathcal{L}(V)^*$, Let $t_{ij} = \varphi(E_{ij})$, Let $T = |t_{ij}|_\xi$

So if $|A|_\xi = |a_{ij}|$, $A \in \mathcal{L}(V)$

$$\text{tr}(AT) = \sum_{i=1}^n |AT|_{ii} = \sum_{i=1}^n \sum_{j=1}^n |A|_{ij} |T|_{ji} = \sum_{i=1}^n \sum_{j=1}^n a_{ij} t_{ij}$$

$$A = \sum_{i,j} a_{ij} E_{ij}, \quad \varphi(A) = \sum_{i,j} a_{ij} \varphi(E_{ij}) = \sum_{i,j} a_{ij} t_{ij}$$

So $\varphi(A) = \text{Tr}(AT) = \varphi_T(A)$

$$\|\varphi\| = \sup_{\|A\|_\infty \leq 1} |\varphi(A)| = \sup_{\|A\|_\infty \leq 1} |\text{Tr}(AT)|$$

$$= \sup_{\|A\|_\infty \leq 1} \left| \sum_{i=1}^n \langle AT e_i, e_i \rangle \right| \leq_{\text{Lemma 1}} \sup_{\|A\|_\infty \leq 1} \|AT\|_1 \leq_{\text{Corollary}^2} \sup_{\|A\|_\infty \leq 1} \|A\|_\infty \|T\|_1 = \|T\|_1$$

$T = UD$, Let $A = U^*$, $\|A\|_\infty = 1$

$$\varphi_T(T) = \text{Tr}(U^*UD) = \text{Tr}(D) = \text{Tr}(\text{diag}(s_1, s_2, \dots, s_n)) = \|T\|_1$$

$$\therefore \|\varphi_T\| \geq \|T\|_1 \therefore \|\varphi_T\| = \|T\|_1$$

Proof of Remark 1

$$\|UTV\|_1 \leq \|U\|_\infty \|T\|_1 \|V\|_\infty = \|T\|_1$$

$$\|T\|_1 = \|U^*(UTV)V^*\|_1 \leq \|U^*\|_\infty \|UTV\|_1 = \|UTV\|_1$$